

Scaling limit for jump, birth and death type dynamics

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Model and Motivation

- particles in the continuum \mathbb{R}^n .

$$\gamma(dx) = \text{" } \gamma(x)d^n x \text{"} = \sum_{i \in I} \delta_{x_i}(x) d^n x$$

Bolker: $N(x) = \gamma(x)d^n x$

- potentially infinite many particles
- Spatial point process \mathbb{P}
- Expectation: $\langle F(\gamma) \rangle_{\mathbb{P}} = \int F(\gamma) dP(\gamma)$
- Expected density at x

$$\langle g(d^n x) \rangle = \rho(x) d^n x$$

- Weak form: f nice function on \mathbb{R}^n .

$$\int_{\mathbb{R}^n} f(x) \gamma(dx) = \sum_{i \in I} \int_{\mathbb{R}^n} f(x) \delta_{x_i}(x) d^n x = \sum_{i=1}^n f(x_i)$$

- $f(x) = 1$ on $\Delta \subset \mathbb{R}^n$, then

$$\int_{\mathbb{R}^n} f(x) \gamma(dx) = \gamma(\Delta) = \#\{i \in I : x_i \in \Delta\} = N_\Delta(\gamma)$$

- Discretization: $\mathbb{R}^n = \cup_{j \in \mathbb{Z}^n} \Delta_j$ and $f(x) = a_j$ if $x \in \Delta_j$. Then

$$\int_{\mathbb{R}^n} f(x) \gamma(dx) = \sum_j f_j \#\{i \in I : x_i \in \Delta_j\} = \sum_j f_j \gamma(\Delta_j) = \sum_j f_j N(j)$$

where $N(j) = \#\{i \in I : x_i \in \Delta_j\} = \gamma(\Delta_j)$.

Birth generator

- Birth

$$N(j) \rightarrow N(j) + \delta_i(j) = \begin{cases} N(j) & \text{for } j \neq i \\ N(j) + 1 & \text{for } j = i \end{cases}, \quad \text{rate } B(i, N(\cdot))$$

in the continuum

$$\gamma(d^n x) \rightarrow \gamma(d^n x) + \delta_y(dx^n)$$

Rate: birth from site j into i

$$N(j)B(j, i, N(\cdot))$$

Generator

$$(L_b F)(N(\cdot)) = \sum_i \sum_j N(j)B(i, j, N(\cdot)) (F(N(\cdot) + \delta_i(\cdot)) - F(N(\cdot)))$$

Birth, death generator

- in the continuum

$$(L_b F)(\gamma) = \int_{\mathbb{R}^n} d^n x \int_{\mathbb{R}^n} \gamma(d^n y) B(x, y, \gamma) (F(\gamma + \delta_y) - F(\gamma))$$

- Independent birth: $B(y, \gamma) = B_0$.
- Death

$$(L_d F)(\gamma) = \int_{\mathbb{R}^n} \gamma(d^n y) D(y, \gamma) (F(\gamma - \delta_y) - F(\gamma)).$$

- Independent death $D(y, \gamma) = D_0$.

Jump generator, dynamics

- Jump

$$(L_j F)(\gamma) = \int_{\mathbb{R}^n} d^n y \int_{\mathbb{R}^n} \gamma(d^n x) A(x, y, \gamma) (F(\gamma + \delta_y - \delta_x) - F(\gamma))$$

- Dynamics

$$\frac{d}{dt} F(\gamma_t) = LF(\gamma_t) + \frac{d}{dt} M(F, t)$$

$M(F, t)$ martingale, in particular $\langle M(F, t) \rangle = 0$.

- Case $F(\gamma) = \int_{\mathbb{R}^n} f(x) \gamma(dx)$, then

$$(L_b F)(\gamma) = \int_{\mathbb{R}^n} d^n y \int_{\mathbb{R}^n} \gamma(d^n x) B(x, y, \gamma) f(y)$$

$$(L_d F)(\gamma) = - \int_{\mathbb{R}^n} \gamma(d^n x) d(x, \gamma) f(x)$$

$$(L_j F)(\gamma) = \int_{\mathbb{R}^n} dy \int_{\mathbb{R}^n} \gamma(d^n x) A(x, y, \gamma) (f(y) - f(x))$$

Dynamic of first correlation function

- Definition $\rho_t(x)d^n x = \langle \gamma_t(d^n x) \rangle$ Hence

$$\int_{\mathbb{R}^n} d^n x f(x) \rho_t(x) = \langle \int_{\mathbb{R}^n} f(x) \gamma_t(d^n x) \rangle$$

Thus

$$\begin{aligned} \frac{d}{dt} \int_{\mathbb{R}^n} d^n x f(x) \rho_t(x) &= \int_{\mathbb{R}^n} d^n y \int_{\mathbb{R}^n} \langle \gamma(d^n x) B(x, y, \gamma) \rangle f(y) \\ &\quad - \int_{\mathbb{R}^n} \langle \gamma(d^n x) d(x, \gamma) \rangle f(x) \\ &\quad + \int_{\mathbb{R}^n} d^n y \int_{\mathbb{R}^n} \langle \gamma(d^n x) A(x, y, \gamma) \rangle (f(y) - f(x)) \\ &\quad + \frac{d}{dt} \langle M(f, \gamma_t) \rangle \end{aligned}$$

If for example $d(x, \gamma) = \int_{\mathbb{R}^n} r(x-y) \gamma(d^n y)$, then

$$\langle \gamma(d^n x) d(x, \gamma) \rangle = \int_{\mathbb{R}^n} r(x-y) \langle \gamma(d^n y) \gamma(d^n x) \rangle$$

where $\langle \gamma(d^n y) \gamma(d^n x) \rangle = 2c(x, y) d^n x d^n y + \delta(x-y) \rho(x) d^n x$

Space scaling

- Discretization: $\mathbb{R}^n = \cup_{j \in \mathbb{Z}^n} L\Delta_j$ and $f_L(x) = a_j$ if $x \in \Delta_j$.
Then

$$\int_{\mathbb{R}^n} f_L(x) \gamma(dx) = \sum_j a_j \#\{i \in I : x_i \in L\Delta_j\}$$

Grows in L often like L^d . Normalize

$$\begin{aligned} & \frac{1}{L^d} \sum_j a_j \#\{i \in I : x_i \in L\Delta_j\} \\ &= \frac{1}{L^d} \sum_j a_j \#\{i \in I : x_i/L \in \Delta_j\} = \int_{\mathbb{R}^n} f(x) \gamma_L(d^n x) \end{aligned}$$

where

$$\gamma_L(d^n x) = L^{-d} \sum_i \delta_{x_i/L}(d^n x)$$

- Then

$$\frac{d}{dt} \int_{\mathbb{R}^n} f(x) \rho_L(t, dx) = \frac{d}{dt} \left\langle \int_{\mathbb{R}^n} f(x) \gamma_L(t, dx) \right\rangle \quad (1)$$

$$= L^{-d} \frac{d}{dt} \int_{\mathbb{R}^n} f(x/L) \gamma(dx) \quad (2)$$

- Jump part

$$\begin{aligned} & L^{-d} \int_{\mathbb{R}^n} d^n y \int_{\mathbb{R}^n} \gamma(d^n x) A(x, y, \gamma) (f(y/L) - f(x)) \\ &= \int_{\mathbb{R}^n} d^n y \int_{\mathbb{R}^n} \gamma_L(d^n x) A(xL, y, \gamma) (f(y/L) - f(x)) \end{aligned}$$

- Translation invariance

$$A(x, y, \gamma) = A(0, y - x, \tau_x \gamma), \quad \tau_x \text{ translation.}$$

$$= \int_{\mathbb{R}^n} d^n y \int_{\mathbb{R}^n} \gamma_L(d^n x) A(0, y, \tau_{xL} \gamma) (f(x + y/L) - f(x))$$

- Independent jump : $A(x, y, \gamma) = a(x - y)$ Then

$$= \int_{\mathbb{R}^n} d^n y \int_{\mathbb{R}^n} \gamma_L(d^n x) a(y) (f(x + y/L) - f(x))$$

- Expansion in large L

$$= \int_{\mathbb{R}^n} d^n y \int_{\mathbb{R}^n} \gamma_L(d^n x) A(0, y, \tau_{xL} \gamma) \left(f(x) + \sum_{k=1}^n \partial_i f(x) y_i / L \right. \\ \left. + \sum_{k,j=1}^n \partial_i \partial_j f(x) y_i y_j / L^2 + O(L^{-3}) - f(x) \right) \\ = \int_{\mathbb{R}^n} \gamma_L(d^n x) \left(L^{-1} \sum_{k=1}^n a_i^{(1)}(\tau_{xL} \gamma) \partial_i f(x) \right. \\ \left. + L^{-2} \sum_{k,j=1}^n a_{i,j}^{(2)}(\tau_{xL} \gamma) \partial_i \partial_j f(x) + O(L^{-3}) \right)$$

where $a_i^{(1)}(\gamma) = \int_{\mathbb{R}^n} d^n y A(0, y, \gamma) y_i$
 and $a_{i,j}^{(2)}(\gamma) = \int_{\mathbb{R}^n} d^n y A(0, y, \gamma) y_i y_j$

- rewritten

$$\begin{aligned}
 &= L^{-1} \sum_{k=1}^n \int_{\mathbb{R}^n} \gamma_L(d^n x) \partial_i f(x) a_i^{(1)}(\tau_{xL} \gamma) \\
 &+ L^{-2} \sum_{k,j=1}^n \int_{\mathbb{R}^n} \gamma_L(d^n x) \partial_i \partial_j f(x) a_{i,j}^{(2)}(\tau_{xL} \gamma) + O(L^{-3})
 \end{aligned}$$

- Independent jump: $A(x, y, \gamma) = a(x - y)$

$$\begin{aligned}
 \frac{d}{dt} \int_{\mathbb{R}^n} \gamma_L(t, d^n x) f(x) &= L^{-1} \sum_{k=1}^n \int_{\mathbb{R}^n} \gamma_L(t, d^n x) \partial_i f(x) a_i^{(1)} \\
 &+ L^{-2} \sum_{k,j=1}^n \int_{\mathbb{R}^n} \gamma_L(t, d^n x) \partial_i \partial_j f(x) a_{i,j}^{(2)} \\
 &+ \frac{d}{dt} M(F, t)
 \end{aligned}$$

- In expectation

$$\begin{aligned} \frac{d}{dt} \int_{\mathbb{R}^n} \rho_L(t, d^n x) f(x) &= \frac{d}{dt} \int_{\mathbb{R}^n} \langle \gamma_L(t, d^n x) \rangle f(x) \\ &= L^{-1} \sum_{k=1}^n \int_{\mathbb{R}^n} \rho_L(t, d^n x) \partial_i f(x) a_i^{(1)} \\ &\quad + L^{-2} \sum_{k,j=1}^n \int_{\mathbb{R}^n} \rho_L(t, d^n x) \partial_i \partial_j f(x) a_{i,j}^{(2)} + O(L^{-3}) \end{aligned}$$

- On timescale L we get

$$\frac{d}{dt} \int_{\mathbb{R}^n} \rho(t, d^n x) f(x) = \sum_{k=1}^n \int_{\mathbb{R}^n} \rho(t, d^n x) \partial_i f(x) a_i^{(1)}$$

- If $a^{(1)} = 0$ on timescale L^2 we get

$$\frac{d}{dt} \int_{\mathbb{R}^n} \rho(t, d^n x) f(x) = \sum_{k,j=1}^n \int_{\mathbb{R}^n} \rho_L(t, d^n x) \partial_i \partial_j f(x) a_{i,j}^{(2)}$$

- for each sample

$$\begin{aligned} \frac{d}{dt} \int_{\mathbb{R}^n} \gamma_L(t, d^n x) f(x) &= L^{-1} \sum_{k=1}^n \int_{\mathbb{R}^n} \gamma_L(t, d^n x) \partial_i f(x) a_i^{(1)} \\ &+ L^{-2} \sum_{k,j=1}^n \int_{\mathbb{R}^n} \gamma_L(t, d^n x) \partial_i \partial_j f(x) a_{i,j}^{(2)} + O(L^{-3}) + \frac{d}{dt} M(F, t) \end{aligned}$$

- If $a^{(1)} = 0$ on timescale L^2 we get for $L \rightarrow \infty$

$$P \left(\left| \int_{\mathbb{R}^n} \gamma_L(t, d^n x) f(x) - \int_{\mathbb{R}^n} \rho(t, d^n x) f(x) \right| \geq \varepsilon \right) = 0$$

Interacting

- In expectation

$$\begin{aligned} \frac{d}{dt} \int_{\mathbb{R}^n} \rho_L(t, d^n x) f(x) &= \frac{d}{dt} \int_{\mathbb{R}^n} \langle \gamma_L(t, d^n x) \rangle f(x) \\ &= L^{-1} \sum_{k=1}^n \int_{\mathbb{R}^n} \partial_{ij} f(x) \langle \gamma_L(t, d^n x) a_i^{(1)}(\tau_{xL} \gamma_t) \rangle \\ &\quad + L^{-2} \sum_{k,j=1}^n \int_{\mathbb{R}^n} \partial_i \partial_j f(x) \langle \gamma_L(t, d^n x) a_{i,j}^{(2)}(\tau_{xL} \gamma_t) \rangle + O(L^{-3}) \end{aligned}$$

- If $a^{(1)} = 0$ on timescale L^2 we get

$$\begin{aligned} \frac{d}{dt} \int_{\mathbb{R}^n} \rho_L(t, d^n x) f(x) \\ &= L^{-2} \sum_{k,j=1}^n \int_{\mathbb{R}^n} \partial_i \partial_j f(x) \langle \gamma_L(t, d^n x) a_{i,j}^{(2)}(\tau_{xL} \gamma_t) \rangle + O(L^{-3}) \end{aligned}$$

- Type of closure problem

$$\langle \gamma_L(t, d^n x) a_{i,j}^{(2)}(\tau_{xL} \gamma_t) \rangle = D(\rho_L) \quad \text{What is } D(\rho_l)$$

- Assume existence reversible spatial point process
- Example $A(0, y, \gamma) = A(0, -y, \gamma)$ (gradient system)
- Invariant spatial point processes: all Poisson $\pi_z, z \geq 0$
- Local equilibrium: large time, order L^2

$$\left\langle \int_{\mathbb{R}^n} g(x) \gamma_L(t, d^n x) a_{i,j}^{(2)}(\tau_{xL} \gamma(t, \cdot)) \right\rangle \sim \int_{\mathbb{R}^n} g(x) \gamma_L(t, d^n x) \int a_{i,j}^{(2)}(\gamma) \pi_z$$

Define

$$D_{i,j}(z) = \int a_{i,j}^{(2)}(\gamma) \pi_z(d\gamma)$$

- Limiting equation

$$\frac{d}{dt} \int_{\mathbb{R}^n} \rho(t, d^n x) f(x) = \sum_{k,j=1}^n \int_{\mathbb{R}^n} D_{i,j}(\rho(t, x)) \partial_i \partial_j f(x) \rho(t, x) d^n x$$

- If $A(0, y, \gamma) \neq A(0, -y, \gamma)$ then relation is given by variational principle (Green-Kubo)

- Then

$$\frac{d}{dt} \int_{\mathbb{R}^n} f(x) \rho_L(t, dx) = \frac{d}{dt} \left\langle \int_{\mathbb{R}^n} f(x) \gamma_L(dx) \right\rangle \quad (3)$$

$$= L^{-d} \frac{d}{dt} \int_{\mathbb{R}^n} f(x/L) \gamma(dx) \quad (4)$$

- Birth part

$$\begin{aligned} & L^{-d} \int_{\mathbb{R}^n} d^n y \int_{\mathbb{R}^n} \gamma(d^n x) B(x, y, \gamma) f(y/L) \\ &= \int_{\mathbb{R}^n} d^n y \int_{\mathbb{R}^n} \gamma_L(d^n x) B(xL, y, \gamma) f(y/L) \end{aligned}$$

- Translation invariance

$$B(x, y, \gamma) = B(0, y - x, \tau_x \gamma), \quad \tau_x \text{ translation.}$$

$$= \int_{\mathbb{R}^n} d^n y \int_{\mathbb{R}^n} \gamma_L(d^n x) B(0, xL + y, \tau_{xL} \gamma) f(x + y/L)$$

- expansion in L

$$\begin{aligned}
 &= \int_{\mathbb{R}^n} \gamma_L(d^n x) \left(b^{(0)}(\tau_{xL}\gamma) f(x) + L^{-1} \sum_{k=1}^n b_i^{(1)}(\tau_{xL}\gamma) \partial_i f(x) \right. \\
 &\quad \left. + L^{-2} \sum_{k,j=1}^n b_{i,j}^{(2)}(\tau_{xL}\gamma) \partial_i \partial_j f(x) + O(L^{-3}) \right)
 \end{aligned}$$

where

$$b^{(0)}(\gamma) = \int_{\mathbb{R}^n} d^n y B(0, y, \gamma)$$

$$b_i^{(1)}(\gamma) = \int_{\mathbb{R}^n} d^n y B(0, y, \gamma) y_i$$

$$b_{i,j}^{(2)}(\gamma) = \int_{\mathbb{R}^n} d^n y B(0, y, \gamma) y_i y_j$$

Independent birth

- independent birth

$$B(x, y, \gamma) = b(x - y)$$

Then

$$= \int_{\mathbb{R}^n} d^n y \int_{\mathbb{R}^n} \gamma_L(d^n x) b(y) f(x + y/L)$$

- Expansion in large L

$$= \int_{\mathbb{R}^n} d^n y \int_{\mathbb{R}^n} \gamma_L(d^n x) b(y) \left(f(x) + \sum_{k=1}^n \partial_i f(x) y_i / L \right. \\ \left. + \sum_{k,j=1}^n \partial_i \partial_j f(x) y_i y_j / L^2 + O(L^{-3}) \right) \\ = \int_{\mathbb{R}^n} \gamma_L(d^n x) \left(b^{(0)} f(x) + L^{-1} \sum_{k=1}^n b_i^{(1)} \partial_i f(x) \right. \\ \left. + L^{-2} \sum_{i,j=1}^n b_{i,j}^{(2)} \partial_i \partial_j f(x) + O(L^{-3}) \right)$$

$$\begin{aligned} &= \int_{\mathbb{R}^n} \gamma_L(d^n x) \left(b^{(0)} f(x) + L^{-1} \sum_{k=1}^n b_i^{(1)} \partial_i f(x) \right. \\ &\quad \left. + L^{-2} \sum_{k,j=1}^n b_{i,j}^{(2)} \partial_i \partial_j f(x) + O(L^{-3}) \right) \end{aligned}$$

where

$$b^{(0)} = \int_{\mathbb{R}^n} d^n y b(y)$$

$$b_i^{(1)} = \int_{\mathbb{R}^n} d^n y b(y) y_i$$

$$b_{i,j}^{(2)} = \int_{\mathbb{R}^n} d^n y b(y) y_i y_j$$

Independent death

- independent death

$$D(x, \gamma) = d^{(0)}$$

Then

$$= - \int_{\mathbb{R}^n} \gamma_L(d^n x) d^{(0)} f(x)$$

Altogether

$$\begin{aligned} \frac{d}{dt} \int_{\mathbb{R}^n} \gamma_L(d^n x) f(x) &= (b^{(0)} - d^{(0)}) \int_{\mathbb{R}^n} \gamma_L(d^n x) f(x) \\ &+ L^{-1} \sum_{k=1}^n b_i^{(1)} \int_{\mathbb{R}^n} \gamma_L(d^n x) \partial_i f(x) \\ &+ L^{-2} \sum_{k,j=1}^n b_{i,j}^{(2)} \int_{\mathbb{R}^n} \gamma_L(d^n x) \partial_i \partial_j f(x) + O(L^{-3}) + \frac{d}{dt} M(F, t) \end{aligned}$$

- In expectation

$$\begin{aligned} \frac{d}{dt} \int_{\mathbb{R}^n} d^n x \rho_L(t, x) f(x) &= (b^{(0)} - d^{(0)}) \int_{\mathbb{R}^n} d^n x \rho_L(t, x) f(x) \\ &+ L^{-1} \sum_{k=1}^n b_i^{(1)} d^n x \rho_L(t, x) \partial_i f(x) \\ &+ L^{-2} \sum_{k,j=1}^n b_{i,j}^{(2)} \int_{\mathbb{R}^n} d^n x \rho_L(t, x) \partial_i \partial_j f(x) + O(L^{-3}) + 0 \end{aligned}$$

- No moment closure problem

Characteristics

- Martingale: $F(X_t) - F(X_0) - \int_0^t ds LF(X_s) =: M_t(F, X)$

- Generator

$$LF(\gamma) = d \sum_{x \in \text{supp}(\gamma)} \left(F(\gamma - \delta_x) - F(\gamma) \right) + \int dy \sum_{x \in \text{supp}(\gamma)} a(x-y) \left(F(\gamma + \delta_y) - F(\gamma) \right)$$

- Compensator

$$\left\langle M(F, X) \right\rangle_t = \int_0^t ds \square_L(F, F)(X_s)$$

$$\square_L(F, F)(\gamma) := d \sum_{x \in \text{supp}(\gamma)} \left(F(\gamma - \delta_x) - F(\gamma) \right)^2 + \int dy \sum_{x \in \text{supp}(\gamma)} a(x-y) \left(F(\gamma + \delta_y) - F(\gamma) \right)^2$$

Characteristics

- Martingale: $F(X_t) - F(X_0) - \int_0^t ds LF(X_s) =: M_t(F, X)$

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$$LF(\gamma) = d \sum_{x \in \text{supp}(\gamma)} \left(F(\gamma - \delta_x) - F(\gamma) \right) \\ + \int dy \sum_{x \in \text{supp}(\gamma)} a(x-y) \left(F(\gamma + \delta_y) - F(\gamma) \right)$$

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$$\square_L(F, F)(\gamma) := d \sum_{x \in \text{supp}(\gamma)} \left(F(\gamma - \delta_x) - F(\gamma) \right)^2 \\ + \int dy \sum_{x \in \text{supp}(\gamma)} a(x-y) \left(F(\gamma + \delta_y) - F(\gamma) \right)^2$$

Invariant measures

- density $\rho_t \rightarrow \begin{cases} +\infty & \text{for } d < \int dy a(y) \\ 0 & \text{for } d = \int dy a(y) \\ -\infty & \text{for } d > \int dy a(y) \end{cases}$
- Time development of correlation functions

$$\begin{aligned} \frac{\partial k_t}{\partial t}(\eta) &= |\eta| \left(\int dy a(y) - d \right) k_t(\eta) \\ &\quad + \sum_{x \in \eta} \int dy a(x-y) [k_t(\eta \cup y \setminus x) - k_t(\eta)] \\ &\quad + \sum_{x_1 \in \eta} \sum_{x_2 \in \eta} a(x_1 - x_2) k_t(\eta \setminus x_1) \end{aligned}$$

- Critical value: $d = \int dy a(y)$
- Characterization of invariant measure via correlation (cummulants)
- Bounds $O((n!)^2)$. Clustering

Invariant measures

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- Time development of correlation functions

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Invariant measures

- LLN:

$$\varepsilon^n \sum_{x \in \gamma} \varphi(\varepsilon x) \rightarrow \rho \int dy \varphi(y)$$

- CLT:

$$\varepsilon^{n/2+1} \left(\sum_{x \in \gamma} \varphi(\varepsilon x) - \varepsilon^{-n} \rho \int dy \varphi(y) \right)$$

converges to Gauss measure on $\mathcal{S}'(\mathbb{R}^n)$ with covariance

$$2\rho \left(\sum_{i,j=1}^n \int_{\mathbb{R}^n} y_i y_j a(y) dy \partial_i \partial_j \right)^{-1}$$

Characteristics

- $X^{(\varepsilon)}$ fulfills

$$\langle \varphi, X_t^{(\varepsilon)} \rangle - \langle \varphi, X_0^{(\varepsilon)} \rangle - \int_0^t ds L^{(\varepsilon)} \langle \varphi, \cdot \rangle (X_s^{(\varepsilon)}) =: M_t^{(\varepsilon)}(\langle \varphi, \cdot \rangle, X^{(\varepsilon)})$$

is a martingale, where

$$L^{(\varepsilon)} \langle \varphi, \cdot \rangle = \langle A_\varepsilon \varphi, \gamma \rangle$$

with

$$A_\varepsilon \varphi(x) := -d\varepsilon^{-2} \varphi(x) + \varepsilon^{-2} \int dy \varepsilon^{-n} a(\varepsilon^{-1}(y-x)) \varphi(y)$$

- Compensator

$$\langle M^{(\varepsilon)}(\langle \varphi, \cdot \rangle, X^{(\varepsilon)}) \rangle_t = \int_0^t ds \left\langle d\varphi^2 + \int dy \varepsilon^{-n} a(\varepsilon^{-1}(y-\cdot)) \varphi^2(y), X_s^{(\varepsilon)} \right\rangle$$

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- $X^{(\varepsilon)}$ fulfills

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$$\begin{aligned} A_\varepsilon \varphi(x) &= \varepsilon^{-2} \int dy a(y) (\varphi(x + \varepsilon y) - \varphi(x)) \\ &= \sum_{i,j=1}^d \left(\int dy a(y) y_i y_j \right) \partial_i \partial_j \varphi(x) + o(\varepsilon) \end{aligned}$$

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Main result

Theorem

Let $X_0^{(\varepsilon)} \in \Gamma^{(\varepsilon)}(X)$ with $X_0^{(\varepsilon)} \rightarrow \nu$.

Then $(X^{(\varepsilon)})_\varepsilon$ converges weakly w.r.t. Skorokhod topology to a unique measure valued càdlàg process X such that

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is a martingale, where $A\varphi := \frac{1}{2} \sum_{i,j=1}^d \left(\int dy a(y) y_i y_j \right) \partial_i \partial_j$ and

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- Lattice version: R. Durrett and E. A. Perkins, '99
 - Same limiting process
 - Finite measure as initial condition
 - Artefacts from discrete structure
 - Slightly non-critical
- Continuous version
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Scheme of proof

- Bound uniform in $0 \leq t \leq T$ and ε of

$$\langle \varphi, X_t^{(\varepsilon)} \rangle$$

- Explicit scaling limit for $\langle \varphi, X_t^{(\varepsilon)} \rangle$.
- Control of process up to times $\varepsilon^{-2}T$.
- Compactness in weak topology w.r.t. Skorokhod topology
- Martingale representation, explicit formula for quadratic variation
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Further development

- Hydrodynamic limit:

$$\varepsilon^n \int_{\mathbb{R}^n} \varphi(\varepsilon x) X_{\varepsilon^{-2}T}(dx)$$

- Critical fluctuations at non-zero density