

# A probabilistic formula for the gradient of solutions of some Hypoelliptic Dirichlet problems

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# Introduction and setting of the problem

Consider the following problem in  $H = \mathbb{R}^d$ ,

$$\begin{cases} D_t u(t, x) = \frac{1}{2} \operatorname{Tr} [C D_x^2 u(t, x)] + \langle Ax, D_x u(t, x) \rangle, & t \geq 0, x \in \mathbb{R}^d, \\ u(0, x) = \varphi(x) \in \mathbb{R}^d \end{cases} \quad (1)$$

where  $A$  and  $C$  are  $d \times d$  matrices and  $C$  is semi-definite positive. We shall assume that

$$\det \left( \int_0^T e^{tA} C e^{tA^*} dt \right) > 0, \quad \forall T > 0. \quad (2)$$

Therefore the operator above is **hypoelliptic**.  
We are mainly interested in the case when, besides (2), we have  $\det C = 0$ ; in this case the problem is **degenerate**.

It is well known that, under assumption (2), problem (1) has a unique  $C^\infty$  strict solution, given by

$$u(t, x) = \mathbb{E}[\varphi(X(t, x))], \quad t > 0, x \in \mathbb{R}^d, \quad (3),$$

where  $X(t, x)$  is the Ornstein–Uhlenbeck process

$$X(t, x) = e^{tA}x + \int_0^t e^{(t-s)A} \sqrt{C} dW(s) =: e^{tA}x + W_A(t),$$

and  $W$  is an  $\mathbb{R}^d$ -valued Wiener process on a probability space

$$(\Omega, \mathcal{F}, \mathbb{P}).$$

This talk is devoted to the regularity of the solution to the following **Cauchy–Dirichlet** problem,

$$\begin{cases} D_t(t, x) = \frac{1}{2} \operatorname{Tr}[CD_x^2 u(t, x)] + \langle Ax, D_x u(t, x) \rangle, & t > 0, x \in \mathcal{O}_r, \\ u(t, x) = 0, & t > 0, x \in \partial \mathcal{O}_r, \\ u(0, x) = \varphi(x), & x \in \mathcal{O}_r, \end{cases} \quad (5)$$

where  $\mathcal{O}_r$  is an open, bounded subset of  $\mathbb{R}^d$  of the form  $\mathcal{O}_r = \{g < r\}$ ,  $g$  being regular and **convex**, and  $\varphi \in B_b(\mathbb{R}^d)$  is bounded and Borel.

A solution of problem (5) is provided by the probabilistic formula

$$u(T, x) = \mathbb{E} [\varphi(X(T, x)) \mathbb{1}_{T \leq \tau_x}], \quad T > 0, x \in \overline{\mathcal{O}_r},$$

where  $\tau_x$  is the **exit time** of  $X(\cdot, x)$  from  $\overline{\mathcal{O}_r}$ ,

$$\tau_x = \inf\{s \in [0, T] : e^{sA}x + W_A(s) \in \overline{\mathcal{O}_r}^c\}.$$

In other words,

$$\begin{aligned} u(T, x) &:= \mathbb{R}_T^{\mathcal{O}_r} \varphi(x) = \\ &= \int_{\{g(e^{sA}x + W_A(s)) \leq r, \forall 0 \leq s \leq T\}} \varphi(e^{TA}x + W_A(T)) d\mathbb{P}. \end{aligned} \tag{5}$$

By this formula it is hard to show the existence of the gradient of  $u(T, x)$  up to the boundary of  $\mathcal{O}_r$ .

By using suitable transformations of identity (5) we shall prove, however, the existence of

$$D_x R_T^{\mathcal{O}_r} \varphi$$

up to the boundary as well as an explicit formula when  $\varphi$  is just Borel and bounded on  $\overline{\mathcal{O}_r}$

# Some references

Regularity of  $u(T, x)$  at the interior of  $\mathcal{O}_r$  was proved by

*Dynkin, Markov processes, Springer 1965.*

Regularity up to the boundary for **general** hypoelliptic operators has been proved by

*Cattiaux, Bull. Sci. Math. (I) and (II), 90-91*

using **Malliavin calculus**; but his results do not cover problem (5), because he requires  $\det C > 0$ .

We believe that our method should work for more general equations of the form

$$D_t u(t, x) = \frac{1}{2} \text{Tr} [C D_x^2 u(t, x)] + \langle Ax + b(x), D_x u(t, x) \rangle.$$

where  $b : \mathbb{R}^d \rightarrow \mathbb{R}^d$  is nonlinear and regular.



## Example

Let  $d = 2$ ,  $x = (x_1, x_2)$ ,  $\mathcal{O} = B_1 = \{x \in \mathbb{R}^2 : |x| < 1\}$ .

$$\begin{cases} D_t u(t, x_1, x_2) = \frac{1}{2} D_{x_1}^2 u(t, x_1, x_2) + x_1 D_{x_2} u(t, x_1, x_2) \\ u(t, x) = 0, \quad |x| = 1, \\ u(0, x) = \varphi(x), \quad x = (x_1, x_2) \in \mathbb{R}^2. \end{cases}$$

Then  $A = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$ ,  $C = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$ . Consequently

$$Q_t = \int_0^t e^{sA} C e^{sA^*} ds = \int_0^t \begin{pmatrix} 1 & s \\ s & s^2 \end{pmatrix} ds = \begin{pmatrix} t & t^2/2 \\ t^2/2 & t^3/3 \end{pmatrix}.$$

Therefore  $\det C = 0$  but  $\det Q_t > 0$  for any  $t > 0$ .



# The main result

We fix  $T > 0$  and set  $u(T, x) = R_T^{\theta_r} \varphi(x)$ . Then we start by the previous identity

$$R_T^{\theta_r} \varphi(x) = \int_{\{g(e^{sA}x + W_A(s)) \leq r, \forall 0 \leq s \leq T\}} \varphi(e^{TA}x + W_A(T)) d\mathbb{P}. \quad (5)$$

We make the change of variables

$$\Omega \rightarrow X = L^2(0, T; \mathbb{R}^d), \quad \omega \rightarrow W_A(\cdot)(\omega),$$

$$R_T^{\theta_r} \varphi(x) = \int_{\{g(e^{sA}x + h(s)) \leq r, \forall 0 \leq s \leq T\}} \varphi(e^{TA}x + h(T)) N_{\mathbb{Q}_T}(dh), \quad (6)$$

where  $N_{\mathbb{Q}_T}$  is the law of  $W_A(\cdot)$  in  $X$ , which is Gaussian as well known.

To show that  $R_T^{\sigma_r} \varphi$  is differentiable, we shall first eliminate  $e^{TA}x$  from the argument of  $\varphi$  using the **Cameron–Martin** formula.

The obvious translation  $h \rightarrow h - e^A x$  does not work, because the measures  $N_{e^A x, \mathbb{Q}_T}$  and  $N_{\mathbb{Q}_T}$  are **singular** for  $x \neq 0$ .

For this reason we construct another translation  $h \rightarrow h - a(x, \cdot)$  such that  $a(x, \cdot)$  **belongs** to  $\mathbb{Q}_T(X)$  for all  $x \in H$  and:

$$a(x, T) = e^{TA}x, \quad \forall x \in H.$$

With such a translation  $h \rightarrow h - a(x, \cdot)$ , we shall find

$$\varphi(e^{TA}x + h(T)) \rightarrow \varphi(h(T))$$

so that  $x$  will disappear from  $\varphi$ .

$a(x, \cdot)$  is provided by the following simple lemma.

### Lemma

For all  $T > 0$  the matrix

$$V := \int_0^T r e^{rA} C e^{rA^*} dr$$

is non singular. Moreover, setting

$$v(x, t) := e^{(T-t)A^*} V^{-1} e^{TA} x, \quad t \in [0, T], x \in X.$$

and

$$a(x, \cdot) := \mathbb{Q}_T v(x, \cdot), \quad x \in H,$$

it results

$$a(x, T) = e^{TA} x, \quad \forall x \in H,$$

as required.

Since measures  $N_{a(x,\cdot),\mathbb{Q}_T}$  and  $N_{\mathbb{Q}_T}$  are equivalent, by the **Cameron–Martin Theorem** we have

$$\frac{dN_{a(x,\cdot),\mathbb{Q}_T}}{dN_{\mathbb{Q}_T}}(h) = \exp \left\{ -\frac{1}{2} \|\mathbb{Q}_T^{-1/2} a(x, \cdot)\|_X^2 + \langle \mathbb{Q}_T^{-1/2} a(x, \cdot), \mathbb{Q}_T^{-1/2} h \rangle_X \right\},$$

After some simple computations, we can write

$$\frac{dN_{a(x,\cdot),\mathbb{Q}_T}}{dN_{\mathbb{Q}_T}}(h) = \exp \left\{ -\frac{1}{2} F(x) + G(x, h) \right\}, \quad x \in H, h \in X,$$

where

$$F(x) := \langle v(x, t), a(x, \cdot) \rangle_X$$

and,

$$G(x, h) = \langle v(x, t), h \rangle_X.$$

Note that both  $F$  and  $G$  are regular.

Now our identity becomes

$$R_T^{\mathcal{O}_r} \varphi(x) = \int_{\{M(h+d(x,\cdot)) \leq r\}} \varphi(h(T)) \exp \left\{ -\frac{1}{2} F(x) + G(x, h) \right\} N_{\mathbb{Q}_T}(dh), \quad (7)$$

where for all  $x \in \overline{\mathcal{O}_r}$ , we have:

$$d(x, t) = e^{tA} x - a(x, t), \quad t \in [0, T],$$

and

$$M(h+d(x, \cdot)) = \sup_{t \in [0, T]} \{g(h(t)+d(x, t))\}, \quad h \in X = L^2(0, T]; \mathbb{R}^d.$$

Note that the variable  $x$  does not appear anymore in the argument of  $\varphi$  but only in the domain of integration of (7).

## Remark

One can show that the measure  $N_{Q_T}$  is concentrated on  $E := C([0, T]; \mathbb{R}^d)$ .

Moreover, its **Cameron–Martin** space is still given by  $Q_T^{1/2}(X)$ .

As a consequence, integrations with respect to  $N_{Q_T}$  can be performed equivalently both in  $E$  and in  $X$ , giving the same results.

Since the mapping  $x \rightarrow M(h + d(x, \cdot))$  is continuous on  $E$  the semigroup  $R_T^{\theta_r}$ ,  $T > 0$ , is **strong Feller** that is

$$\varphi \in B_b(\overline{\mathcal{O}_r}) \Rightarrow R_T^{\theta_r} \varphi \in C_b(\overline{\mathcal{O}_r}), \quad \forall T > 0.$$

More difficult is to show that  $R_T^{\theta_r} \varphi$  is  $x$ -differentiable for all  $\varphi \in B_b(\overline{\mathcal{O}_r})$  and all  $T > 0$ .

As it is expected, differentiation of  $R_T^{\theta_r} \varphi$  will produce infinite dimensional surface integrals which, unfortunately, cannot be handled by the classical theory of

*Airault–Malliavin, Bull. Sci. Math. 88*

To overcome this difficulty we shall introduce an approximation  $R_{T,n}^{\theta_r} \varphi$  of  $R_T^{\theta_r} \varphi$  defined by **finite dimensional** integrals.

More precisely, we shall replace any function  $h$  from  $E$  by a suitable **step function**.

Let

$$\sigma_n := \{t_j = j T 2^{-n}, \quad j = 0, 1, \dots, 2^n\}, \quad n \in \mathbb{N},$$

be a decomposition of  $[0, T]$ ; then the linear mapping

$$E = C([0, T]; H) \rightarrow H^{2^n}, \quad h \rightarrow (h(t_1), h(t_2), \dots, h(t_{2^n})),$$

has a Gaussian law, say  $N_{\mathbb{Q}_{T,n}}$ .



Now we define

$$R_{T,n}^{\theta_r} \varphi(x) = \int_{\{M_n(\xi+d(x,\cdot)) \leq r\}} \varphi(\xi_{2^n}) \exp\{-\frac{1}{2} F(x) + G^n(x, \xi)\} N_{\mathbb{Q}_{T,n}}(d\xi),$$

where

$$M_n(\xi+d(x, \cdot)) = \max \{g(\xi_j + d(x, t_j)), t_j = j T 2^{-n}, j = 0, 1, \dots, 2^n\}$$

and

$$G^n(x, \xi) = \sum_{j=1}^{2^n} (v(x, t_j) \cdot \xi_j) (t_j - t_{j-1}), \quad \xi \in H^{2^n},$$

recall that  $G(x, h) = \langle v(x, t), h \rangle_x$ .

Now we can differentiate  $R_{T,n}^{\theta_r} \varphi(x)$  in any direction  $y \in \mathbb{R}^d$ .

$$D_x R_{T,n}^{\theta_r} \varphi(x) \cdot y =: I_1(n, x, y) + I_2(n, x, y),$$

where

$$I_1(n, x, y) = \int_{\{M_n(h+d(x,\cdot)) \leq r\}} \varphi(h(T)) \exp \left\{ -\frac{1}{2} F(x) + G^n(x, h) \right\} \\ \times \left( -\frac{1}{2} F_x(x)y + G_x^n(x, h)y - G_h^n(x, h) \cdot (d_x(x, \cdot)y) \right) N_{\mathbb{Q}_T}(dh). \quad (8)$$

$$I_2(n, x, y) = \int_{\{M_n(h+d(x,\cdot)) \leq r\}} \varphi(h(T)) \exp \left\{ -\frac{1}{2} F(x) + G^n(x, h) \right\} \\ \times \langle \mathbb{Q}_{T,n}^{-1/2} (d_x(x, \cdot)y), \mathbb{Q}_{T,n}^{-1/2} h \rangle_{H^{2n}} N_{\mathbb{Q}_T}(dh). \quad (9)$$

Letting  $n \rightarrow \infty$  in  $I_1(n, x, y)$  is easy, just by using the Dominated Convergence Theorem, whereas for  $I_2(n, x, y)$  there is a problem due to the factor

$$\langle \mathbb{Q}_{T,n}^{-1/2}(d_x(x, \cdot)y), \mathbb{Q}_{T,n}^{-1/2}h \rangle_{H^{2n}}, \quad (\text{bad term})$$

that will converge as  $n \rightarrow \infty$  to

$$\langle \mathbb{Q}_T^{-1/2}(d_x(x, \cdot)y), \mathbb{Q}_T^{-1/2}h \rangle_X.$$

But this term is not meaningful because  $d_x(x, \cdot)y$  does not belong to the Cameron–Martin space of  $N_{\mathbb{Q}_T}$ .

So, we shall provide a different expression of  $I_2(n, x, y)$ , using a suitable integration by parts formula as in

*DP-Lunardi-Tubaro, Trans. AMS, 2018*

## Lemma

The following identity holds

$$\begin{aligned} I_2(n, x, y) &= \int_{\{M_n(h+d(x,\cdot)) \leq r\}} \\ &\times \varphi(h(T)) D_h \exp \left\{ -\frac{1}{2} F(x) + G^n(x, h) \right\} \cdot (d_x(x, \cdot) y) N_{\mathbb{Q}_T}(dh) \\ &\quad + \lim_{\epsilon \rightarrow 0} \frac{1}{2\epsilon} \int_{\{r-\epsilon \leq M_n(h+d(x,\cdot)) \leq r+\epsilon\}} \\ &\times \varphi(h(T)) M'_n(h + d(x, \cdot)) \cdot (d_x(x, \cdot) y) N_{\mathbb{Q}_T}(dh). \end{aligned} \tag{10}$$

In identity (10) the bad term disappeared.

The price to pay, however, is that we have to compute the limit  $\epsilon \rightarrow 0$  in identity (10) and then let  $n \rightarrow \infty$ .

This will require, as we shall see, that

$$\frac{dN_{\mathbb{Q}_T} \circ (M(h + d(x, \cdot)))^{-1}}{d\ell}(s) = D_r^+ \Lambda_x(s) =: \rho(x, s),$$

$$\frac{dN_{\mathbb{Q}_T} \circ (M_n(h + d(x, \cdot)))^{-1}}{d\ell}(s) = D_r^+ \Lambda_{x,n}(s) =: \rho_n(x, s)$$

where  $\ell$  is the Lebesgue measure,  $\rho(x, s)$  and  $\rho_n(x, s)$  are locally integrable and  $\rho_n \rightarrow \rho$ .

This will require the **Ehrhard inequality**.

# The Erhard Inequality

Let  $X$  be a separable Hilbert space,  $\mu$  a gaussian measure in  $X$ ,  $A \subset X$ ,  $B \subset X$  convex. Set

$$\Phi(r) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^r e^{-\frac{1}{2}x^2} dx, \quad r \in \mathbb{R}.$$

Then the following **concavity** inequality holds

$$\Phi^{-1}[\mu((1-t)A+tB)] \geq (1-t)\Phi^{-1}[\mu(A)] + t\Phi^{-1}[\mu(B)], \quad \forall t \in [0, 1].$$

As a consequence if  $g : X \rightarrow \mathbb{R}$  is convex and

$$F(r) := \mu(g \leq r) = \int_{g \leq r} d\mu,$$

it follows that  $\Phi^{-1} \circ F$  is concave, so that  $F$  is **absolutely continuous** and possesses right and left derivatives. See e.g.

*Bogachev, Gaussian measures Th. 4.2.2*

# Using the Ehrhard inequality

Define

$$\Lambda_x(s) := N_{\mathbb{Q}_T}(M(h + d(x, \cdot)) \leq s), \quad s \geq 0.$$

$$\Lambda_{n,x}(s) := N_{\mathbb{Q}_T}(M_n(h + d(x, \cdot)) \leq s), \quad s \geq 0.$$

Since  $g$  is convex, mappings  $M(\cdot + d(x, \cdot))$  and  $M_n(\cdot + d(x, \cdot))$  are convex as well. So, by the **Ehrhard** inequality we see that the real functions

$$[0, +\infty) \rightarrow \mathbb{R}, \quad s \rightarrow S_x(s) = \Phi^{-1}(\Lambda_x(s)),$$

$$[0, +\infty) \rightarrow \mathbb{R}, \quad s \rightarrow S_{n,x}(s) = \Phi^{-1}(\Lambda_{n,x}(s)),$$

are concave. As a consequence, they are differentiable at any  $s > 0$  up to a discrete set where there exist the left and the right derivative; we shall denote by  $D_r^+ \Lambda_x(s)$  and  $D_r^+ \Lambda_{n,x}(s)$  the right derivatives at any discontinuity point.

It follows that the measures

$$N_{\mathbb{Q}_T} \circ (M(h + d(x, \cdot)))^{-1}$$

and

$$N_{\mathbb{Q}_T} \circ (M_n(h + d(x, \cdot)))^{-1}$$

are absolutely continuous with respect to the Lebesgue measure  $\ell$  in  $\mathbb{R}$  and it results

$$\frac{dN_{\mathbb{Q}_T} \circ (M(h + d(x, \cdot)))^{-1}}{d\ell}(s) = D_r^+ \Lambda_x(s) =: \rho(x, s)$$

$\ell$  in  $\mathbb{R}$  and

$$\frac{dN_{\mathbb{Q}_T} \circ (M_n(h + d(x, \cdot)))^{-1}}{d\ell}(s) = D_r^+ \Lambda_{x,n}(s) =: \rho_n(x, s)$$



Now the following lemma can be proved using the fact that  $\Lambda_x(s)$  and  $\Lambda_{n,x}(s)$  are increasing on  $s$  and decreasing on  $n$  and the selection principle of **Helly**.

### Lemma

*There exists  $a > 0$  such that*

$$\lim_{n \rightarrow \infty} \rho_n(x, s) = \rho(x, s) \quad \forall x \in \overline{\mathcal{O}_r}, \quad s \in [r - a, r + a].$$

Now, we can prove the existence of the limit

$$M_{2,2}(n, x, y) = \lim_{\epsilon \rightarrow 0} \frac{1}{2\epsilon} \int_{\{r-\epsilon \leq M_n(h+d(x, \cdot)) \leq r+\epsilon\}} \\ \times \varphi(h(T)) M'_n(h + d(x, \cdot)) \cdot (d_x(x, \cdot) y) N_{\mathbb{Q}_T}(dh),$$

that we write as

$$M_{2,2}(n, x, y) = \lim_{\epsilon \rightarrow 0} \frac{1}{2\epsilon} \int_X \mathbb{E}_{N_{\mathbb{Q}_T}} [\mathbb{1}_{\{r-\epsilon \leq M_n(h+d(x, \cdot)) \leq r+\epsilon\}} \\ \times \varphi(h(T)) M'_n(h + d(x, \cdot)) \cdot (d_x(x, \cdot) y) | M_n(h + d(x, \cdot))] N_{\mathbb{Q}_T}(dh),$$

that is

$$M_{2,2}(n, x, y) = \lim_{\epsilon \rightarrow 0} \frac{1}{2\epsilon} \int_{r-\epsilon}^{r+\epsilon} \mathbb{E}_{N_{\mathbb{Q}_T}} [\varphi(h(T)) M'_n(h + d(x, \cdot)) \cdot (d_x(x, \cdot) y) \\ | M_n(h + d(x, \cdot)) = s] \rho_{n,x}(s) ds.$$

It results








$$\begin{aligned} M_{2,2}(n, x, y) &= \mathbb{E}_{N_{\mathbb{Q}_T}}[\varphi(h(T)) (M'_n(h + d(x, \cdot)) \cdot (d_x(x, \cdot) y)) \\ &\quad \times \mathbb{E}[|M_n(h + d(x, \cdot)) = r] \rho_{n,x}(r)]. \end{aligned}$$

Finally, letting  $n \rightarrow \infty$  we obtain the main result.

For all  $\varphi \in B_b(\overline{\mathcal{O}}_r)$  there exists the gradient of  $R_T^{\mathcal{O}_r} \varphi$  in all direction  $y \in \mathbb{R}^d$  and it results

$$\begin{aligned} D_x R_T^{\mathcal{O}_r} \varphi(x) \cdot y &= \int_{\{M(h+d(x,\cdot)) \leq r\}} \varphi(h(T)) \exp \left\{ -\frac{1}{2} F(x) + G(x, h) \right\} \\ &\quad \times \left( -\frac{1}{2} F_x(x)y + G_x(x, h)y \right) N_{\mathbb{Q}_T}(dh) \\ &+ \mathbb{E} \left[ \varphi(h(T)) (M'(h + d(x, \cdot)) \cdot (d_x(x, \cdot)y) M(h + d(x, \cdot)) = r \right] \rho_x(r). \end{aligned}$$

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