

Evolutionary Dynamics, Equilibrium Selection and Network Structure

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(joint work with A. Montanari)

Outline

- Motivating question: diffusion of behavior or technology in a social network
- Ising model, Glauber dynamics, and meta stability
- Interpretation of the results in the context of social networks

Models for the spread of behavior or technology

- Epidemic or cascade models (contact process e.g. Liggett, Kleinberg)
- Dynamics of a game
(individual strategy and social structure)

Coordination games

- Players: nodes in graph $G(V,E)$
- Action space

$$\underline{x} = \{x_i : i \in V\}, x_i \in \{+1, -1\}$$

- Payoff matrix
 - $A > D$ and $B > C$

	+	-
+	A	C
-	D	B

Example

- Choosing a cell phone provider

+ : AT&T

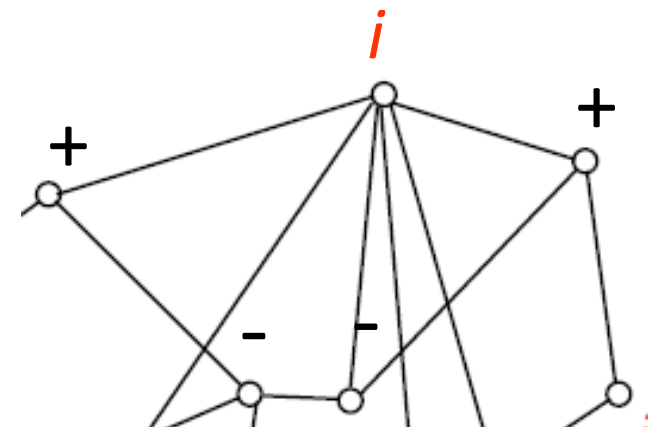
- : Verizon

- Payoff of i in the network

$$+ : 6N_+ (i) + 2N_i (i)$$

$$i : 2N_+ (i) + 5N_i (i)$$

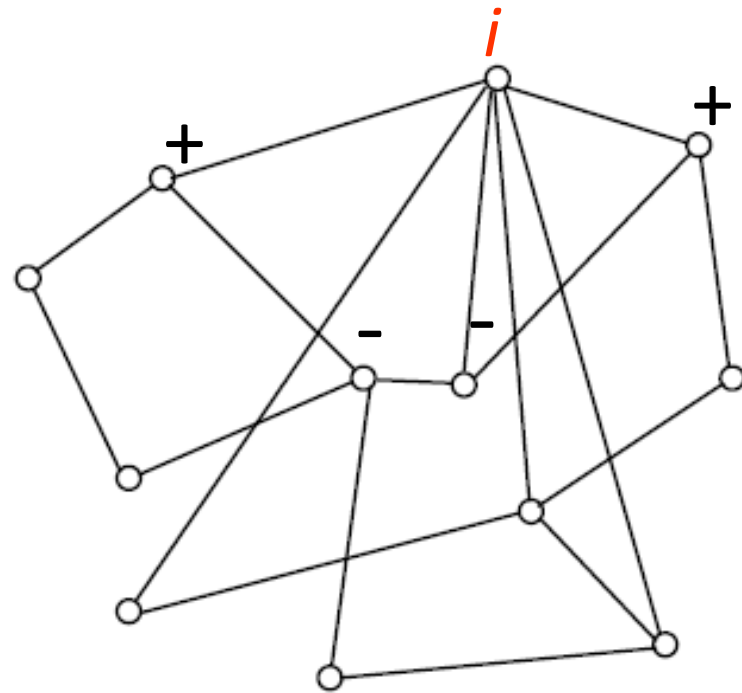
	+	-
+	6	2
-	2	5



Best response dynamics

- For every i there is an h_i such that best response is

$$\text{sign}\left(h_i + \sum_{j \in \partial i} x_j(t)\right)$$



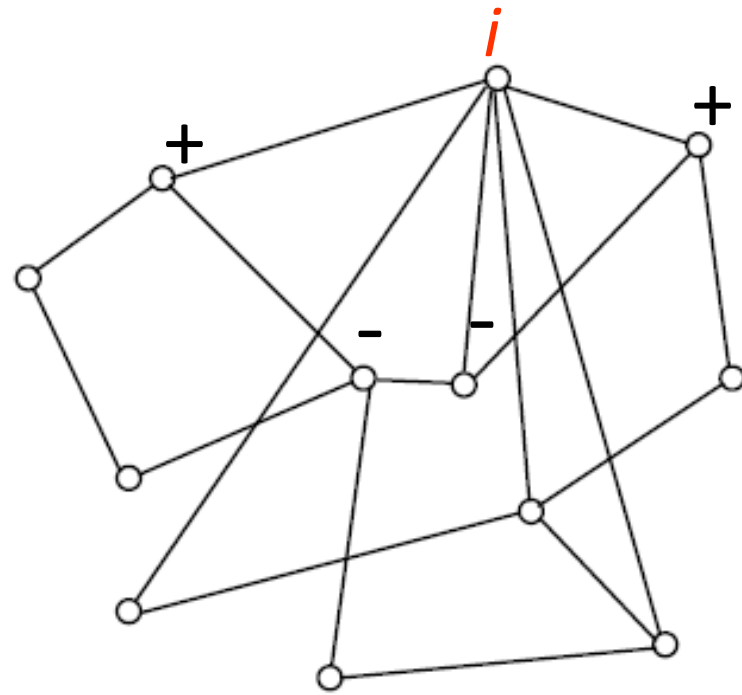
Best response dynamics

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$$\text{sign}\left(h_i + \sum_{j \in \partial i} x_j(t)\right)$$

↑

$$h_i = \frac{a - d - b + c}{a - d + b - c} |\partial i|$$

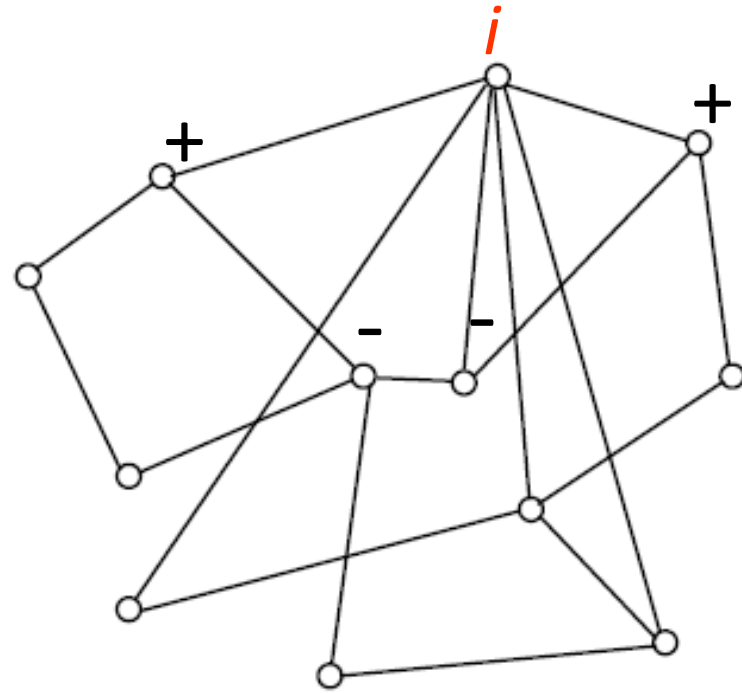


Best response dynamics

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wlog assume $h_i > 0$

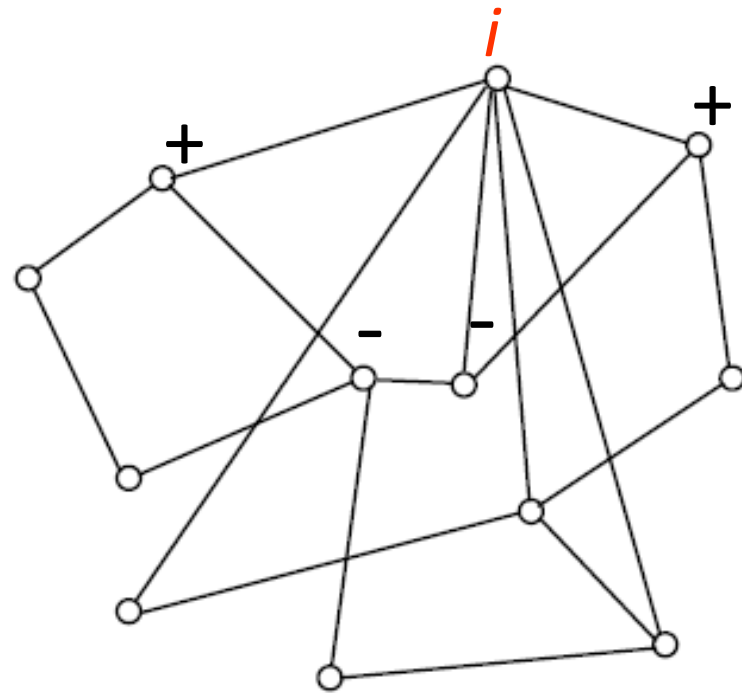


Best response dynamics

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- Best response dynamics increases the potential function

$$H(\underline{x}) = \sum_{(i,j) \in E} x_i x_j + \sum_{i \in V} h_i x_i$$

Example

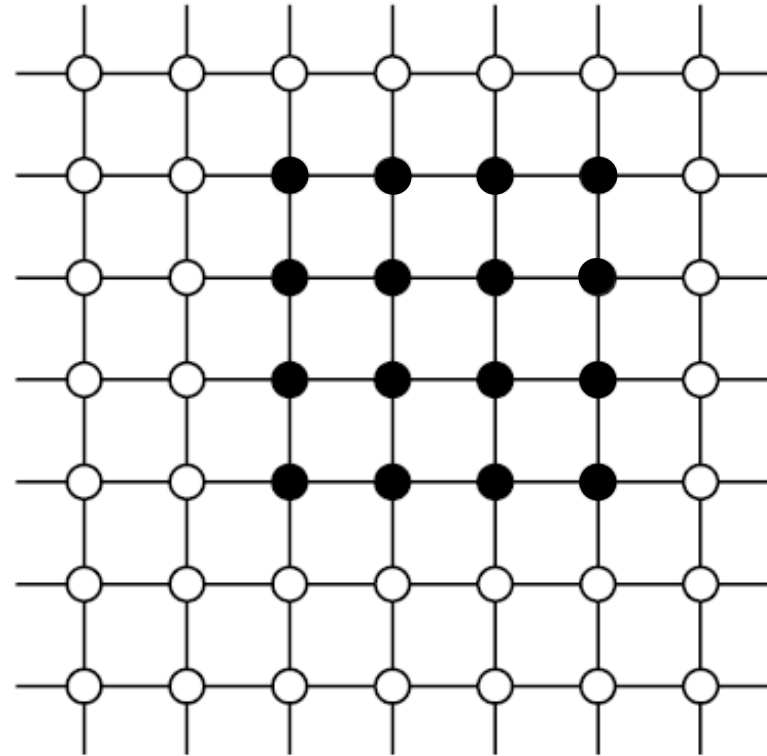
Suppose $h_i = 0.1$ for all i

Best response dynamics: stays at this equilibrium

Allow for some noise:

the + area expands to the whole graph

Kandori, Mailath, Rob 93
also physics (nucleation)



The effect of graph structure

- $\tau_+(G)$: time to hit all +

- Ellison (1993) : if the probability of mistake is ϵ

If $G = (\text{LINE})^k$, then $\tau_+(G) = \epsilon^{-\Theta(1)}$.
If $G = K_n$, then $\tau_+(G) = \epsilon^{-\Theta(n)}$.

Small no of neighbors



Global interaction



Our goal

- Find the graph theoretic property that captures the rate of convergence
- Demonstrate on specific graph sequences
 - Expanders
 - Finite range graphs
 - Small-worlds

The dynamics (definition)

Asynchronous: strategy revision at arrival of a Poisson clock

$$\Pr(x_i = y | \partial i) = \exp \left\{ \beta y \left(h_i + \sum_{j \in \partial i} x_j(t) \right) \right\}$$

← Glauber dynamics for the Ising model

Reversible: with the stationary distribution

$$\mu(\underline{x}) \propto \exp \left\{ \beta H(\underline{x}) \right\} = \exp \left\{ \beta \sum_{(i,j) \in E} x_i x_j + \beta \sum_{i \in V} h_i x_i \right\}$$

The measure concentrates around +1 as $\beta \rightarrow 1$

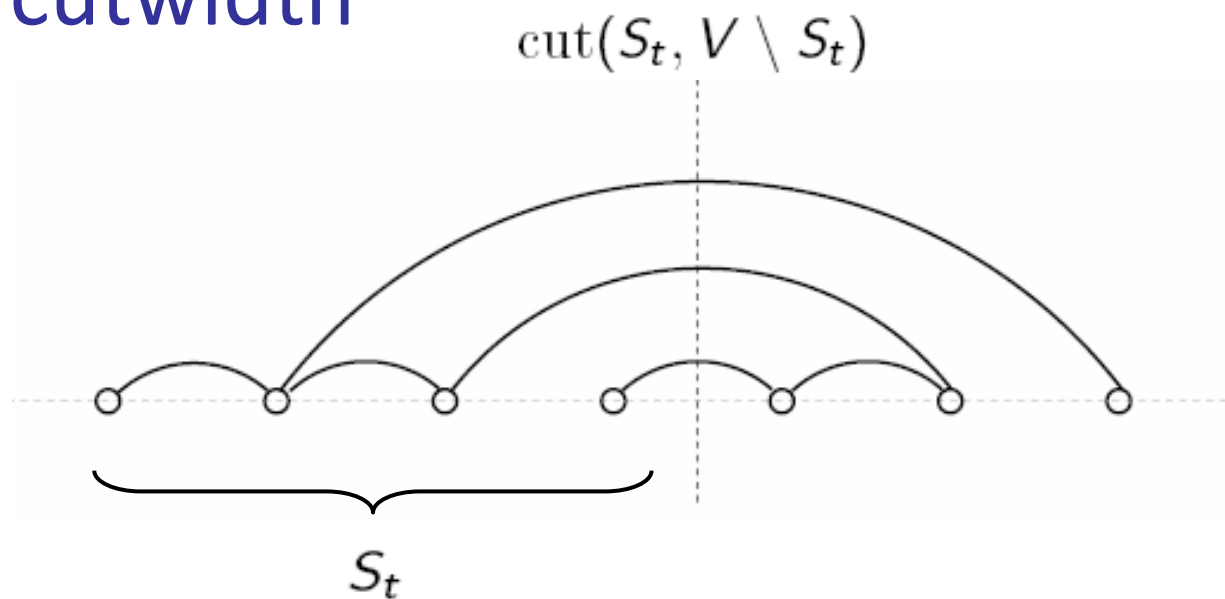
The question

Meta-stability: typical hitting time of + from the worst starting point

$$\tau_+(G) \equiv \sup_{\underline{x}} \inf \{ t \geq 0 : \mathbb{P}_{\underline{x}}^{\times} \{ T_+ \geq t \} \leq e^{-1} \}$$

Studied in mathematical physics for 2,3D grids
(c.f. Neves & Schonman 92, Bovier & Manzo 02)

Tilted cutwidth



$$\Gamma(G; \underline{h}) \equiv \min_{S: \emptyset \rightarrow V} \max_{t \leq n} [\text{cut}(S_t, V \setminus S_t) - |S_t|_h]$$

$$|S|_h \equiv \sum_{i \in S} h_i$$


Note that cutwidth is simply $\Gamma(G; 0)$

Proposition: for large enough $\bar{\tau}$

$$\tau_+(G) = \exp\{\beta\Gamma_*(G; \underline{h}) + o(\beta)\},$$

where

$$\Gamma_*(G; \underline{h}) = \max_{F \subseteq G} \Gamma(F; \underline{h}^F)$$


$$h_i^F = h_i + |\partial i|_{G \setminus F}.$$

Remark 1: $\underline{h} = 0$, Kenyon-Mossel-Peres 01

$$\tau_{\text{mix}}(G) \leq \exp\{2\beta\Gamma(G; 0)\}.$$

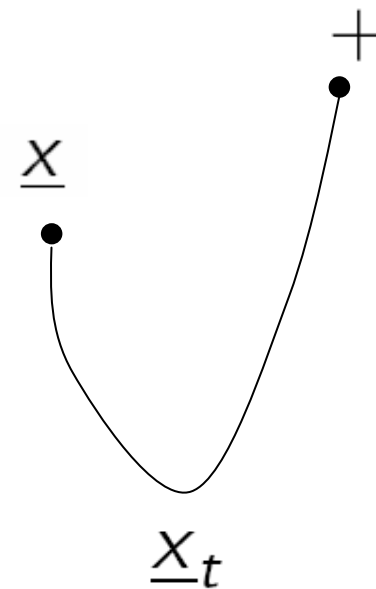
Remark 2: at $\bar{\tau} = 1$ recovers Morris 00

$$\max_{F \subseteq G} \Gamma(F; \underline{h}^F) = 0$$

Proof idea

Hitting time is related to the size of barrier: Variation of Markov chain comparison (Diaconis-Saloff coste, Jerrum-Sinclair)

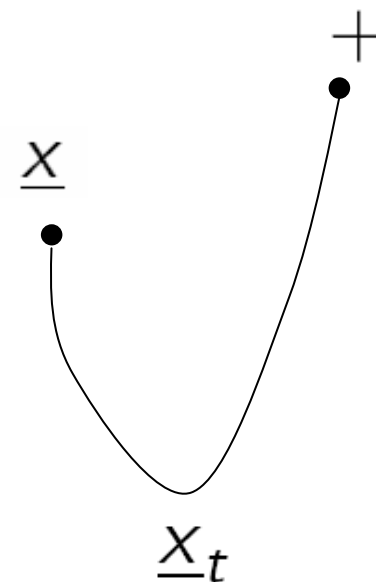
$$\Gamma_*(G; \underline{h}) \simeq \max_{\underline{x}} \min_{\text{path}} \max_t H(\underline{x}) - H(\underline{x}_t)$$



Proof idea

Lemma: There is a path with minimum barrier that is **monotone** (flips only – to +)

$$\min_{\text{monotone path}} \max_t H(\underline{x}) - H(\underline{x}_t)$$

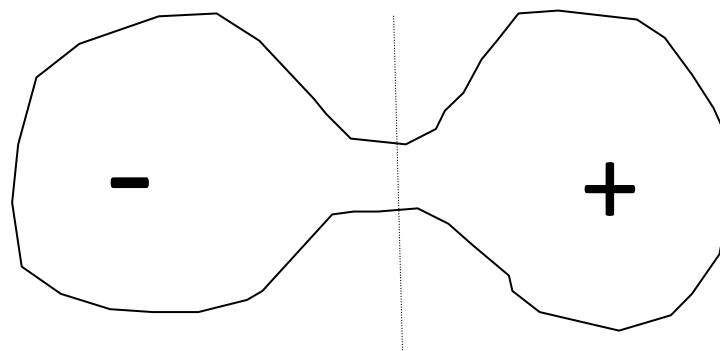


Tilted cutwidth is the ordering defined by minimum path defined by \underline{x}

Also a dual notion

Worst Bottleneck: gives a lower bound

$$\Delta(G; \underline{h}) \equiv \max_{\Omega} \min_{(S_1, S_2) \in \partial\Omega} \max_{i=1,2} [\text{cut}(S_i, V \setminus S_i) - |S_i|_h]$$



Tilted cut is equal to the tilted cutwidth in the worst subgraph!

Our goal

- Find the graph theoretic property that captures convergence
- Demonstrate on specific graph sequences
 - Expanders
 - Finite range graphs
 - Small-worlds

Expanders

G is (λ, δ) -**expander** if and only if

$$\forall S \subset V, |S| \leq \delta n, \text{ cut}(S, V \setminus S) \geq \lambda|S|$$

If G is a (λ, δ) -**expander** then $\Gamma_*(G; \underline{h}) \geq (\lambda - h_{\max})\delta n$.

Proof:

$$\begin{aligned} \Gamma_*(G; \underline{h}) \geq \Delta(G, \underline{h}) &\geq \min_{|S|=t} [\text{cut}(S, V \setminus S) - |S|h] \\ &\geq \min_{|S|=t} [\lambda|S| - h_{\max}|S|] \end{aligned}$$

Expanders

G is (λ, δ) -**expander** if and only if

$$\forall S \subset V, |S| \leq \delta n, \text{cut}(S, V \setminus S) \geq \lambda |S|$$

If G is a (λ, δ) -**expander** then $\Gamma_*(G; \underline{h}) \geq (\lambda - h_{\max})\delta n$.

Corollary: Convergence time is exponential for random regular and power-law graphs!
(different from Ellison's prediction)

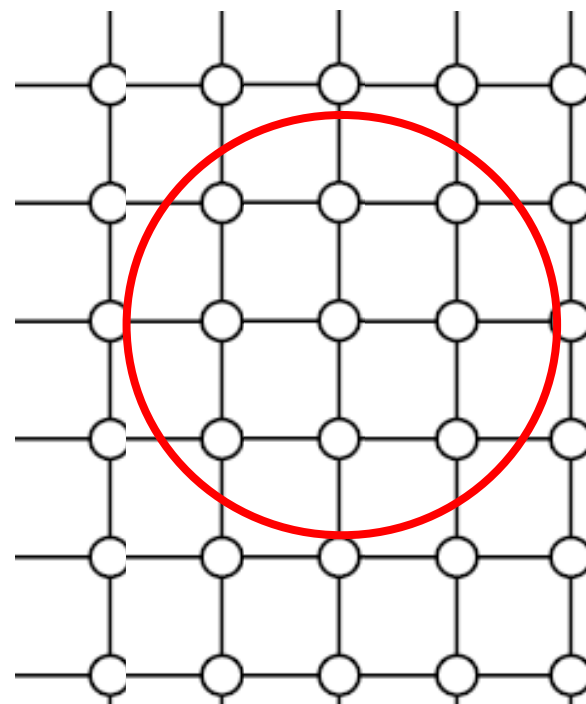
Convergence and Isoperimetric function

If for some $\alpha < 1$, and $\forall V \subseteq V(G)$

$$\exists S \subset V, \text{cut}(S, V \setminus S) \leq |S|^\alpha$$

Then

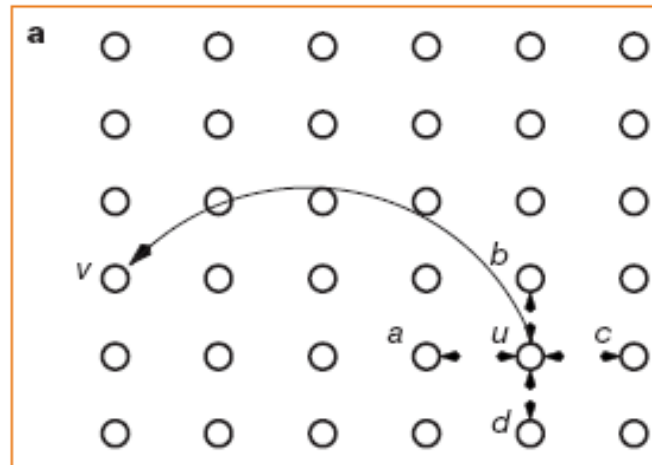
$$\Gamma_*(G; \underline{h}) = O(1)$$



Corollary: Convergence time is fast for all low-dimensional graphs (e.g. k-dimensional grids)

Small-world networks

- Watts-Strogatz, Kleinberg 95

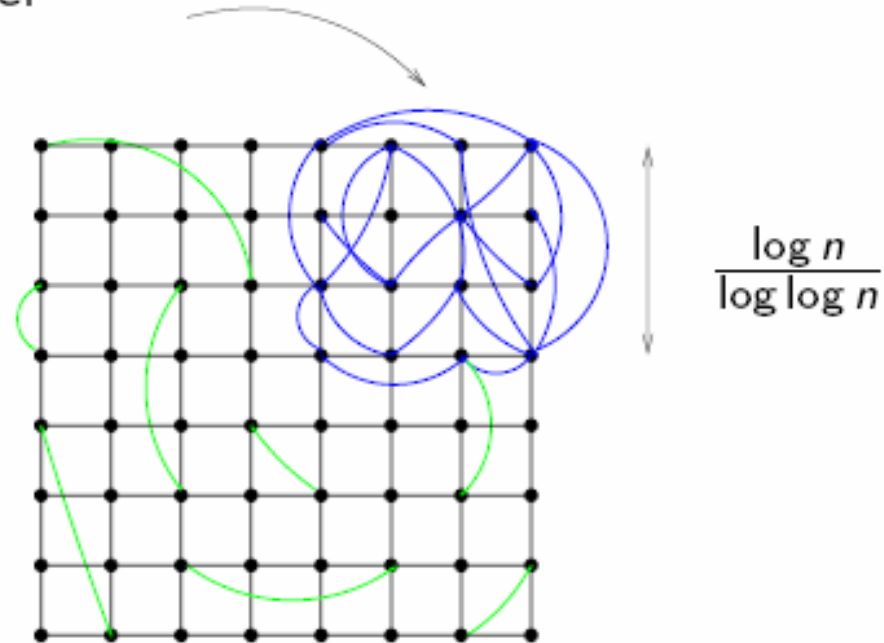


$$P(u, v) \propto \frac{1}{d(u, v)^r}$$

Small-world networks

If G is small world with $r \geq d$, then $\Gamma_*(G; \underline{h}) = \Omega\left(\frac{\log n}{\log \log n}\right)$.

expander



Small world graphs with $r < d$ have constant expansion!

Summary

Consider asynchronous reversible dynamics.

If G is:

d -dimensional finite-range, then $\tau_+(G) = e^{\beta\Theta(d)}$.

has constant expansion, then $\tau_+(G) = e^{\beta\Omega(n)}$.

small world with $r > d$, then $\tau_+(G) = e^{\beta\Omega(\log n / \log \log n)}$.

small world with $r \leq d$, then $\tau_+(G) = e^{\beta\Omega(n)}$.

Comparison with epidemic models

Epidemic models: the behavior spreads from an infected node to a healthy neighbor independently
e.g. the contact process

In contrast with the dynamics of coordination games

High degree nodes and well-connected subgraphs help the spread of behavior in contagion dynamics
(e.g. Berger, Borgs, Chayes, S. 04)

Which model is more realistic?

Case study:

- MusicLab (Salagnik-Watts)
 - 14k participants
 - 8 independent worlds
- Communities in live journal:
 - 1 million users
 - 2200 communities
- “happiness” in blogsphere:
 - Crawling blogger, myspace etc..
 - 15,000 new feelings per day!



Joint work with S. Ceyhan and S. Kamvar

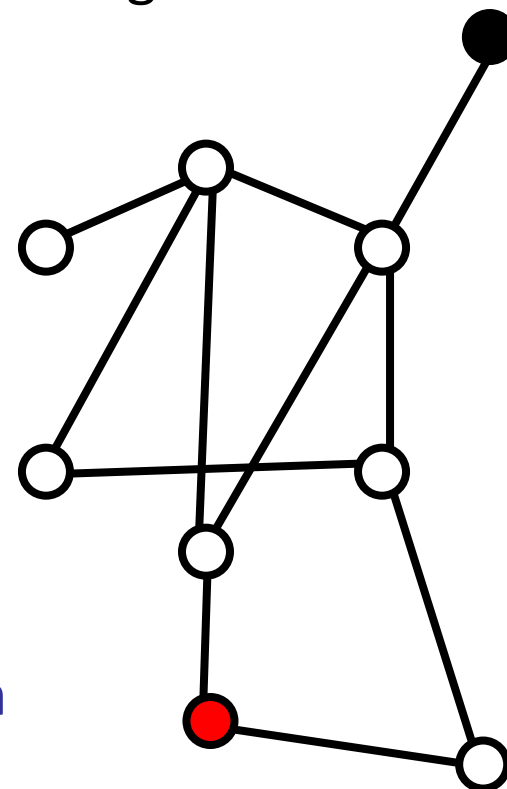
Dynamics with heterogeneous users

- Zealots: a small set of individual who don't change their behavior

Typical behavior?

- Oscillation between the alternatives
- Well-defined territories

Centrality of zealots, connectivity of the graph



work in progress with D. Acemoglu and A. Ozdaglar

Summary & open problems

Coordination games

- Rate of convergence and network structure
- “Small number of connections” is not enough for fast convergence
- More precise measure: tilted cutwidth or isoperimetric function of the graph

To do

- Obtain a similar understanding of other games (especially non-potential games)
- Algorithms for computing tilted cutwidth/predicting the outcome of dynamics