

MAPPING CLASS GROUPOIDS & MOTION GROUPOIDS

TALK 1

Fiona Torzewska

University of Leeds

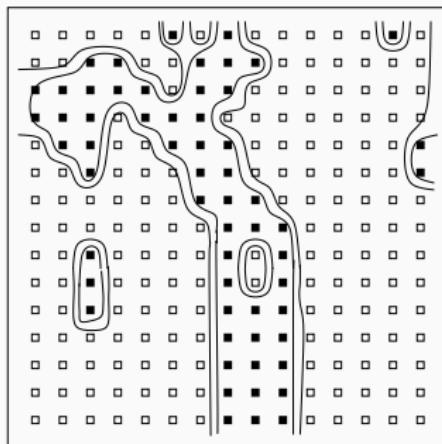
MOTIVATION

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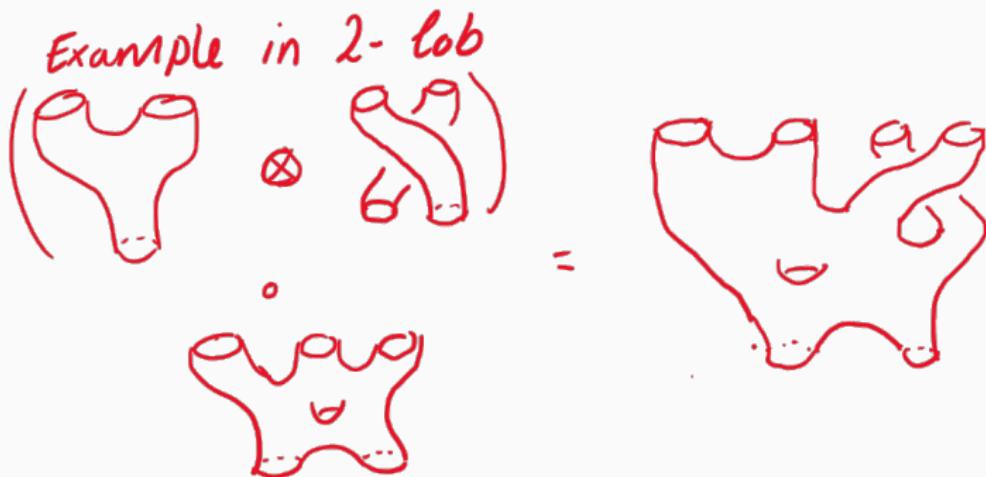
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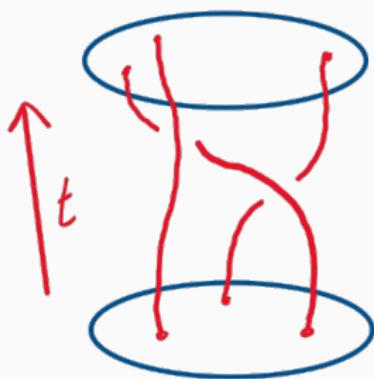
ALSO: Lots of really nice maths, invariants of closed manifolds...

PLAN OF TALKS

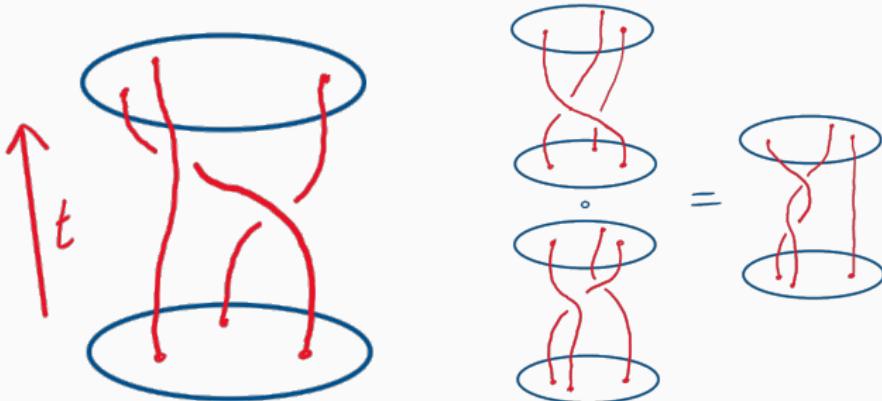
1. Preliminaries
2. Braid group(oid)s as fundamental groupoids of configuration spaces
3. Motion groupoids
4. Mapping class groupoids
5. Relationship between the two
6. Motion groupoids and categories of (embedded) cobordisms

BRAID GROUPOIDS - THE IDEA

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PRELIMINARIES

PRELIMINARIES - COMPACT OPEN TOPOLOGY

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Example

- If X is the one point space, then maps can be labelled by elements of Y and the compact open topology is the same as the topology on Y .
- Similarly if X is the n point space with the discrete topology, the compact open topology on maps X to Y is the same as the topology on $Y \times \dots \times Y$, the product of Y with itself n times.

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$$\cap_i B(K_i, U_i)$$

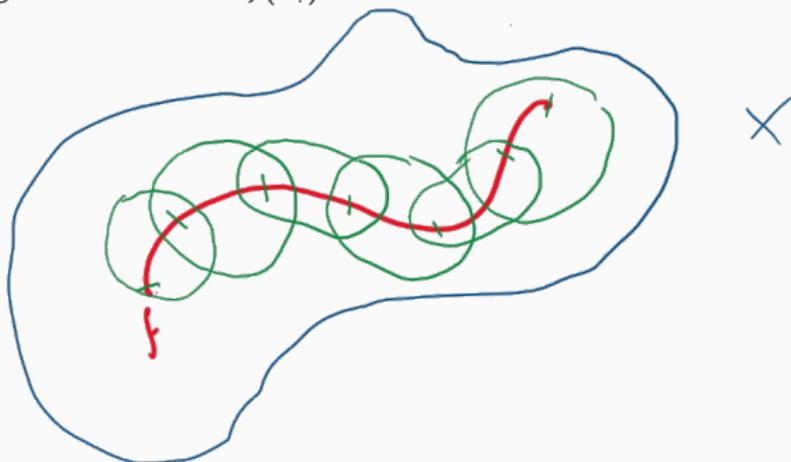
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(Coming from the adjunction of $\mathbf{TOP}(Y, -)$ and $- \times Y$.)

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We use $\gamma: x \rightarrow x'$ for a path $\gamma: I \rightarrow X$ with $\gamma(0) = x$ and $\gamma(1) = x'$.

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$$h: I \times I \rightarrow X$$

such that $h(t, 0) = \gamma(t) \forall t \in I$, $h(t, 1) = \gamma'(t) \forall t \in I$ and $h|_{I \times \{s\}}$ is a path x to $x' \forall s \in I$.

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- Using the lemma, this is the same as a continuous map

$$\tilde{h}: I \rightarrow PX$$

such that $\tilde{h}(0) = \gamma$, $\tilde{h}(1) = \gamma'$ and $\tilde{h}(t)$ is a path x to $x' \forall t \in I$ i.e. a path in the space of paths.

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We have that $\pi(X, *)$ is the fundamental group based at $* \in X$.

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Let the **ordered configuration space** of n points in the disk be the set

$$OC_n = \{(x_1, \dots, x_n) \mid x_i \in \text{int}(D), x_i \neq x_j \forall i \neq j\}$$

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The **unordered configuration space** of n points in the disk is the quotient space

$$UC_n = OC_n / S_n.$$

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with fibre $int(D) \setminus *$. And hence a short exact sequence

$$\pi_2(int(D)) \rightarrow \pi_1(int(D) \setminus *) \rightarrow \pi_1(OC_2) \rightarrow \pi_1(int(D))$$

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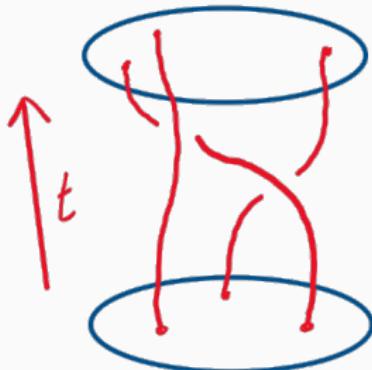
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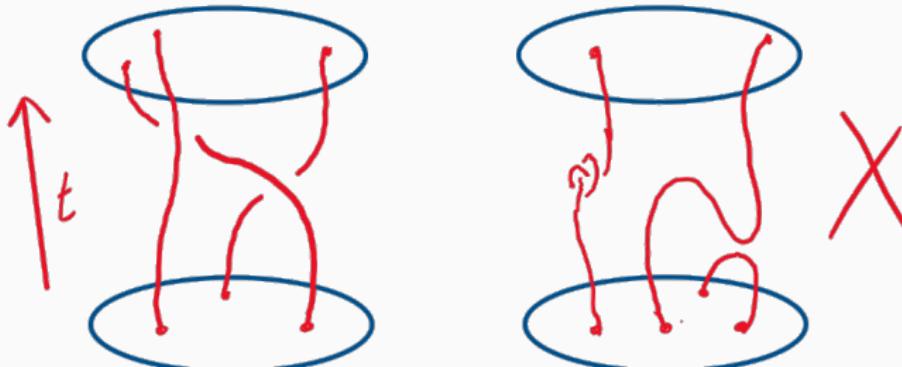
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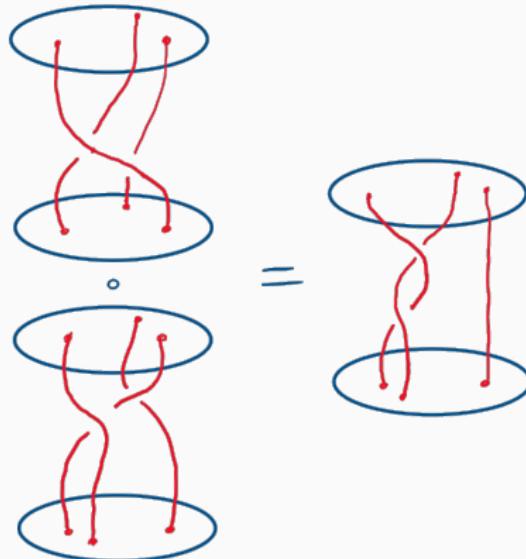
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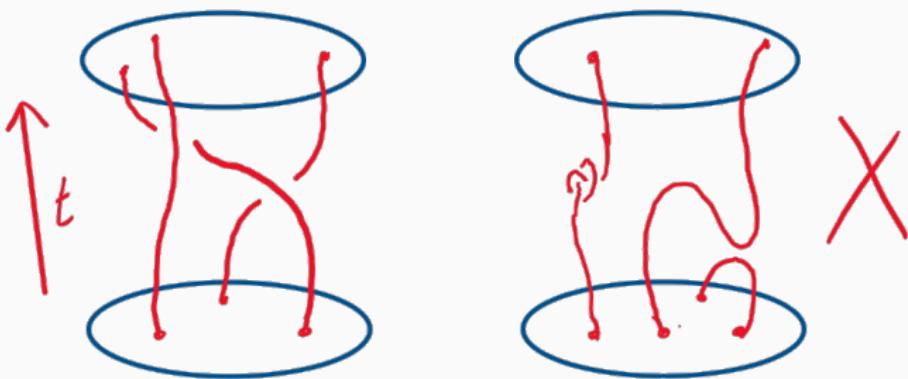
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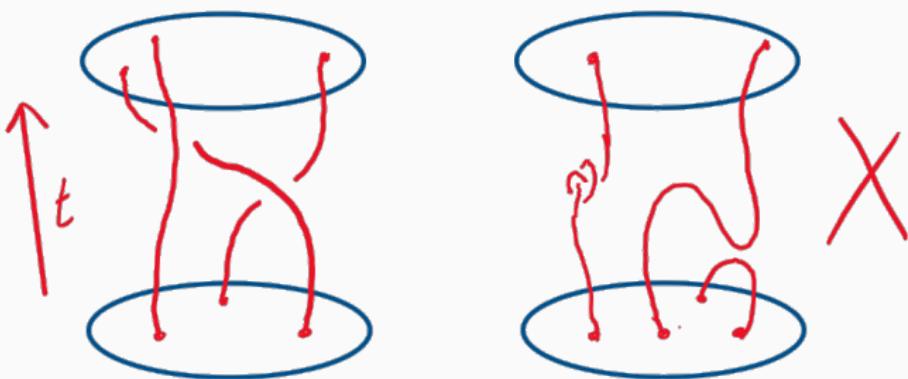


BRAID GROUPOIDS - A QUESTION

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Question

Can we construct a category which does contain things like the picture on the right? Is there a well defined/ faithful functor from \mathcal{B}_n ?

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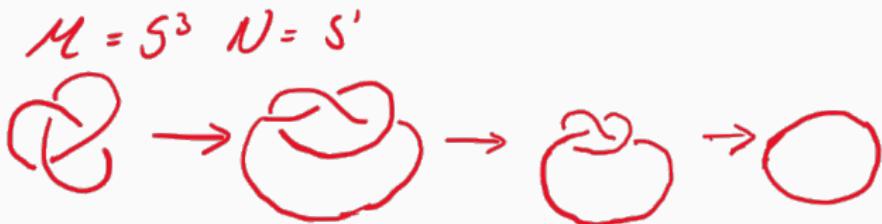
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For N the n point space with discrete topology,

$$E(N, M) = OC_n$$

GENERALISING BRAIDS TO EMBEDDINGS

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And we cannot extend to neighbourhood of N .



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$$Homeo_M(N, N') = \left\{ f: M \rightarrow M \text{ homeos} \mid \begin{array}{l} f \text{ preserves orientation on } M \\ f \text{ fixes the boundary of } M \text{ pointwise} \\ f(N) = N' \end{array} \right\}$$

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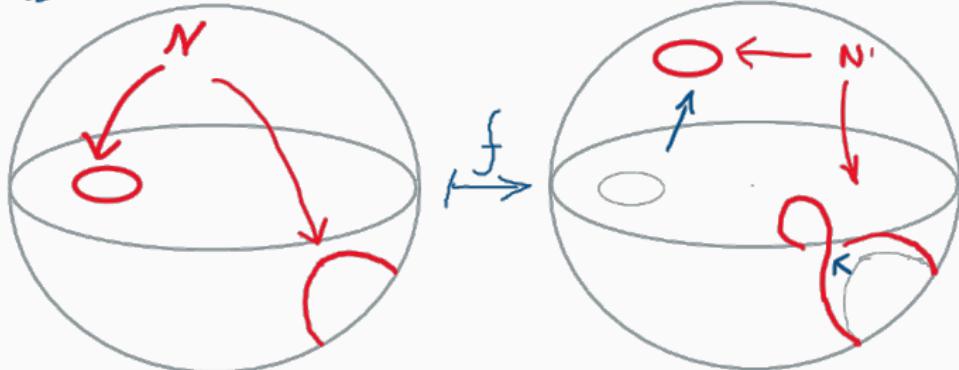
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Ex $M = B^3$



TOPOLOGICAL GROUPS

Lemma

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This means the function mapping elements to their inverses and the group operation are continuous.

GROUPIDS OF SELF HOMEOMORPHISMS

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Proposition

Let M be a compact, connected, orientable manifold. There is a groupoid denoted Homeo_M such that

- objects are subsets of M ,
- and morphisms between subspaces are elements of $\text{Homeo}_M(N, N')$.

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Proof

Identity and inverse are obvious homeomorphisms. Composition of homeomorphisms is associative.

Closure: $g \circ f(N) = g(N') = N''$ and $g \circ f(\partial M) = g(\partial M) = \partial M$

MOTION GROUPOIDS

MOTION GROUPOIDS - MOTIONS

Definition

A motion from N to N' denoted $f: N \rightarrow N'$ is a path $f: I \rightarrow \text{Homeo}_M(\emptyset, \emptyset)$ with $f_0 = id_M$ and $f_1 \in \text{Homeo}_M(N, N')$.

Definition

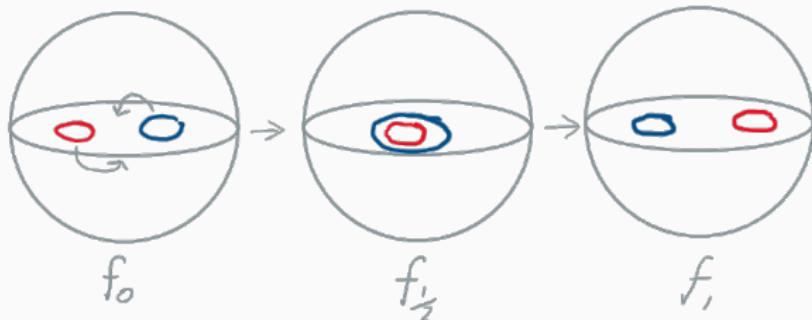
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Using lemma $\text{Top}(X, \text{TOP}(Y, Z)) \rightarrow \text{Top}(X \times Y, Z)$

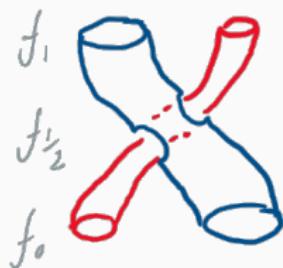
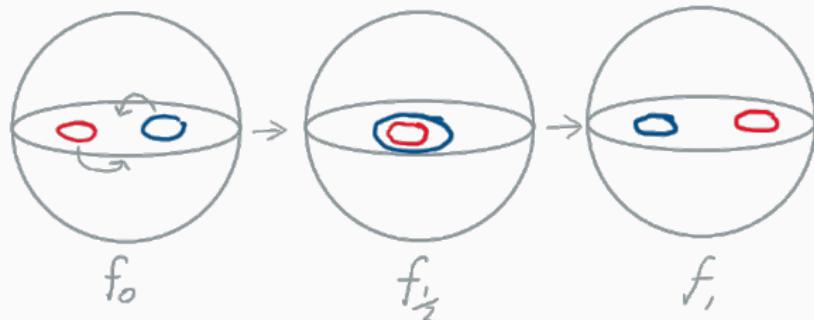
$$\{I \rightarrow \text{Homeo}_M(\emptyset, \emptyset)\} \leftrightarrow \{M \times I \rightarrow M\} \leftrightarrow \{M \times I \rightarrow M \times I\}$$

MOTION GROUPOIDS - MOTIONS

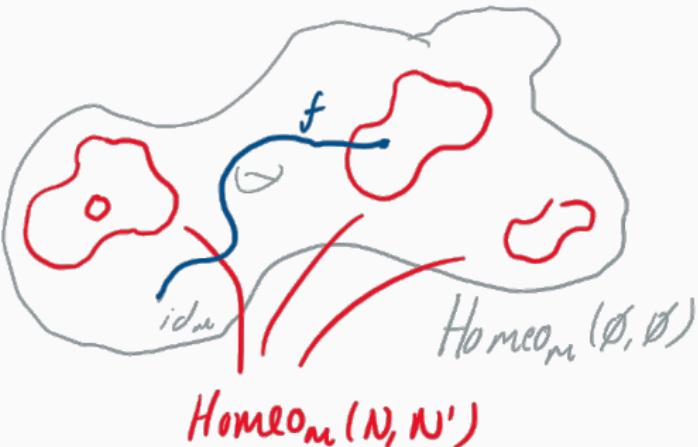
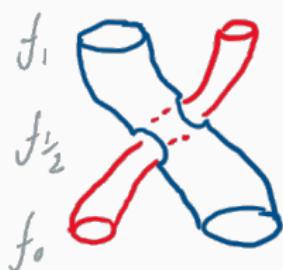
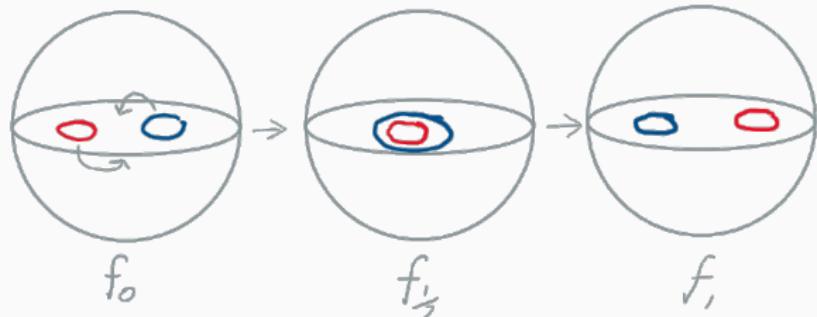
MOTION GROUPOIDS - MOTIONS



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MOTION GROUPOIDS - MOTIONS



MOTION GROUPOIDS - DEFINITIONS

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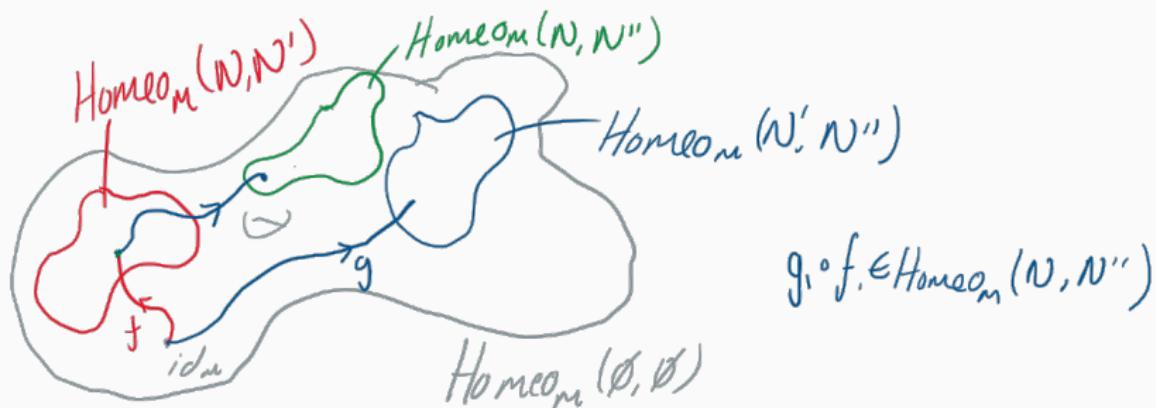
We can define composition of motions $f: N \rightarrow N'$ and $g: N' \rightarrow N''$

$$g * f = \begin{cases} f_{2t} & 0 \leq t \leq 1/2 \\ g_{2(t-1/2)} \circ f_1 & 1/2 \leq t \leq 1 \end{cases}$$

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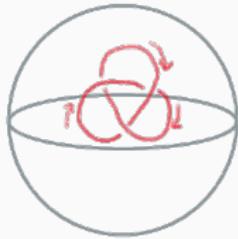
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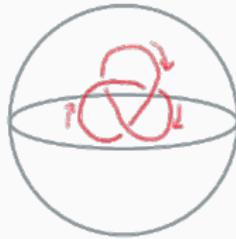


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As a picture in $M \times I$ of a stationary motion looks like N remains fixed in M at all t .

MOTION GROUPOIDS - DEFINITIONS

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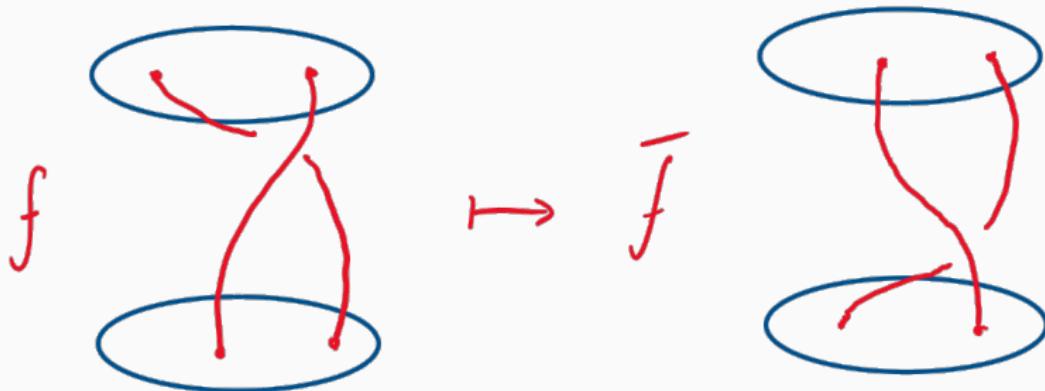
Define motion corresponding to each $f: N \rightarrow N'$

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This means a continuous map

$$H: (M \times I) \times I \rightarrow M \times I$$

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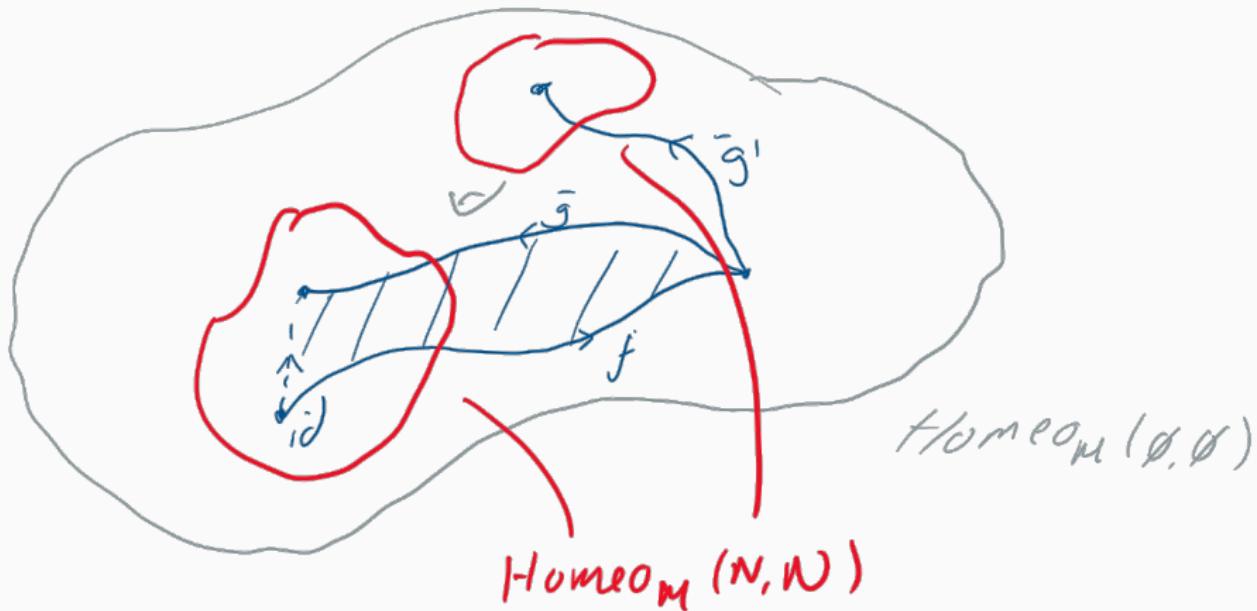
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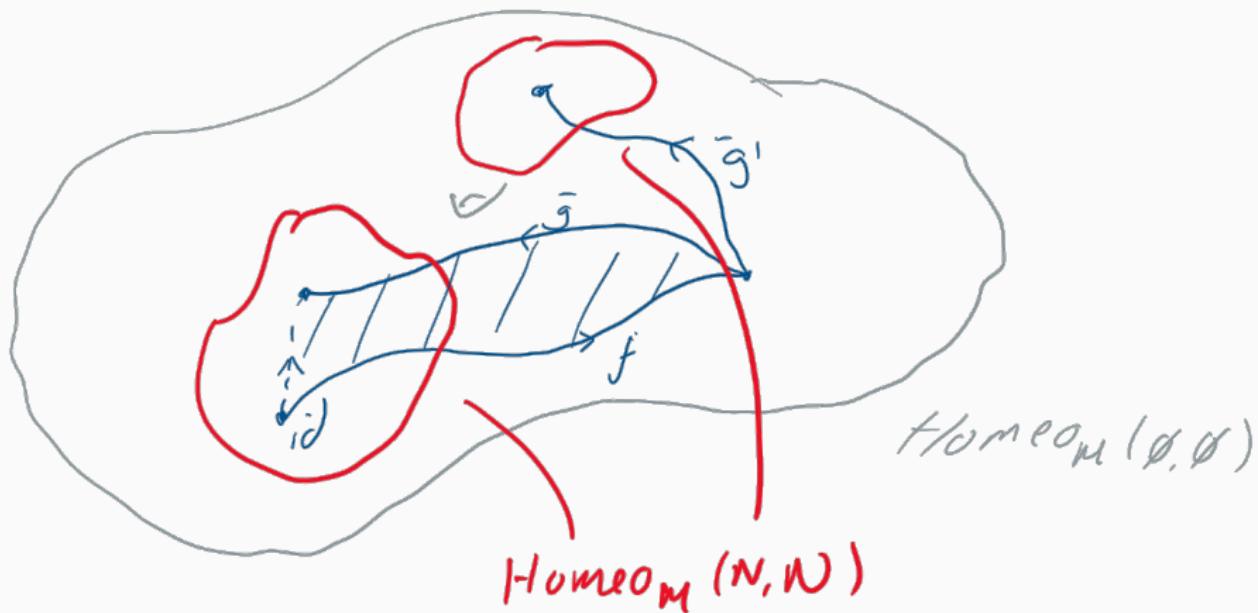
- $\gamma(0) = \bar{g} * f$
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MOTION GROUPOIDS - EQUIVALENCE

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(Notice this implies stationary motions are equivalent to the trivial motion $f_t = i_M$ for all t .)

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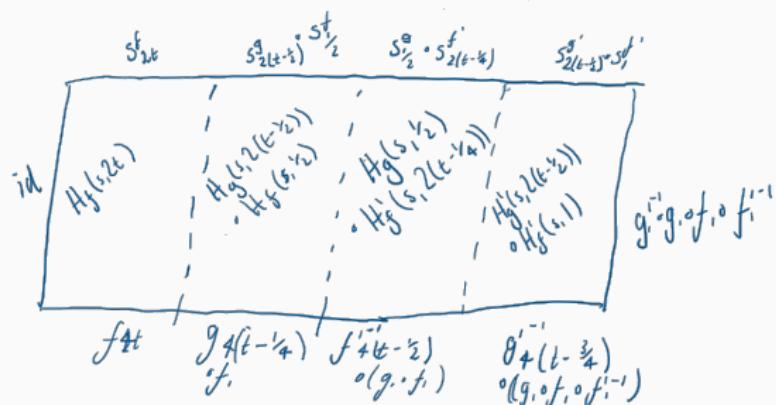
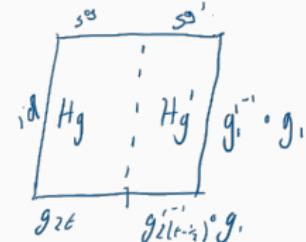
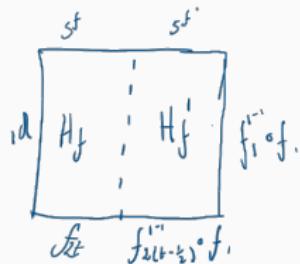
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The motion \bar{f} is an inverse for each f .

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The full subcategory of the motion groupoid Mot_D taking subsets of points in the interior as objects is isomorphic to the braid groupoid.

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Have map

$$Mot_D(x, x) \rightarrow \mathcal{B}_n(x, x).$$

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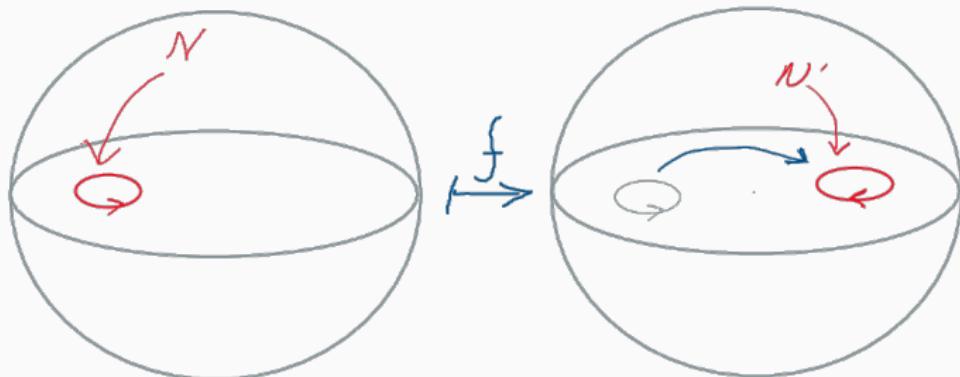
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$\exists M = B^3$, N, N' one component trivial links



ORIENTED GROUPOIDS OF SELF HOMEOMORPHISMS

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Propostion

Let M be a compact, connected, orientable manifold. There is a groupoid denoted resp. $\text{Homeo}_M^{\text{or}}$ such that

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Lemma

There is a faithful functor $\text{Homeo}_M^{\text{or}} \rightarrow \text{Homeo}_M$ given by forgetting the orientation on manifolds N and N' .

ORIENTED MOTION GROUPOID

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PURE SELF HOMEOMORPHISMS

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Now let $N = N'$.

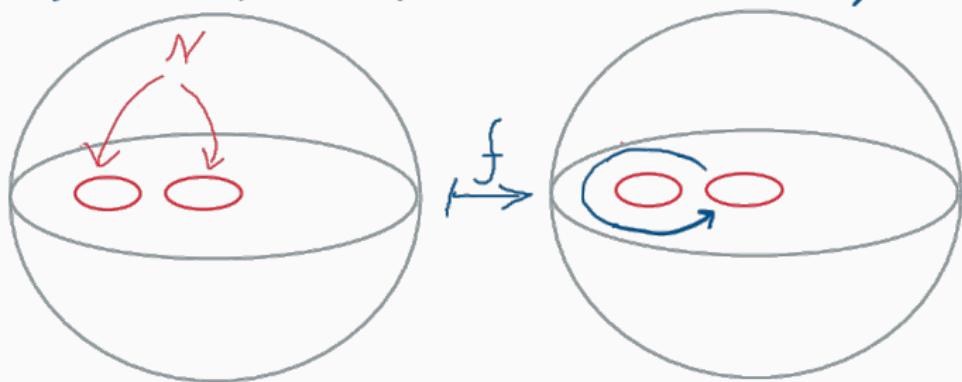
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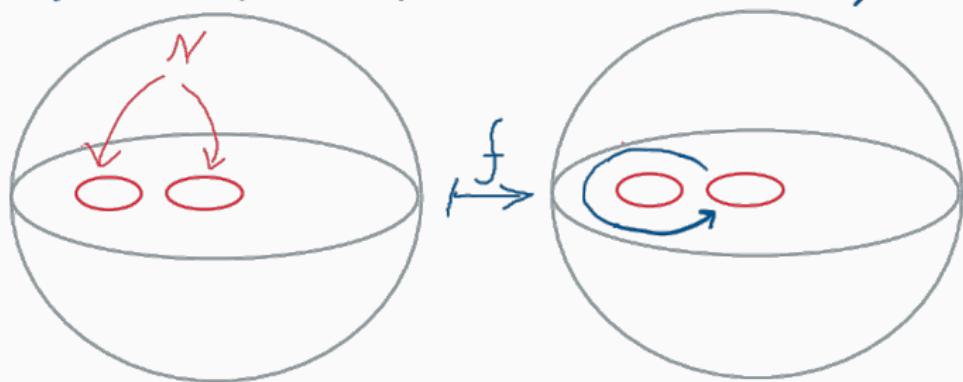
$\exists M = B^3$, trivial link with 2 connected components



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Now let $N = N'$. $\text{PHomeo}_M(N, N) \subset \text{Homeo}_M(N, N)$ such that homeomorphisms fix connected components of N .

Ex: $M = B^3$, N trivial link with 2 connected comp



Define in the same way $\text{PHomeo}_M^{or}(N, N) \subset \text{Homeo}_M^{or}(N, N)$.

REFERENCES

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- Braid groups as configuration spaces: Fox, Ralph, and Lee Neuwirth. "The braid groups." *Mathematica Scandinavica* 10 (1962): 119-126.