

Stability of the bipartite matching model

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joint work with Varun Gupta (Carnegie Mellon University) and
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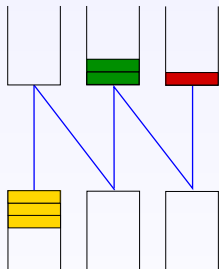
Edinburgh, June 2010

Bipartite Matching Model

Model with multiclass flavor but with customers/servers playing completely symmetrical roles.

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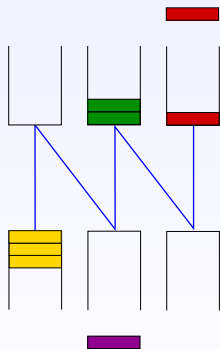
Model with multiclass flavor but with customers/servers playing completely symmetrical roles.



- ▶ Both “customers” and “servers” arrive into the system and depart from it.
- ▶ **Discrete time**: at each time step there is one customer and one server that arrive into the system, independently of the past.
- ▶ **Instantaneous matchings** according to a bipartite **matching graph**. Customers/servers that cannot be matched are stored in a buffer.

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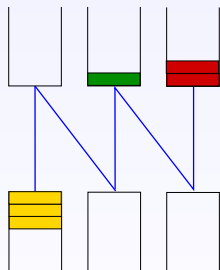
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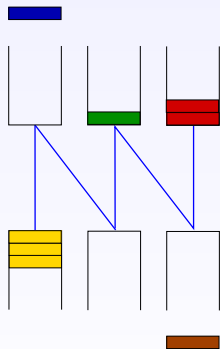
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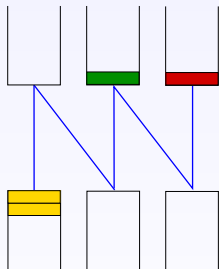
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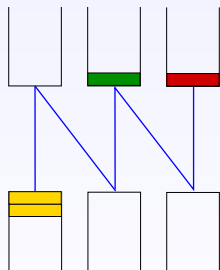
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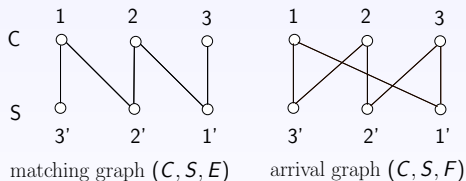
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Fully specified by: a matching graph, a joint probability measure μ for arrivals of customers/servers and a matching policy.

Bipartite Matching Model

Def. A **bipartite matching structure** is a quadruple (C, S, E, F) where:

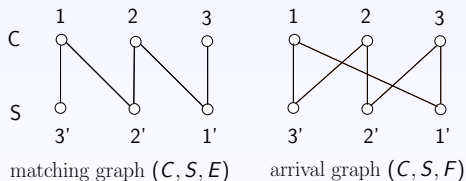
- ▶ C (resp. S) finite set of customer (resp. server) types;
- ▶ $E \subset C \times S$ is the set of possible matchings;
- ▶ $F \subset C \times S$ is the set of possible arrivals.



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Def. A **bipartite matching model** is a triple $[(C, S, E, F), \mu, \text{POL}]$ where $\text{supp}(\mu) = F$, the marginals of μ satisfy: $\text{supp}(\mu_C) = C$, $\text{supp}(\mu_S) = S$, and POL is an **admissible** policy.

Bipartite Matching Model

A matching policy POL is **admissible** if:

- ▶ Only the current state of the buffer is taken into account;
- ▶ **Buffer-first** assumption: priority is given to customers/servers that are already present in the buffer.

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Discrete time Markov chain on:

- ▶ **commutative** (ex. Match the Longest, Random, Priorities)

$$\left\{ (x, y) \in \mathbb{N}^C \times \mathbb{N}^S : \sum_{c \in C} x_c = \sum_{s \in S} y_s; \forall (c, s) \in E, x_c y_s = 0 \right\} \quad (1)$$

- ▶ or **non-commutative** state space (ex. FIFO):

$$\left\{ (u, v) \in \cup_{k \geq 0} (C^k \times S^k) : ([u], [v]) \text{ belongs to (1)} \right\},$$

where $[u]$ is the commutative image of u .

Previous results

Introduced by Caldentey, Kaplan, and Weiss (2009):
FIFO and $\mu = \mu_C \times \mu_S$.

Related models:

- ▶ Constrained queueing networks (Tassiulas and Ephremides, 1992).
- ▶ Input-queued crossbar switches (McKeown, Mekkittikul, Anantharam, and Walrand, 1999).
- ▶ Models for call centers with “skills-based routing” (Gans, Koole, and Mandelbaum, 2003).

Necessary stability conditions

Def. The model is said to be **stable** if the Markov chain has a **unique** and **attractive** stationary probability measure

(i.e. measure π such that $\pi P = \pi$ and $\frac{1}{n} \sum_{k=1}^n \nu P^k$ converges weakly to π for any initial measure ν , where P is the transition probability matrix).

For a matching graph (C, S, E) we denote:

$$C(s) = \{c \in C : (c, s) \in E\}, \quad S(c) = \{s \in S : (c, s) \in E\}.$$

Necessary conditions: If the model is stable then the marginals of μ satisfy

$$\text{NCOND} : \begin{cases} \mu_C(U) < \mu_S(S(U)), & \forall U \subsetneq C \\ \mu_S(V) < \mu_C(C(V)), & \forall V \subsetneq S \end{cases}$$

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Prop. Given $[(C, S, E), \mu]$, there exists an algorithm of time complexity $O((|C| + |S|)^3)$ to decide if NCOND is satisfied.

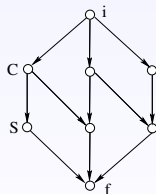
Proof

Proof using network flow arguments:

$$\mathcal{N} = (C \cup S \cup \{i, f\}, E \cup \{(i, c), c \in C\} \cup \{(s, f), s \in S\}).$$

Lemma.

1. There exists a flow of value 1 in \mathcal{N} iff (μ_C, μ_S) satisfies NCOND_{\leq} ($<$ replaced by \leq in NCOND).
2. There exists a flow T of value 1 such that $T(c, s) > 0$ for all $(c, s) \in E$ iff (μ_C, μ_S) satisfies NCOND .



Proof of Lemma 2

⇒ Follows easily from connectedness of the matching graph.

⇐ Fix η such that $0 < \eta < 1/|E|$. A strictly positive flow of value $|E|\eta$:

$$T_\eta(x, y) = \begin{cases} \eta & \text{for } (x, y) = (c, s) \in E \\ |S(c)| \eta & \text{for } (x, y) = (i, c) \\ |C(s)| \eta & \text{for } (x, y) = (s, f). \end{cases}$$

Define: $\tilde{\mu}_C(c) = \frac{\mu_C(c) - |S(c)|\eta}{1 - |E|\eta}$, $\tilde{\mu}_S(s) = \frac{\mu_S(s) - |C(s)|\eta}{1 - |E|\eta}$.

For η small enough, $\tilde{\mu}_C$, $\tilde{\mu}_S$ are probability measures satisfying NCOND.

For $\tilde{\mu}_C$, $\tilde{\mu}_S$ there exists a flow \tilde{T} of value 1.

A strictly positive flow of value 1: $T = T_\eta + (1 - |E|\eta)\tilde{T}$.

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Verification algorithm: The pair (μ_C, μ_S) satisfies NCOND iff the pair $(\tilde{\mu}_C, \tilde{\mu}_S)$ satisfies NCOND for η strictly positive and small enough.

Run MAXFLOW on the input $(\mathcal{N}, \tilde{\mu}_C, \tilde{\mu}_S)$ by considering η as a **formal parameter** “as small as needed”.

Stable structures

Def. A bipartite matching structure (C, S, E, F) is **stable** if there exists a probability measure μ such that:

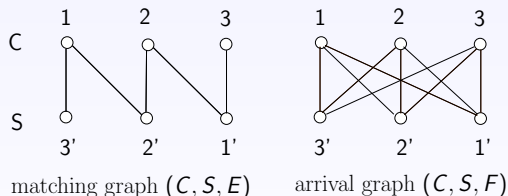
- ▶ $\text{supp}(\mu) = F$, $\text{supp}(\mu_C) = C$, $\text{supp}(\mu_S) = S$.
- ▶ μ_C and μ_S satisfy NCOND.

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Example 1.



Consider the product measure $\mu = \mu_C \times \mu_S$ with:

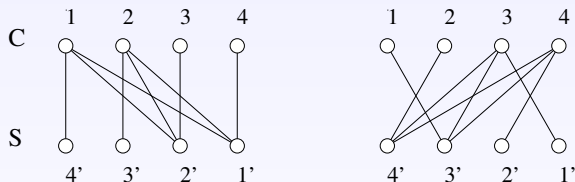
$$\mu_C : \mu_C(1) = \mu_C(2) = 2/5, \mu_C(3) = 1/5,$$

$$\mu_S : \mu_S(1') = \mu_S(2') = 2/5, \mu_S(3') = 1/5.$$

Then (μ_C, μ_S) satisfy NCOND.

Stable structures

Example 2.



Consider any μ with $\text{supp}(\mu) = F$. We have

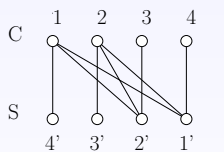
$$\mu_S(\{1', 2'\}) = \mu(3, 1') + \mu(4, 2') \leq \mu_C(\{3, 4\}),$$

which contradicts NCOND for $U = \{3, 4\}$.

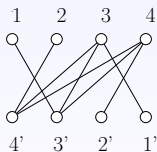
Connectivity properties

Consider a bipartite matching structure (C, S, E, F) . Associated **directed** graph: the nodes are $C \cup S$ and the arcs are

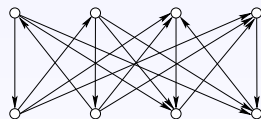
$$c \longrightarrow s, \quad \text{if } (c, s) \in E, \quad s \longrightarrow c, \quad \text{if } (c, s) \in F.$$



matching graph (C, S, E)



arrival graph (C, S, F)



associated directed graph

Connectivity properties

Thm. For a bipartite matching structure (C, S, E, F) the following properties are equivalent:

1. There exists μ such that $\text{supp}(\mu) = F$, $\text{supp}(\mu_C) = C$, $\text{supp}(\mu_S) = S$ and μ satisfies NCOND.
2. The associated directed graph is strongly connected.

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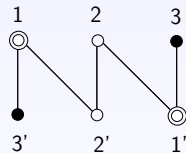
Def. Property UTC for the transition graph of the Markov chain: existence of a unique (terminal) strictly connected component with all states leading to it.

Thm. If the associated directed graph of (C, S, E, F) is strongly connected, then any bipartite matching model $[(C, S, E, F), \mu, \text{POL}]$ satisfies the property UTC.

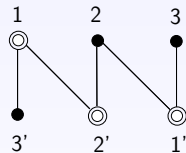
State space decomposition

The state space can be decomposed into facets, defined only by the non-empty classes.

Def. A **facet** is an ordered pair (U, V) such that: $U \subset C, V \subset S$ and $U \times V \subset (C \times S - E)$.



facet $(\{3\}, \{3'\})$



facet $(\{2, 3\}, \{3'\})$

For a facet $\mathcal{F} = (U, V)$, define:

$$\begin{aligned} C_{\bullet}(\mathcal{F}) &= U, & C_{\odot}(\mathcal{F}) &= C(V), & C_{\circ}(\mathcal{F}) &= C - (C_{\bullet}(\mathcal{F}) \cup C_{\odot}(\mathcal{F})) \\ S_{\bullet}(\mathcal{F}) &= V, & S_{\odot}(\mathcal{F}) &= S(U), & S_{\circ}(\mathcal{F}) &= S - (S_{\bullet}(\mathcal{F}) \cup S_{\odot}(\mathcal{F})). \end{aligned}$$

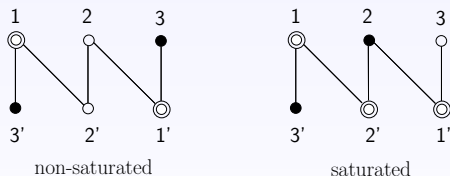
Sufficient conditions

Conditions **SCOND**:

$$\mu_C(C_{\odot}(\mathcal{F})) + \mu_S(S_{\odot}(\mathcal{F})) > 1 - \mu(E \cap C_{\circ}(\mathcal{F}) \times S_{\circ}(\mathcal{F})), \forall \mathcal{F} \neq (\emptyset, \emptyset)$$

Def. A facet \mathcal{F} is called **saturated** if $C_{\circ}(\mathcal{F}) = \emptyset$ or $S_{\circ}(\mathcal{F}) = \emptyset$.

SCOND \implies **NCOND** (considering only the saturated facets).



Prop. (Sufficient conditions) A bipartite model with probability μ satisfying **SCOND** is stable under any admissible matching policy.

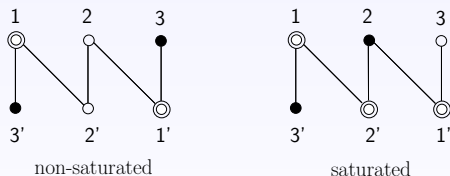
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Cor. Consider a bipartite graph in which **any non-zero facet is saturated**. For any admissible matching policy, **the stability region is maximal**.

Match the Longest has maximal stability region

Match the Longest (ML) policy: a newly arriving customer of class c is matched to a server in $S(c)$ with the largest buffer (similarly for newly arriving server).

Thm. For any bipartite graph, ML has a maximal stability region.

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Proof:

- ▶ Quadratic Lyapunov function: $L(x, y) = \sum_{c \in C} x_c^2 + \sum_{s \in S} y_s^2$.
- ▶ ML minimizes the value of this Lyapunov function at each step.

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- ▶ ML minimizes the value of this Lyapunov function at each step.
- ▶ **Facet-dependent alternate policy.** In a non-zero facet \mathcal{F} : the server $s \in S_{\odot}(\mathcal{F})$ is matched to $c \in C_{\bullet}(\mathcal{F}) \cap C(s)$ with probability $P_{sc}^{\mathcal{F}}$. These probabilities can be chosen such that:

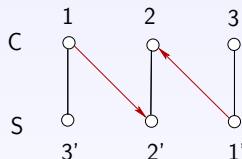
$$\forall c \in C_{\bullet}, \quad \sum_{s \in S(c)} \mu_S(s) P_{sc}^{\mathcal{F}} > \mu_C(c).$$

(and symmetrically for customers)

- ▶ For this alternate policy stability can be shown using Foster-Lyapunov criterion.

Priorities and Match the Shortest are not always stable

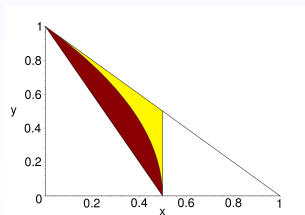
Prop. NN model with either the MS policy or the PR (priority) policy such that customers of class 1 (resp. servers of class 1') give priority to servers of class 2' (resp. to customers of class 2):



For both policies, the stability region is not maximal.

Proof:

Consider $\mu_C = (1/3, 2/5, 4/15)$, $\mu_S = \mu_C$, and $\mu = \mu_C \times \mu_S$. The conditions NCOND are satisfied, but the Markov chain is transient (for MS or PR defined as above).



Final remarks/questions

- ▶ ML has a maximal stability region. Is stability region is always maximal for some other policies (ex. FIFO and RANDOM)?
- ▶ MS and Priorities have non-maximal stability region. How to compute the stability region?
- ▶ Better sufficient conditions for stability, valid for all admissible policies?
- ▶ More general arrival assumptions?