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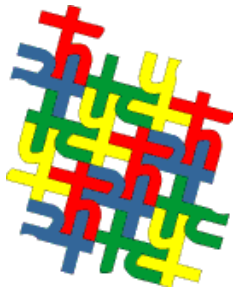
Inductive limits of quantum systems, equilibrium states and dynamics

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ICMS Workshop
Mathematical Physics & Quantum Technology:
From finite to infinite dimensions

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limits of quantum systems,

ICMS Workshop
Mathematical Physics & Quantum Technology:
From finite to infinite

Examples

- ▶ Mean field limit ($N \rightarrow \infty$, permutation symmetry)
- ▶ Classical limit ($\hbar \rightarrow 0$)
- ▶ Infinite volume limit (lattice system)
- ▶ Continuum limits (lattice spacing $\rightarrow 0$, renormalization)
- ▶ Continuum limits (repeated \rightarrow continuous measurement)

Features

- ▶ Not just a parameter, structure may change in the limit
- ▶ Limit in norm for states and/or observables
- ▶ General results do some of the work for
 - Limit space
 - Dynamics
 - Equilibrium states

Soft inductive limits

Each term in a sequence/net
lives in a **different universe**

Then how can they be called **similar**?

Introduce **comparison maps**
These are the conceptual basis of
the limit scheme

Soft inductive limits

Indices for the limit: a directed set $(N, >)$

Nets $(x_n)_{n \in N}$, $x_n \in E_n = \text{Banach space}$

Comparison maps $j_{nm}: E_m \rightarrow E_n$ for $n > m$,
such that

- each j_{nm} is linear, $\|j_{nm}\| \leq 1$
- system is **asymptotically transitive**:

$$\lim_k \limsup_n \|(j_{nm} - j_{nk} j_{km})x_m\| = 0 \quad \forall x_m \in E_m$$

More (or less) **structure** as needed: j_{nm} then
completely positive, unital, homomorphism

Soft inductive limits

A nets $(x_n \in E_n)_{n \in \mathbb{N}}$ is called **j-convergent**,
if $\lim_k \limsup_n \|x_n - j_{nm} x_m\| = 0$.

j-convergent sets x_n, y_n are said to have the
same limit if $\lim_n \|x_n - y_n\| = 0$.

j- $\lim_n x_n = x_\infty \in E_\infty =$ quotient space
= “**abstract limit space**”

- E_∞ is complete with the norm $\|x_\infty\| = \limsup_n \|x_n\|$
- For fixed $x_m \in E_m$ the **basic net** $y_n = j_{nm} x_m$ converges
- Define $j_{\infty m}: E_m \rightarrow E_\infty$ by $j_{\infty m} x_m := j\text{-}\lim_n y_n$
- Basic nets are dense

Soft inductive limits: general remarks

The notion of **convergent net** is more fundamental than the comparison maps:

Can change j_{nm} for any finite n, m . Only asymptotic $n \gg m \rightarrow \infty$ enter.

Two families j_{nm} and j'_{nm} are called **equivalent**, if they have same convergent nets

Construction jointly **generalizes strict** inductive limits ($j_{nm} = j_{nk} j_{km}$) and the **completion** construction (all $j_{nm} = \text{id}$, any seminorm on E_1).

Sometimes may compare directly E_n and E_∞

A **split** inductive system is of the form $j_{nm} = p_n i_m$ with

$i_n: E_n \rightarrow E_\infty$, $p_n: E_\infty \rightarrow E_n$, $p_n i_n = \text{id}_n$, $i_n p_n \rightarrow \text{id}_\infty$ strongly.

Example 1: Mean Field

Fix one-site algebra \mathcal{A} (C^* , often finite matrix algebra)

$$E_n = \mathcal{A}^{\otimes n} \quad j_{nm}(A) = \text{sym}_n(A \otimes 1^{\otimes(n-m)}) \\ = \text{average over permutations}$$

Strict inductive system, unknown if equivalent to split

A_n, B_n convergent, $C_n = A_n B_n \Rightarrow C_n$ convergent, $[A_n, B_n] \rightarrow 0$
Hence E_∞ is an abelian C^* -algebra.

$$E_\infty \cong C(\Sigma), \Sigma = \text{state space of } \mathcal{A}: \quad A_\infty(\rho) = \lim_n \rho^{\otimes n}(A_n)$$

Example 2: Classical Limit

Fix a finite dimensional phase space (Ξ, σ)

\mathcal{H}_{\hbar} carries Weyl operators $W_{\hbar}(\xi)$,

$$W_{\hbar}(\xi) W_{\hbar}(\eta) = \exp(-i\sigma(\xi, \eta)/(2\hbar)) W_{\hbar}(\xi + \eta)$$

$$\alpha_{\hbar, \xi}^{\hbar}(A) = W_{\hbar}(\xi)^* A W_{\hbar}(\xi)$$

$$E_{\hbar} = \mathbf{T}(\mathcal{H}_{\hbar}) \quad \text{or} \quad E_{\hbar} = \{A \in \mathbf{B}(\mathcal{H}_{\hbar}) \mid \xi \rightarrow \alpha_{\hbar, \xi}^{\hbar}(A) \text{ norm contin.}\}$$

$j = \alpha$ -covariant / not too noisy / $w_{\hbar}(\xi) := W_{\hbar}(\hbar\xi)$ convergent
can be chosen split or strict (not both)

$$E_0 = \mathbf{L}^1(\Xi, d\xi) \quad \text{or} \quad E_0 = \{f \in \mathbf{L}^{\infty}(\Xi, d\xi) \mid \xi \rightarrow \alpha_{\hbar, \xi}^{\hbar}(f) \text{ norm contin.}\}$$

Get $j_{0\hbar}$ by expectation with coherent vector

Asymptotically homomorphic.

j -convergence $\Rightarrow j^*$ -convergence

Example 3: Quasilocal algebra

$X = \mathbf{Z}^d$, lattice with observables \mathcal{A}_x at site $x \in X$

\mathcal{N} = family of (some) finite regions, \subset

$\mathcal{A}_n = \bigotimes_{x \in n} \mathcal{A}_x$; j_{nm} = inclusion by tensoring with $\mathbf{1}$

\mathcal{A}_∞ = quasilocal algebra [Bratteli-Robinson]

Examples:

- renormalization/lattice refinement
- Finite Weyl systems $\rightarrow [x,p]=i$
- Continuous measurement
- Tensor products of inductive systems

Dynamics

Hamiltonians usually not convergent:

Mean field: $H_n = nh_n$ must be extensive

Classical: dynamics generated by $U_t = \exp(-iH_{\hbar}t/\hbar)$
must not converge to implement anything

Lattice: Hamiltonian is not quasilocal

Mean field/Classical:

get Poisson bracket as next order commutator:

$$j\text{-}\lim_n ni[A_n, B_n] = \{A_\infty, B_\infty\}$$

Aim: jj-convergence $T_{n,t}$ = semigroup on E_n such that
 x_n convergent $\Rightarrow T_{n,t}x_n$ convergent.

$$T_{\infty,t}x_\infty := j\text{-}\lim_n T_{n,t}x_n$$

Dynamics

Our theory neatly separates:

(A) Limit for the generator
equations of motion

(B) Limit for the semigroup
solution

Nettified version of
semigroup theory

(A) Densely defined
generator G

(B) $(s-G)$ has
dense range

(A) Uses net structure j_{nm}

(B) Can be done in E_∞ (often simpler!)

Dynamics: Theorem

Given soft inductive system (E, j) and semigroups

$$T_{n,t} = \exp(t G_n).$$

Then equivalent

- (1) $T_{n,t}$ preserves j -convergence and $T_{\infty,t}$ is a strongly continuous semigroup with generator G_{∞}
- (2) The resolvents $R_n(\lambda) = (\lambda - G_n)^{-1}$ ($\lambda > 0$) preserve j -convergence and $R_{\infty}(\lambda)$ has dense range.
- (3) There is a dense subset \mathcal{D} of convergent nets such that $(\lambda - G_n)\mathcal{D}$ is also a dense subspace of convergent nets
- (4) G_{∞} is well-defined and generates a semigroup

Mean field dynamics, Hamiltonian case

$$G_n(A) = i[nh_n, A] \Rightarrow \text{energy density } h_\infty = \text{j-lim}_n h_n$$

$$G_\infty(f) = \{h_\infty, f\}, \text{ with suitable definition of Poisson bracket} \\ (T_{\infty,t} f)(\sigma) = f(\mathcal{F}_t(\sigma)), \mathcal{F}_t(\sigma) = \text{Hamiltonian flow}$$

For $f \in C(\Sigma)$: **gradient** $df(\sigma) \in \mathcal{A}$:

$$\text{tr}(\rho df(\sigma)) := d/(dt) f(t\rho + (1-t)\sigma) |_{t=0}$$

$$\{f, g\}(\sigma) = \text{tr}(\sigma i[df(\sigma), dg(\sigma)])$$

Mean field tagged dynamics, Hamiltonian case

Modified inductive system: leave **M sites** out of sym-operation

$$E_\infty = C(\Sigma) \otimes \mathcal{A}^{\otimes M} \cong \mathcal{A}^{\otimes M}\text{-valued functions on } \Sigma$$

For dynamics get $(T_{\infty,t} f)(\sigma) = U^*(t, \sigma)^{\otimes M} f(\mathcal{F}_t(\sigma)) U(t, \sigma)^{\otimes M}$

$$d/(dt)U(t, \sigma) = iH(t)U(t, \sigma) \text{ with } H(t) = i dh_\infty(\mathcal{F}_t(\sigma))$$

Mean field dynamics, Lindblad case

$$G_n(A) = n \text{Sym}_n(\text{Lindblad terms}) \quad (\text{operator permutations})$$

Special simple case:

$$G_n(A) = i[nh_n, A] + n \sum_j (a_{j,n}^* [A, a_{j,n}] + [a_{j,n}^*, A] a_{j,n}) \quad (*)$$

Tagged dynamics:

$$(T_{\infty,t} f)(\sigma) = \Lambda_{t,\sigma}^{\otimes M}(f(\mathcal{F}_t(\sigma)))$$

$\mathcal{F}_t(\sigma)$ = non-Hamiltonian flow
(arbitrary)

$\Lambda_{t,\sigma}$ = cp cocycle

$S(\Lambda_{t,\sigma}^* \rho, \mathcal{F}_t(\sigma))$ decreases

Assuming (*)

Spectrum of $\mathcal{F}_t(\sigma)$ conserved
(otherwise arbitrary)

Λ generated by Hamiltonian

$$dh_{\infty} + \sum_j \text{Im}(a_{j,\infty}^* da_{j,\infty})$$

Classical limit dynamics, Hamiltonian case

$H_n =$ Schrödinger operator with \leq quadratic potential
 or $\xi \rightarrow \alpha_{\xi}^{\hbar}(H_{\hbar})$ has j -convergent (bounded!) 2nd derivatives

This ensures Hamiltonian vector field of H_0
 uniformly Lipschitz, hence with global existence

Project: extend this to incomplete dynamics
 (escape $\rightarrow \infty$ and non-esa Hamiltonians)

This approach avoids **WKB artefacts**:

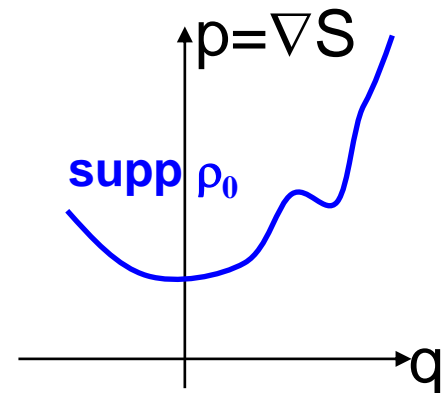
$$\psi(x) = \varphi(x) \exp(iS(x)/\hbar); \quad \rho_{\hbar} = |\psi\rangle\langle\psi|$$

$\rho_0 = j^* \text{-} \lim_{\hbar} \rho_{\hbar}$, i.e., for all j -convergent A :

$$\text{i.e., } \lim_{\hbar} \text{tr}(\rho_{\hbar} A_{\hbar}) = \int \rho_0(d\xi) A_0(\xi)$$

$$\rho_0(dp dq) = |\varphi(x)|^2 \delta(p - dS(x)) dp dq$$

Form **not stable under flow**



Classical limit dynamics, **monitored**

The hallmark of classical theory is the possibility to monitor the system continuously, essentially without disturbance.

How does this arise in the limit?

Interlace the dynamics with (“mild _{\hbar} ”) measurements:

- at times **fixed** independently of the state, or
- as **jump events** in a Lindblad evolution (e.g. GRW).

Then, with suitable choice of parameters,

- limiting dynamics with **same Hamiltonian**
- monitoring outcomes **correct**.

Classical limit dynamics, **quasifree (divisible)**

Quasifree evolution: $T_t(W(\xi)) = f_t(\xi) W(S_t \xi)$ on (Ξ, σ)

Probable **Theorem** (Alberto Barchielli, RFW, yesterday)

This defines a dynamical semigroup iff

- $S_t = \exp(tZ)$ is a matrix semigroup
- $f_t(\xi) = \exp \int_0^t d\tau \Psi(S_\tau \xi)$
- $\Psi(\xi) = ia^T \xi - \frac{1}{2} \xi^T A \xi + \int \mu(d\eta) (e^{i\eta^T \xi} - 1 - i\eta^T \xi h(\eta))$
- $\mu = \text{L\`evy measure: } \min\{|\xi|^2, 1\} \text{ integrable, } h = \text{cutoff}$
- $A + \frac{i\hbar}{2} (\sigma Z + Z^T \sigma) \geq 0$

Limit $\hbar \rightarrow 0$ of semigroups with data (a, A, μ) gives same for $\hbar = 0$:
Generalized Ornstein-Uhlenbeck process, which also describes
the evolution of Wigner functions for all \hbar

Lattice dynamics: some features

Nothing really new relative to Bratteli&Robinson, but some features simplified/more natural:

$N=(\text{regions}, \subset)$, directed index set

- **Translations** act in no finite E_n , but do map j -convergent sequences to j -convergent sequences. Hence they act on the infinite lattice.
- Independence of **boundary conditions** is automatic:

(3) There is a dense subset \mathcal{D} of convergent nets such that $(\lambda-G_n)\mathcal{D}$ is also a dense subspace of convergent nets.

Choose \mathcal{D} so observables see only interior points.

Equilibrium states: Gibbs variational principle

Start from j -limit of observables,

$H_n =$ Hamiltonian density

Take $s_n: E_n^* \rightarrow \mathbf{R} \cup \{-\infty\}$ entropy density functional
upper semicont. and concave

Local equilibrium state ω_n minimizes “free energy”

$$g(\omega) = \omega(H_n) - \beta^{-1} s_n(\omega) \quad (\beta^{-1} = kT)$$

Find: $\lim_n g(\omega_n)$ and j^* -limits or cluster points of the net ω_n

Idea: understand limit $s_n \rightarrow s_\infty$

Then free energies converge, satisfy Gibbs $_\infty$, and minimizers converge to minimizers