

Pathwise well-posedness of stochastic nonlinear Schrödinger equation with multiplicative noises

Guangqu Zheng

joint with Tadahiro Oh (Edinburgh)



THE UNIVERSITY
of EDINBURGH

Problem

Stochastic nonlinear Schrödinger equation posed on d -dimensional torus \mathbb{T}^d :

$$i\partial_t u + \Delta u = |u|^{2k}u + \boxed{u\Phi\zeta} \quad \text{multiplicative noise (SNLS)}$$

$$u|_{t=0} = u_0 \in H^s(\mathbb{T}^d)$$

- power nonlinearity $\mathcal{N}(u) = |u|^{2k}u$, $k \in \mathbb{N}_0$
- $\zeta =$ space-white, time-fractional/white noise on $\mathbb{R} \times \mathbb{T}^d$
- $\Phi =$ Hilbert-Schmidt operator from $L^2(\mathbb{T}^d)$ to $H^s(\mathbb{T}^d)$: $\widehat{\Phi}f(n) = \phi(n)\widehat{f}(n)$ s.t. $\phi(n)(1+|n|^2)^{s/2} \in \ell^2(\mathbb{Z}^d)$

■ Cylindrical process $W(t, x) = \sum_{n \in \mathbb{Z}^d} \beta_n(t) \phi(n) e^{in \cdot x}$

■ $\{\beta_n\} =$ independent complex fractional Brownian motions with $\beta_{-n} = \overline{\beta_n}$ & Hurst index $\gamma \in (0, 1) \Rightarrow \beta_n(t) \in \mathcal{C}_t^{\gamma-\varepsilon}$; $\gamma = 1/2$ corresp. to Brownian motion $\Rightarrow W(t, x) \in \mathcal{C}_t^{\gamma-\varepsilon} H_x^s$

Goal: Get pathwise local well-posedness

Duhamel formulation: ($S_t = e^{it\Delta}$ linear Schrödinger propagator)

$$u_t = S_t u_0 - i \int_0^t S_{t-r} \mathcal{N}(u)(r) dr - i \underbrace{\int_0^t S_{t-r} u_r dW_r}_{\text{stochastic convolution}} \quad \text{(mild)}$$

\Rightarrow Need to define the **stochastic convolution**

$\gamma = 1/2$ White-in-time, Ito calculus

- de Bouard-Debussche '99, '03
- Brzeźniak-Millet '14
- Brzeźniak-Hornung-Weis '19
- Cheung-Mosincat '19

■ The stochastic convolution

$$\int_0^t S_{t-r} u_r dW_r \quad \text{(Sto.Conv.)}$$

- = Ito integral, **NOT pathwise**
- What if $\gamma \neq 1/2$?
No martingale structure, THEN?

Main task: Define (Sto.Conv.) in a **pathwise** manner for all $\gamma \in (0, 1)$

Theorem (Oh-Zheng '22) \approx 1st pathwise LWP result

For $\gamma \in [1/2, 1)$, and $s > d/2$. Then, (SNLS) is locally well posed in $H^s(\mathbb{T}^d)$.

First difficulty: deficiency of temporal regularities

- $f: \mathbb{R} \rightarrow \mathbb{R}$ continuous, $g: \mathbb{R} \rightarrow \mathbb{R}$ of bounded variation

$$\Rightarrow \mathcal{I}_{t,r} := \int_r^t f dg \quad \text{Riemann-Stieltjes integral}$$

- Extension to $f \in \mathcal{C}^\alpha$, $g \in \mathcal{C}^\beta \Rightarrow$

- $\alpha + \beta > 1$: **Young** integral (Young '36)
- $\alpha + \beta \leq 1$: **rough** integral (**rough path theory**: Lyons '98, Gubinelli '04)

- Back to the **infinite-dimensional setting** (i.e. $H^s(\mathbb{T}^d)$ -valued paths)

$$\int_0^t \underbrace{S_{t-r}}_{\text{bad}} \underbrace{u_r}_{\gamma-\varepsilon} \underbrace{dW_r}_{\gamma-\varepsilon} \Rightarrow \text{deficiency in temporal regularities even in Young case}$$

Reduction via interaction representation: Apply $v_t = S_{-t} u_t$ to (mild) \Rightarrow

Equivalent formulation:

$$v_t = v_0 + (-i) \int_0^t S_{t-r} \mathcal{N}(S_r v_r) dr + (-i) \int_0^t S_{t-r} (S_r v_r) dW_r$$

- Why interaction representation? $\Leftarrow v \in \mathcal{C}_t^\gamma H_x^s$ leads to $S_t v_t \in \mathcal{C}_t^\gamma H_x^{s-2\gamma}$ “interplay between temporal and spatial regularities”

- $H^s(\mathbb{T}^d)$ Hilbert-algebra \Rightarrow power-nonlinearity $\mathcal{N} =$ easy term

From now on, focus on

$$v_t = v_0 + \int_0^t S_{t-r} dW_r S_r v_r \quad \text{(mild2)}$$

Next: Young & rough cases \Leftarrow controlled rough paths + PDE ideas

Notations: $(\delta f)_{t_1, t_2} = f_{t_1} - f_{t_2}$, $(\delta g)_{t_1, t_2, t_3} = g_{t_1, t_3} - g_{t_1, t_2} - g_{t_2, t_3}$ for $t_1 > t_2 > t_3$

Sewing lemma (Gubinelli '04, Gubinelli-Tindel '10) *Formally*, for a 2-parameter process in $H^s(\mathbb{T}^d)$ with $\delta g \sim 1 + \varepsilon$ (temporal) regularity $\|(\delta g)_{t_1, t_2, t_3}\|_{H_x^s} \lesssim |t_1 - t_3|^{1+\varepsilon}$, we can *invert* $g = \Lambda \delta g$ with $\Lambda =$ sewing map.

Young case: $\gamma \in (1/2, 1)$

Main task: Need to define

$$\mathcal{I}_{t,r} = \int_r^t S_{-t_1} dW_{t_1} S_{t_1} v_{t_1}$$

- $\mathcal{I}_{t,r} = \int_r^t S_{-t_1} dW_{t_1} S_{t_1} v_r + R_{t,r} =: \mathbf{X}_{t,r} v_r + R_{t,r}$

■ introduced integral (random) operators $\mathbf{X}_{t,r}$ (Q1: definition & properties?)

■ How to define the remainder $R_{t,r}$?

- Apply the finite-difference operator δ to both sides (see **Notations**):

(i) LHS additive over disjoint interval $\Rightarrow (\delta \mathcal{I})_{t_1, t_2, t_3} = \mathcal{I}_{t_1, t_3} - \mathcal{I}_{t_1, t_2} - \mathcal{I}_{t_2, t_3} = 0$

(ii) For RHS: Simple algebraic computation $\Rightarrow (\delta \mathbf{X} v)_{t_1, t_2, t_3} = -\mathbf{X}_{t_1, t_2} (\delta v)_{t_2, t_3}$

$$(i) + (ii) \Rightarrow (\delta R)_{t_1, t_2, t_3} = \underbrace{\mathbf{X}_{t_1, t_2}}_{\gamma-\varepsilon?} (\delta v)_{t_2, t_3}$$

$$\gamma-\varepsilon? \quad \gamma-\varepsilon \rightarrow \text{sum} = 2\gamma - 2\varepsilon > 1$$

- **Sewing lemma** \Rightarrow We can define

$$R = \Lambda \delta R = \Lambda \mathbf{X} \delta v = -\Lambda \delta \mathbf{X} v$$

Once **Q1** answered, we can define

$$\int_r^t S_{-t_1} dW_{t_1} S_{t_1} v_{t_1} = [(\text{Id} - \Lambda \delta)(\mathbf{X} v)]_{t,r}$$

Answer to Q1:

$$\|\mathbf{X}_{t,r}\|_{H^s \rightarrow H^s} \lesssim |t-r|^{\gamma-\varepsilon} \quad \text{(OP)}$$

On Fourier side: $\mathcal{F}_x(\mathbf{X}_{t,r} f)(n) = \sum_{\substack{n_1, n_2 \in \mathbb{Z}^d \\ n_1 + n_2 = n}} \underbrace{\int_r^t e^{it_1(|n_1|^2 - |n_2|^2)} \phi(n_1) d\beta_{n_1}(t_1) \widehat{f}(n_2)}_{\text{Wiener integral}}$

with split $\mathbf{X} = \mathbf{X}^g + \mathbf{X}^b$ (n_1 much smaller, $\phi(n_1)$ can not absorb n)
 $|n| \sim |n_2| \gg |n_1|$

Key ingredients in the proof of (OP)

- **good part:** Random matrix estimates
 - $\gamma = 1/2$: Deng-Nahmod-Yue '22, Bringmann '22, Oh-Wang-Zine '22
 - $\gamma > 1/2$: fractional Brownian motion analogue Oh-Zheng '22
- **bad part:** Schur's test + Kolmogorov continuity argument

Rough case: $\gamma = 1/2$, Brownian-in-time

- Like (scalar) rough integral, immediate issue = **deficiency of temporal regularity**
- **worse** mapping property of the integral operator \mathbf{X} (to be proved similarly):

$$\mathbf{X}_{t,r}^g: H^s(\mathbb{T}^d) \rightarrow H^s(\mathbb{T}^d) \quad \text{and} \quad \mathbf{X}_{t,r}^b: H^s(\mathbb{T}^d) \rightarrow H^{s-\varepsilon}(\mathbb{T}^d)$$

\Rightarrow Need to reformulate (**mild2**):

(I) **Finite difference viewpoint from controlled rough path:**

$$(\delta v)_{t,r} = \mathbf{X}_{t,r}(v_\bullet) \quad (1)$$

$$= \mathbf{X}_{t,r}^g(v_\bullet) + \mathbf{X}_{t,r}^b(v_\bullet)$$

$$= \mathbf{X}_{t,r}^g(v_\bullet) + \mathbf{X}_{t,r}^b(v_0) + \mathbf{X}_{t,r}^b[(\delta v)_{\bullet,0}] \quad (2)$$

(II) **Partial iterations of Duhamel formulation:**

$$(\delta v)_{t,r} = \mathbf{X}_{t,r}^g(v_\bullet) + \mathbf{X}_{t,r}^b(v_0) + \mathbf{X}_{t,r}^b[\mathbf{X}_{\bullet,0}(v_\bullet)] \Leftarrow \text{plug (1) into (2)}$$

$$= \mathbf{X}_{t,r}^g(v_\bullet) + \mathbf{X}_{t,r}^b(v_0) + \mathbf{X}_{t,r}^b[\mathbf{X}_{\bullet,0}(v_0)] + \mathbf{X}_{t,r}^b[\mathbf{X}_{\bullet,0}((\delta v)_{\bullet,0})]$$

$$=: \mathbf{X}_{t,r}^g(v_\bullet) + \sum_{j=1}^2 \mathbf{X}_{t,r}^b(\mathbf{X}_{\bullet,0}^{j-1} v_0) + \mathbf{X}_{t,r}^b(\mathbf{X}_{\bullet,0}^2(v_\bullet))$$

$$= \sum_{j=1}^J \mathbf{X}_{t,r}^b(\mathbf{X}_{\bullet,0}^{j-1} v_0) + \mathbf{X}_{t,r}^g(v_\bullet) + \mathbf{X}_{t,r}^b[\mathbf{X}_{\bullet,0}^J(v_\bullet)]$$

for W temporal smooth: **vanishes** as $J \rightarrow \infty$

where $\mathbf{X}_{t,r}^j(v_\bullet) = \mathbf{X}_{t,r}[\mathbf{X}_{\bullet,0}^{j-1}(v_\bullet)]$

$$(I) + (II) \Rightarrow (\delta v)_{t,r} = \sum_{j=1}^{\infty} \mathbf{X}_{t,r}^b(\mathbf{X}_{\bullet,0}^{j-1} v_0) + \mathbf{X}_{t,r}^g(v_\bullet) \quad \text{(mild3)}$$

■ **infinite sum** = influence of **bad part** from each iteration, only depends on v_0

■ mapping property of \mathbf{X}^b on generic element in $H^s(\mathbb{T}^d) =$ bad

BUT $\mathbf{X}_{t,r}^b(\mathbf{X}_{\bullet,0}^{j-1} v_0) \in H^s(\mathbb{T}^d)$ defined a priori via stochastic analysis

Main task now = Define $\mathbf{X}_{t,r}^g(v_\bullet)$; Then solve (mild3) via standard fixed-point

• **Impose a controlled structure:** In view of (mild3)

$$(\delta v)_{t,r} = \sum_{j=1}^{\infty} \mathbf{X}_{t,r}^b(\mathbf{X}_{\bullet,0}^{j-1} v_0) + \mathbf{X}_{t,r}^g v_r + R_{t,r} \quad \boxed{R_{t,r} \sim 1-}$$

- **Insert the controlled structure** into $\mathbf{X}_{t,r}^g(v_\bullet) = \mathbf{X}_{t,r}^g(v_r) + \mathbf{X}_{t,r}^g((\delta v)_{\bullet,r}) \Rightarrow$

$$\mathbf{X}_{t,r}^g(v_\bullet) = \mathbf{X}_{t,r}^g(v_r) + \mathbf{X}_{t,r}^g\left(\sum_{j=1}^{\infty} \mathbf{X}_{t,r}^b(\mathbf{X}_{\bullet,0}^{j-1} v_0)\right) + \underbrace{\mathbf{X}_{t,r}^g(\mathbf{X}_{\bullet,r}^g)}_{\mathbf{X}_{t,r}^g} v_r + \underbrace{Q_{t,r}}_{\text{def?}}$$

- Apply δ as before $\Rightarrow (\delta Q)_{t_1, t_2, t_3} = \underbrace{\mathbf{X}_{t_1, t_2}^g R_{t_2, t_3}}_{(1/2)-} + \underbrace{\mathbf{X}_{t_1, t_2}^g (\delta v)_{t_2, t_3}}_{(1/2)-} \sim 1+$

- **Sewing lemma** $\Rightarrow Q = \Lambda \delta Q \Rightarrow \mathbf{X}_{t,r}^g(v_\bullet) = [(\text{Id} - \Lambda \delta) \text{previous box}]_{t,r}$

■ infinite-sum term motivated by spatial-regularity loss

■ 2nd-order operator \mathbf{X}^g motivated by deficiency in temporal and spatial regularity

What else to do? Rougher noise ($\gamma < 1/2$; $s \leq d/2$), $u^k \Phi \zeta$ for $k \geq 2$,

still reading? Thanks! **END**