

Level Sets of Eigenfunctions and Harmonic Functions

David Jerison (MIT)

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Hot Spots Conjecture (Rauch 1974)

If $\Omega \subset \mathbb{R}^n$ is convex, and ψ_1 is the first non-trivial Neumann eigenfunction, then $\nabla \psi_1(x) \neq 0$ for all $x \in \Omega$.

Neumann Eigenfunctions

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How do level sets of (stable) solutions to $\Delta u = f(u)$ fit together?

Dirichlet Eigenfunctions

Rectangle: $\Psi(x) = \prod_{j=1}^n \sin(k_j x_j)$, $\Omega = [0, \pi/k_1] \times [0, \pi/k_2] \times \dots$

$$\frac{\nabla^2 \Psi(x)}{\Psi(x)} \equiv \begin{pmatrix} -k_1^2 & 0 & \dots & 0 \\ 0 & -k_2^2 & \dots & 0 \\ \vdots & \dots & \dots & 0 \\ 0 & \dots & 0 & -k_n^2 \end{pmatrix}$$

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Hessian Conjecture (1994)

If $\Omega \subset \mathbb{R}^n$ is convex, then the first Dirichlet eigenfunction ψ_0 satisfies

$$\frac{\nabla^2 \psi_0(x)}{\psi_0(x)} \approx \text{constant}$$

for $\psi_0(x) > \frac{1}{2} \max \psi_0$.

Harmonic Functions

Polya-Szegö Capacitary Conjecture (1950)

For $n \geq 3$, the extremal for convex $\Omega \subset \mathbb{R}^n$ of

$$\inf_{\Omega} \frac{\text{cap}(\Omega)^{1/(n-2)}}{\sigma(\partial\Omega)^{1/(n-1)}} \text{ is a flat disk.}$$

Recall, the equilibrium potential u for Ω in \mathbb{R}^n is the harmonic function in $\mathbb{R}^n \setminus \Omega$ satisfying

$$\begin{aligned} u &= 1 \quad \text{on } \partial\Omega; \quad u(x) \rightarrow 0 \quad \text{as } x \rightarrow \infty; \\ u(x) &= \text{cap}(\Omega) c_n |x|^{2-n} + O(|x|^{1-n}) \quad \text{as } x \rightarrow \infty. \end{aligned}$$

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The common feature of these three conjectures is that they involve convex level sets of equations of the form $\Delta u = f(u)$. So far, a rather superficial connection.

A variational principle for level sets

Klartag 2019: The nodal set $M_0 = \{\psi = 0\}$ is stationary for a weighted area measure $|\nabla\psi|d\sigma$ just as minimal surfaces are stationary for area $d\sigma$.

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In fact (DJ) The level set flow

$$dx/d\tau = (1/|\nabla\psi|)\mathbf{N}, \quad M_\tau := \{\psi(x) = \tau\}$$

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Proof:
$$\frac{d}{dt} \int_{M_\tau + t\nu\mathbf{N}} |\nabla\psi|, d\sigma \Big|_{t=0} = -\lambda\tau \int_{M_\tau} v d\sigma$$

Moreover, $\max \int v d\sigma$ constrained by $\int v^2 |\nabla\psi| d\sigma = 1$ is realized by

$$v = c \frac{1}{|\nabla\psi|}$$

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Mean curvature flow $dx/dt = H\mathbf{N}$ decreases area fastest, so

$$1/|\nabla\psi| \longleftrightarrow H$$

Analogy with mean curvature and Ricci flow

High hopes for the analogy with MCF and Ricci flow:

- Level sets resemble **shrinkers**.
- Hamilton's **Harnack inequalities**, $H(x_1, t_1) \approx H(x_2, t_2)$, might prevent $|\nabla\psi_1|$ from vanishing.
- Hamilton's **curvature pinching estimates** could stabilize the Hessian of ψ_0 .
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But what does this have to do with Polya-Szegö?

Hamilton's approach is to study $\partial_t g_{ij}$, $\partial_t h_{ij}$, Δh_{ij} and other tensors. Key ingredient: **his differential inequalities are sharp, and their form is dictated solitons, for which they are equalities.**

Our solitons will be confocal ellipsoids, the family of examples motivating the Polya-Szegö Conjecture.

Confocal Ellipsoids

Confocal ellipsoids are defined for $-a_1^2 \leq -a_2^2 \leq \dots \leq -a_n^2 < s$ by

$$\partial\Omega_s := \left\{ x \in \mathbb{R}^n : \sum_{j=1}^n \frac{x_j^2}{a_j^2 + s} = 1 \right\}.$$

The equilibrium potential U with these levels sets is

$$U(x) = \Phi(s), \quad \Phi'(s) = \frac{1}{\sqrt{(s + a_1^2)(s + a_2^2) \cdots (s + a_n^2)}}.$$

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FIRST STEP: For $\Delta u = 0$,

Find geometric invariants of $M_\tau = \{x : u(x) = \tau\}$ that are zero for the solitons U .

Classical Geometry and Affine Geometry

Classical geometry of hypersurfaces

In \mathbb{R}^n , $\partial_j = (\partial/\partial x_j)$ is covariant constant:

$$\nabla_{\partial_i}(a\partial_j) = (\partial_i a)\partial_j$$

The Levi-Civita connection D^{LC} and 2nd fundamental form A on M are defined by writing $\nabla_X Y$ in tangential and normal components:

$$\nabla_X Y = D_X^{LC} Y + A(X, Y)\mathbf{N} \quad (X, Y \in TM)$$

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Affine geometry of hypersurfaces

The **affine normal** μ is a transverse SL_n invariant vector.

$$\nabla_X Y = D_X^\mu Y + A^\mu(X, Y)\mu \quad (X, Y \in TM)$$

Harmonic Level Set Geometry

We introduce the **harmonic normal** defined by

$$\nu = |\nabla u| \mathbf{N} - \nabla^A |\nabla u|$$

with $\nabla^A f$ defined by $A(\nabla^A f, Y) = Yf$.
(On ellipsoids, ν is the radial vector.)

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We define a “harmonic” connection D and quadratic form L on the level surface $M_\tau = \{u = \tau\}$ by

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(The flux $|\nabla u| d\sigma$ is covariant constant with respect to the connection D on the surface M_τ .)

Higher Harmonic Invariants

Following the analogy with affine geometry, we differentiate the basic invariants:

$$\text{Cubic Form: } F(X, Y, Z) = (D_X L)(Y, Z).$$

$$\text{Shape Operator: } S(X) = -\nabla_X \nu \quad (S : TM_\tau \rightarrow TM_\tau).$$

The shape operator is symmetric with respect to L , so we can define another natural quadratic form

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The properties that indicate that this is the natural choice are

1. $F \equiv 0$ if and only if M is a quadric.
2. In the case $u = U$, \tilde{L} is the metric on the unit sphere for all τ .

What's Next?

Since $\partial_\tau \tilde{L} = 0$ for confocal ellipsoids, we also have, for example,

$$\partial_\tau^2 \widetilde{\text{Riem}} = 0,$$

with $\widetilde{\text{Riem}}$ the Riemann curvature tensor of \tilde{L} .

Hamilton's mean curvature and Ricci flow differential inequalities are based on the heat operator, $\partial_t - \Delta_t$, for the intrinsic Laplacian Δ_t on the evolving manifold M_t . We expect ours to be based on the ordinary Laplace operator Δ . For any harmonic function u with $\nabla u \neq 0$, the Laplace operator can be written using the coordinate $u = \tau$ and the intrinsic Laplacian Δ_τ on $\{u = \tau\}$ as

$$\Delta = |\nabla u|^2 \partial_\tau^2 + \Delta_\tau.$$