# Rough differential equations for volatility

Signatures and Rough Paths: From Stochastics, Geometry and Algebra to ML

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## Rough paths to model stochastic dynamics

• Suppose we are interested in giving meaning to stochastic differential equations

$$dY_t = F(Y_t)dX_t, \quad Y_0 = y_0.$$
 (1)

with X a given multidimensional stochastic process.

 $\cdot$  We must only give meaning to the terms

$$\boldsymbol{X}_{s,t}^{\alpha_{1}...\alpha_{n}} = \int_{s < u_{1} < ... < u_{n} < t} \mathrm{d}X_{u_{1}}^{\alpha_{1}} \cdots \mathrm{d}X_{u_{n}}^{\alpha_{n}}, \quad |\alpha_{1}| + \ldots + |\alpha_{n}| \leq 1$$

with  $X^{\alpha} \mid \! \alpha \! \mid \! \text{-Hölder, e.g. through some kind of notion of stochastic } \! \int \! .$ 

 $\cdot$  (1) will then automatically inherit meaning as

 $Y_t \approx Y_s + F_{\alpha}(Y_s) X_{s,t}^{\alpha} + \ldots + F_{\alpha_1} \circ \cdots \circ F_{\alpha_n}(Y_s) \boldsymbol{X}_{s,t}^{\alpha_1 \ldots \alpha_n}$ 

• Is consistent with Itô and Stratonovich calculus and works for many other multidimensional stochastic processes beyond semimartingales, including 1/4 < H-fBm<sup>1</sup>.





 $\cdot\,$  Option pricing: find dynamics for the (discounted) stock S

 $\mathrm{d}S_t = \sigma_t S_t \mathrm{d}W_t^{\mathbb{Q}}$ 

such that the values of  $\mathbb{E}^{\mathbb{Q}}\Phi(S_t)$  agree with those on the market, for liquid instruments  $\Phi$ , e.g. call options C(K,T).

- Black-Scholes:  $\sigma_t \equiv \sigma$ , too simple, volatility surface;
- Local volatility:  $\sigma_t = \sigma(S_t, t)$ ;
- Stochastic volatility:  $\sigma_t$  a Markovian diffusion process, correlated with but not determined by S (Bergomi, Heston, SABR,...).
- Rough volatility<sup>2</sup>: a stoch vol model in which  $\sigma_t$  has behaviour similar to  $0.1 \approx H$ -fBm on short timescales:
  - Good fit to market data (short dated smiles, term structure of the ATM vol skew) with relatively few parameters;
  - Statistical evidence from historical volatility.



<sup>&</sup>lt;sup>2</sup>Gatheral, Jaisson, and Rosenbaum (2018).

• In most rough vol models, *σ* is taken to be an explicit function of type-II fBm, e.g. rough Bergomi:

$$\begin{split} \sigma_t &= \exp \left( \nu B_t^H - \frac{1}{2} c_H^2 \nu^2 t^{2H} \right) \\ \text{where} \quad B_t^H &= c_H \int_0^t (t-s)^{H-1/2} \mathrm{d}B, \qquad B = \rho W + \sqrt{1-\rho^2} W^\perp. \end{split}$$

 $\cdot$  More complex models: take  $\sigma$  to satisfy a Volterra equation

$$\sigma_t = \sigma_0 + \int_0^t (t-s)^{H-1/2} \left( f(\sigma_s, s) \mathrm{d}s + g(\sigma_s, s) \mathrm{d}B_s \right).$$



- Challenges with rough vol:
  - $\cdot \ [\sigma,W] = \infty \implies$  no Stratonovich formulation or classical Wong-Zakai;
  - ·  $H \leq 1/4, W \not\perp B^H \implies (W, B^H)$  not a classical Gaussian rp.
- Use regularity structures<sup>3</sup> to precisely subtract the divergent Itô-Stratonovich correction originating from  $\mathbb{E}B_t^{H,\varepsilon}\dot{W}_t^{\varepsilon} \sim \rho\varepsilon^{H-1/2}$ .
- However this comes at the cost of heavy tools, which become intractable for Volterra equations with low *H*.
- Moreover, Volterra equations driven by B with kernel K(t,s) are different to ODEs driven by  $\int_0^t K(t,s) dB_s$  (even if B is  $C^{\infty}$ ), which are more basic and widespread.
- Since  $\sigma$  is one-dimensional, we could model it as an SDE with drift driven by  $B^H$ .
- However, currently no framework to treat general *joint* dynamics of price and vol, in the ODE sense, when the vol is rough.



<sup>&</sup>lt;sup>3</sup>Bayer, Friz, Gassiat, Martin, and Stemper (2020).

## The Itô lift of an adapted process

- W d-dimensional brownian motion, X an e-dimensional stochastic rough path. Goal: jointly lift X and W to a geometric rough path X.
- Use Greek letters  $\alpha, \beta, \gamma \in [d]$  for W, Latin letters  $i, j, k \in [e]$  for X. Define some terms with Stratonovich or Itô calculus. For  $\alpha, \beta \in [d]$ ,  $v \in [e]^{\bullet}$ :

$$\overline{\boldsymbol{X}}^{v} \coloneqq \boldsymbol{X}^{v}, \quad \overline{\boldsymbol{X}}_{s,t}^{\alpha\beta} \coloneqq \int_{s}^{t} W_{s,u}^{\alpha} \circ \mathrm{d}W_{u}^{\beta},$$

$$\overline{\boldsymbol{X}}_{s,t}^{v\alpha} \coloneqq \int_{s}^{t} \boldsymbol{X}_{s,u}^{v} \mathrm{d}W_{u}^{\alpha}.$$
(2)

•  $\boldsymbol{X}$  of Hölder regularity  $\in (1/3, 1/2]$  and deterministic<sup>4</sup>:

$$\alpha i = i \sqcup\!\!\sqcup \alpha - i \alpha \; \rightsquigarrow \; \overline{\boldsymbol{X}}^{\alpha i} \coloneqq X^i X^\alpha - \overline{\boldsymbol{X}}^{i \alpha}$$

• When the regularity is  $\leq 1/3$  there are more terms needed to define  $\overline{X}$ . Impose some conditions on X:

<sup>4</sup>Diehl, Oberhauser, and Riedel (2015).



#### Definition (Adapted *H*-integrable rough path)

An  $\mathcal{F}_{\bullet}$ -adapted *H*-integrable (geometric) rough path is an  $\mathcal{F}_{\bullet}$ -adapted,  $\mathcal{G}^{\lfloor 1/H \rfloor}(\mathbb{R}^e)$ -valued stochastic process X s.t.  $X_{s,t} := X_s^{-1} \otimes X_t$  satisfies the Chen identity and

 $\sup_{0 \le s \le t \le T} \| \boldsymbol{X}_{s,t}^v \|_{L^p}^p \lesssim_{p,T} (t-s)^{pH \cdot \#v}, \qquad p \in [1,+\infty).$ 

#### Theorem (Itô lift)

There exists a unique geometric rough path extending (2) on words  $\alpha\beta$ , v and  $v\alpha$  for  $v \in [e]^{\bullet}$ . It is  $\mathcal{F}_{\bullet}$ -adapted and

$$|\overline{\boldsymbol{X}}_{st}^{w}(\omega)| \lesssim_{p,T,\omega} (t-s)^{\lambda}, \qquad \lambda < |w|,$$

with the constant of proportionality  $\in L^p$  for all p.



## The Itô lift of an adapted process III

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• Main idea: only words left are of the form  $u\alpha v$  with  $u, v \in [e]^{\bullet}$ . Recursively express  $u\alpha v$  as a  $\square$ -polynomial in words  $u'\alpha, v' (\rightsquigarrow \overline{X} a$  polynomial in rough path terms already defined).

$$u\alpha j_1 \dots j_n = u\alpha \sqcup j_1 \dots j_n - \sum_{k=1}^n (u \sqcup j_1 \dots j_k)\alpha j_{k+1} \dots j_n.$$

• E.g. 
$$i\alpha jk$$
  

$$= i\alpha \sqcup jk - (i \sqcup j)\alpha k - (i \sqcup jk)\alpha$$

$$= i\alpha \sqcup jk - ij\alpha k - ji\alpha k - ijk\alpha - jik\alpha - jki\alpha$$

$$= i\alpha \sqcup jk - [ij\alpha \sqcup k - (ij \sqcup k)\alpha] - [ji\alpha \sqcup k - (ji \sqcup k)\alpha] - ijk\alpha - jik\alpha - jki\alpha$$

$$= i\alpha \sqcup jk - ij\alpha \sqcup k + ikj\alpha + kij\alpha - ji\alpha \sqcup k + kji\alpha.$$

- BDG + Kolmogorov + above statement → Hölder regularity.
- Chen identity is inherited, shuffle property holds by construction.



### A rough path for rough volatility

• Take X to be the canonical rough path above  $X = B^H$ (0.1  $\approx$  H-fBm correlated with X).

#### Proposition

$$\overline{\boldsymbol{X}}_{s,t}^{0^m \alpha 0^n} = \int_s^t \frac{(X_u - X_s)^m}{m!} \frac{(X_t - X_u)^n}{n!} dW_u^\alpha$$
$$\coloneqq \sum_{k=0}^n \frac{X_t^{n-k}}{m!k!(n-k)!} \int_s^t X_{su}^m (-X_u)^k W_u^\alpha.$$

• Consider general dynamics of the form

$$\begin{cases} \mathrm{d}S_t = \sigma_\alpha(S_t, V_t, t) \mathrm{d}\boldsymbol{W}_t^\alpha + g(S_t, V_t, t) \mathrm{d}t, \\ \mathrm{d}V_t = \tau(S_t, V_t, t) \mathrm{d}\boldsymbol{X}_t + \varsigma_\alpha(S_t, V_t, t) \mathrm{d}\boldsymbol{W}_t^\alpha + h(S_t, V_t, t) \mathrm{d}t. \end{cases}$$
(3)



### A rough path for rough volatility II

#### Proposition

 $\boldsymbol{S}$  is given by Itô and Riemann integration as

$$S_{t} = S_{0} + \int_{0}^{t} \sigma(S_{u}, V_{u}, u) dW_{u} + \int_{0}^{t} \left[\frac{1}{2} \sum_{\alpha} (\partial_{S} \sigma_{\alpha} \sigma_{\alpha} + \partial_{V} \sigma_{\alpha} \varsigma_{\alpha}) + g\right] (S_{u}, V_{u}, u) du.$$

- Proof: compare Davie expansions. Interesting to consider the Davie expansion of V ( $1/3 < H \le 1/2$ ):

$$\begin{split} V_{uv} &\approx \tau X_{uv} + \varsigma_{\gamma} W_{uv}^{\gamma} + h \cdot (v - u) + (\partial_V \varsigma_{\beta} \varsigma_{\alpha} + \partial_S \varsigma_{\beta} \sigma_{\alpha}) \int_{u}^{v} W_{ur}^{\alpha} \circ \mathrm{d}W_{r}^{\beta} + \partial_V \tau_{j} \tau_{i} \boldsymbol{X}_{uv}^{ij} \\ &+ [\left(\begin{smallmatrix} 0 \\ \tau_{k} \end{smallmatrix}\right), \left(\begin{smallmatrix} \sigma_{\gamma} \\ \varsigma_{\gamma} \end{smallmatrix}\right)]^{V} \int_{u}^{v} X_{ur}^{k} \mathrm{d}W_{r}^{\gamma} + (\partial_S \tau_{k} \sigma_{\gamma} + \partial_V \tau_{k} \varsigma_{\gamma}) X_{uv}^{k} W_{uv}^{\gamma}, \\ \text{and if } [X, W] < \infty \text{ the second line is equal to} \\ &+ \tau_{k} \partial_V \varsigma_{\gamma} \int_{u}^{v} X_{ur}^{k} \circ \mathrm{d}W_{r}^{\gamma} + (\partial_V \varsigma_{\beta} \varsigma_{\alpha} + \partial_S \varsigma_{\beta} \sigma_{\alpha}) \int_{u}^{v} W_{ur}^{\gamma} \circ \mathrm{d}X_{r}^{k} - \frac{1}{2} [\left(\begin{smallmatrix} 0 \\ \tau_{k} \end{smallmatrix}\right), \left(\begin{smallmatrix} \sigma_{\gamma} \\ \varsigma_{\gamma} \end{smallmatrix}\right)]^{V} [X^{k}, W^{\gamma}]_{uv}. \end{split}$$

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 $\begin{cases} \mathrm{d}S_t = \sigma_\alpha(S_t, V_t, t) \mathrm{d}\boldsymbol{W}_t^\alpha + g(S_t, V_t, t) \mathrm{d}t, \\ \mathrm{d}V_t = \tau(S_t, V_t, t) \mathrm{d}\boldsymbol{X}_t + \varsigma_\alpha(S_t, V_t, t) \mathrm{d}\boldsymbol{W}_t^\alpha + h(S_t, V_t, t) \mathrm{d}t. \end{cases}$ 

- For some dynamics only the original rough path terms are needed: this occurs when  $\varsigma = 0$  and  $\tau$  does not depend on S. This has already been used for "simple" models  $(V_t = f(X_t))$ .<sup>5</sup>
- Correlation between V (rough process that feeds into the diffusion coeff. for S) and S can even be introduced if  $X \perp W$ , thanks to  $\varsigma$ . In this case,  $\overline{X}$  can be viewed as a Gaussian rough path with non i.d. components (the condition is  $H_i + H_j > 1/2$ , always verified if  $H_j = 1/2$ ).
- Includes many models already in the literature, possible to consider multi-asset extensions.



<sup>&</sup>lt;sup>5</sup>Fukasawa and Takano (2024).

## Lead-lag approximations

- How to simulate RDEs? Euler scheme requires prior simulation of rough path terms and derivatives of order-10.
- Every geometric rough path **X** is the limit (in rough path topology) of the Stieltjes lifts of a sequence of smooth paths:

$$\begin{aligned} \boldsymbol{X}_{s,t}^{\alpha_{1}\dots\alpha_{n}} &= \lim_{\varepsilon \to 0} \int_{s < u_{1} < \dots < u_{n} < t} \dot{X}_{u_{1}}^{\varepsilon,\alpha_{1}} \cdots \dot{X}_{u_{n}}^{\varepsilon,\alpha_{n}} \mathrm{d}u_{1} \cdots \mathrm{d}u_{n} \\ & \stackrel{\text{ULT}}{\Longrightarrow} \left( \mathrm{d}Y^{\varepsilon} = F(Y^{\varepsilon}) \mathrm{d}X^{\varepsilon} \right) \xrightarrow{\varepsilon \to 0} \left( \mathrm{d}Y = F(Y) \mathrm{d}X \right) \end{aligned}$$

- **X** Stratonovich lift:  $X^{\varepsilon}$  pwl interpolation,  $X^{\varepsilon} = \varphi_{\varepsilon} \star X$ , etc.
- Itô integrals of one-forms can also be approximated smoothly:<sup>6</sup>

$$\int f(W_t) \mathrm{d}W_t = \lim_{\varepsilon \to 0} \int f(W_t^{\varepsilon,-}) \dot{W}_t^{\varepsilon} \mathrm{d}t.$$

• Define  $(X = B^H)$  for  $t_{i+1} - t_i = \varepsilon$ ,  $t \in [t_i, t_{i+1}]$  piecewise lead-lag approximations

$$W_t^{\varepsilon} \coloneqq W_{t_i} + \frac{t - t_i}{\varepsilon} W_{t_i, t_{i+1}}, \quad X_t^{\varepsilon, -} \coloneqq X_{t-\varepsilon}^{\varepsilon}.$$



<sup>&</sup>lt;sup>6</sup>Flint, Hambly, and Lyons (2016).

## Lead-lag approximations II

Theorem (Strong convergence of lead-lag)

 $\|\|\overline{oldsymbol{X}}-\overline{oldsymbol{X}}^{arepsilon}\|_{\mathscr{C}}\|_{\mathscr{C}}\|_{L^p}\lesssim arepsilon^H$ 

for all  $p \ge 1$  and moreover the convergence is a.s. if the sequence of partitions is regular.

• Similar results using hybrid scheme approximations

$$\int_{0}^{t_{k}} (t_{k} - s)^{H - 1/2} \mathrm{d}B_{s}$$

$$\approx \sum_{i=1}^{k-1} \int_{t_{i-1}}^{t_{i}} (t_{k} - s)^{H - 1/2} \mathrm{d}s \cdot W_{t_{i-1}, t_{i}} + \int_{t_{k-1}}^{t_{k}} (t_{k} - s)^{H - 1/2} \mathrm{d}W_{s}$$

and for mollifier approximations.



• Simulate  $X^{\varepsilon,-}, W^{\varepsilon}$  on a grid and solve CDEs driven by them on a grid several times finer, using Diffrax<sup>7</sup>.

 $\rightsquigarrow$  notebook



<sup>7</sup>Kidger (2023).

# Calibration

• Model:

$$\begin{cases} \frac{\mathrm{d}S_t}{S_t} = \sqrt{a(Z_t - b)^2 + c} \circ \mathrm{d}W_t - \frac{1}{2} \left( a(Z_t - b)^2 + c \right) \mathrm{d}t, & S_0 = s_0 > 0, \\ \mathrm{d}Z_t = \lambda(\theta - Z_t) \mathrm{d}t + \lambda \eta \sqrt{a(Z_t - b)^2 + c} \circ \mathrm{d}B_t^H, & Z_0 = z_0 > 0, \end{cases}$$

• Minimise loss function:

$$\mathcal{L}(a, b, c, \lambda, \theta, \eta) \coloneqq \sum_{j=1}^{L_i} \left( C_{T, K_j}(a, b, c, \lambda, \theta, \eta) - C_{T, K_j}^{\text{obs}} \right)^2,$$



# Thank you

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