

Some kinetic models of swarming

J. A. Carrillo,

in collaboration with J. A. Cañizo and J. Rosado (UAB), to appear in M3AS.

in collaboration with F. Bolley (Paris-Dauphine) and J. A. Cañizo (UAB), preprint INI 2010 and to appear in M3AS.

in collaboration with M. Fornasier (Linz), J. Rosado (UAB) and G. Toscani (Pavia), SIMA 2010.

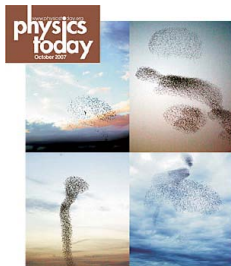
ICREA - Universitat Autònoma de Barcelona

ICMS, Edinburgh 2010

Outline

- 1 Some Swarming Models
 - Particle models.
 - Kinetic Models and measure solutions.
- 2 Qualitative Properties
 - Cucker-Smale Kinetic model
- 3 Stochastic Mean-Field Limit
 - Set-up & Main Result
 - Proof

Swarming



The physics of flocking



Fish schools and Birds flocks.

Outline

- 1 **Some Swarming Models**
 - **Particle models.**
 - Kinetic Models and measure solutions.
- 2 Qualitative Properties
 - Cucker-Smale Kinetic model
- 3 Stochastic Mean-Field Limit
 - Set-up & Main Result
 - Proof

Model with an asymptotic velocity

D'Orsogna, Bertozzi et al. model (PRL 2006):

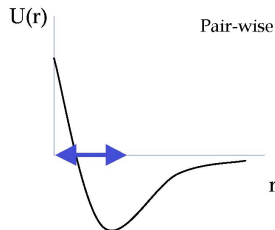
$$\begin{cases} \frac{dx_i}{dt} = v_i, \\ \frac{dv_i}{dt} = (\alpha - \beta |v_i|^2)v_i - \sum_{j \neq i} \nabla U(|x_i - x_j|). \end{cases}$$

Model assumptions:

- Self-propulsion and friction terms determines an asymptotic speed of $\sqrt{\alpha/\beta}$.
- Attraction/Repulsion modeled by an effective pairwise potential $U(x)$.

$$U(r) = -C_A e^{-r/\ell_A} + C_R e^{-r/\ell_R}.$$

$C = C_R/C_A > 1$, $\ell = \ell_R/\ell_A < 1$
and $C\ell^2 < 1$:



Model with an asymptotic velocity

D'Orsogna, Bertozzi et al. model (PRL 2006):

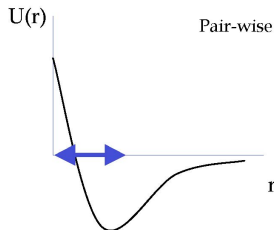
$$\begin{cases} \frac{dx_i}{dt} = v_i, \\ \frac{dv_i}{dt} = (\alpha - \beta |v_i|^2)v_i - \sum_{j \neq i} \nabla U(|x_i - x_j|). \end{cases}$$

Model assumptions:

- Self-propulsion and friction terms determines an asymptotic speed of $\sqrt{\alpha/\beta}$.
- Attraction/Repulsion modeled by an effective pairwise potential $U(x)$.

$$U(r) = -C_A e^{-r/\ell_A} + C_R e^{-r/\ell_R}.$$

$C = C_R/C_A > 1$, $\ell = \ell_R/\ell_A < 1$
and $C\ell^2 < 1$:



Model with an asymptotic velocity

D'Orsogna, Bertozzi et al. model (PRL 2006):

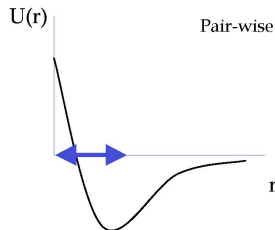
$$\begin{cases} \frac{dx_i}{dt} = v_i, \\ \frac{dv_i}{dt} = (\alpha - \beta |v_i|^2)v_i - \sum_{j \neq i} \nabla U(|x_i - x_j|). \end{cases}$$

Model assumptions:

- Self-propulsion and friction terms determines an asymptotic speed of $\sqrt{\alpha/\beta}$.
- Attraction/Repulsion modeled by an effective pairwise potential $U(x)$.

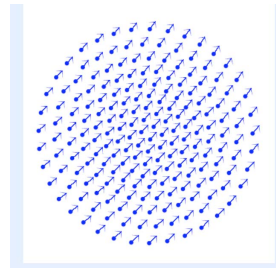
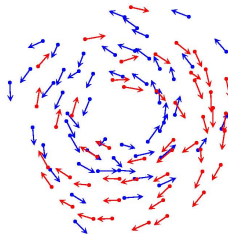
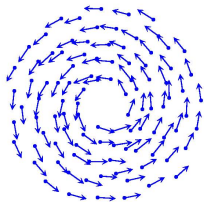
$$U(r) = -C_A e^{-r/\ell_A} + C_R e^{-r/\ell_R}.$$

$C = C_R/C_A > 1$, $\ell = \ell_R/\ell_A < 1$
and $C\ell^2 < 1$:



Model with an asymptotic velocity

Typical patterns: milling, double milling or flocking.



Double milling patterns: Carrillo, D'Orsogna, Panferov, KRM (2009).

Velocity consensus model

Cucker-Smale Model (IEEE Automatic Control 2007):

$$\begin{cases} \frac{dx_i}{dt} = v_i, \\ \frac{dv_i}{dt} = \sum_{j=1}^N a_{ij} (v_j - v_i), \end{cases}$$

with the communication rate, $\gamma \geq 0$:

$$a_{ij} = a(|x_i - x_j|) = \frac{1}{(1 + |x_i - x_j|^2)^\gamma}.$$

Unconditional flocking: $\gamma \leq 1/2$; Ha-Tadmor, Ha-Liu,
Carrillo-Fornasier-Toscani-Rosado.

Conditional flocking: $\gamma > 1/2$.

Velocity consensus model

Cucker-Smale Model (IEEE Automatic Control 2007):

$$\begin{cases} \frac{dx_i}{dt} = v_i, \\ \frac{dv_i}{dt} = \sum_{j=1}^N a_{ij} (v_j - v_i), \end{cases}$$

with the communication rate, $\gamma \geq 0$:

$$a_{ij} = a(|x_i - x_j|) = \frac{1}{(1 + |x_i - x_j|^2)^\gamma}.$$

Unconditional flocking: $\gamma \leq 1/2$; Ha-Tadmor, Ha-Liu,
Carrillo-Fornasier-Toscani-Rosado.

Conditional flocking: $\gamma > 1/2$.

Velocity consensus model

Cucker-Smale Model (IEEE Automatic Control 2007):

$$\begin{cases} \frac{dx_i}{dt} = v_i, \\ \frac{dv_i}{dt} = \sum_{j=1}^N a_{ij} (v_j - v_i), \end{cases}$$

with the communication rate, $\gamma \geq 0$:

$$a_{ij} = a(|x_i - x_j|) = \frac{1}{(1 + |x_i - x_j|^2)^\gamma}.$$

Unconditional flocking: $\gamma \leq 1/2$; Ha-Tadmor, Ha-Liu, Carrillo-Fornasier-Toscani-Rosado.

Conditional flocking: $\gamma > 1/2$.

Outline

- 1 **Some Swarming Models**
 - Particle models.
 - **Kinetic Models and measure solutions.**
- 2 Qualitative Properties
 - Cucker-Smale Kinetic model
- 3 Stochastic Mean-Field Limit
 - Set-up & Main Result
 - Proof

Mesoscopic models

Model with asymptotic velocity + Attraction/Repulsion:

$$\frac{\partial f}{\partial t} + v \cdot \nabla_x f + \operatorname{div}_v [(\alpha - \beta|v|^2)v f] - \operatorname{div}_v [(\nabla_x U \star \rho) f] = 0.$$

Velocity consensus Model:

$$\frac{\partial f}{\partial t} + v \cdot \nabla_x f = \nabla_v \cdot \left[\underbrace{\left(\int_{\mathbb{R}^{2d}} \frac{v-w}{(1+|x-y|^2)^\gamma} f(y, w, t) dy dw \right)}_{:=\xi(f)(x, v, t) = H(x, v) \star_{(x, v)} f} f(x, v, t) \right]$$

Orientation, Attraction and Repulsion:

$$\frac{\partial f}{\partial t} + v \cdot \nabla_x f - \operatorname{div}_v [(\nabla_x U \star \rho) f] = \nabla_v \cdot [\xi(f)(x, v, t) f(x, v, t)].$$

Mesoscopic models

Model with asymptotic velocity + Attraction/Repulsion:

$$\frac{\partial f}{\partial t} + v \cdot \nabla_x f + \operatorname{div}_v [(\alpha - \beta|v|^2)v f] - \operatorname{div}_v [(\nabla_x U \star \rho) f] = 0.$$

Velocity consensus Model:

$$\frac{\partial f}{\partial t} + v \cdot \nabla_x f = \nabla_v \cdot \left[\underbrace{\left(\int_{\mathbb{R}^{2d}} \frac{v - w}{(1 + |x - y|^2)^\gamma} f(y, w, t) dy dw \right)}_{:= \xi(f)(x, v, t) = H(x, v) \star_{(x, v)} f} f(x, v, t) \right]$$

Orientation, Attraction and Repulsion:

$$\frac{\partial f}{\partial t} + v \cdot \nabla_x f - \operatorname{div}_v [(\nabla_x U \star \rho) f] = \nabla_v \cdot [\xi(f)(x, v, t) f(x, v, t)].$$

Mesoscopic models

Model with asymptotic velocity + Attraction/Repulsion:

$$\frac{\partial f}{\partial t} + v \cdot \nabla_x f + \operatorname{div}_v [(\alpha - \beta|v|^2)v f] - \operatorname{div}_v [(\nabla_x U \star \rho) f] = 0.$$

Velocity consensus Model:

$$\frac{\partial f}{\partial t} + v \cdot \nabla_x f = \nabla_v \cdot \left[\underbrace{\left(\int_{\mathbb{R}^{2d}} \frac{v - w}{(1 + |x - y|^2)^\gamma} f(y, w, t) dy dw \right)}_{:= \xi(f)(x, v, t) = H(x, v) \star_{(x, v)} f} f(x, v, t) \right]$$

Orientation, Attraction and Repulsion:

$$\frac{\partial f}{\partial t} + v \cdot \nabla_x f - \operatorname{div}_v [(\nabla_x U \star \rho) f] = \nabla_v \cdot [\xi(f)(x, v, t) f(x, v, t)].$$

Definition of the distance¹

Transporting measures:

Given $T : \mathbb{R}^d \rightarrow \mathbb{R}^d$ measurable, we say that $\nu = T\#\mu$, if $\nu[K] := \mu[T^{-1}(K)]$ for all measurable sets $K \subset \mathbb{R}^d$, equivalently

$$\int_{\mathbb{R}^d} \varphi d\nu = \int_{\mathbb{R}^d} (\varphi \circ T) d\mu$$

for all $\varphi \in C_o(\mathbb{R}^d)$.

Random variables:

Say that X is a random variable with law given by μ , is to say $X : (\Omega, \mathcal{A}, P) \rightarrow (\mathbb{R}^d, \mathcal{B}_d)$ is a measurable map such that $X\#P = \mu$, i.e.,

$$\int_{\mathbb{R}^d} \varphi(x) d\mu = \int_{\Omega} (\varphi \circ X) dP = \mathbb{E}[\varphi(X)].$$

¹C. Villani, AMS Graduate Texts (2003).

Definition of the distance¹

Transporting measures:

Given $T : \mathbb{R}^d \rightarrow \mathbb{R}^d$ measurable, we say that $\nu = T\#\mu$, if $\nu[K] := \mu[T^{-1}(K)]$ for all measurable sets $K \subset \mathbb{R}^d$, equivalently

$$\int_{\mathbb{R}^d} \varphi d\nu = \int_{\mathbb{R}^d} (\varphi \circ T) d\mu$$

for all $\varphi \in C_o(\mathbb{R}^d)$.

Random variables:

Say that X is a random variable with law given by μ , is to say $X : (\Omega, \mathcal{A}, P) \rightarrow (\mathbb{R}^d, \mathcal{B}_d)$ is a measurable map such that $X\#P = \mu$, i.e.,

$$\int_{\mathbb{R}^d} \varphi(x) d\mu = \int_{\Omega} (\varphi \circ X) dP = \mathbb{E}[\varphi(X)].$$

¹C. Villani, AMS Graduate Texts (2003).

Definition of the distance¹

Transporting measures:

Given $T : \mathbb{R}^d \rightarrow \mathbb{R}^d$ measurable, we say that $\nu = T\#\mu$, if $\nu[K] := \mu[T^{-1}(K)]$ for all measurable sets $K \subset \mathbb{R}^d$, equivalently

$$\int_{\mathbb{R}^d} \varphi d\nu = \int_{\mathbb{R}^d} (\varphi \circ T) d\mu$$

for all $\varphi \in C_o(\mathbb{R}^d)$.

Random variables:

Say that X is a random variable with law given by μ , is to say $X : (\Omega, \mathcal{A}, P) \rightarrow (\mathbb{R}^d, \mathcal{B}_d)$ is a measurable map such that $X\#P = \mu$, i.e.,

$$\int_{\mathbb{R}^d} \varphi(x) d\mu = \int_{\Omega} (\varphi \circ X) dP = \mathbb{E}[\varphi(X)].$$

¹C. Villani, AMS Graduate Texts (2003).

Definition of the distance

Kantorovich-Rubinstein-Wasserstein Distance:

$$W_1(\mu, \nu) = \inf_{\pi} \left\{ \iint_{\mathbb{R}^d \times \mathbb{R}^d} |x - y| d\pi(x, y) \right\} = \inf_{(X, Y)} \{ \mathbb{E} [|X - Y|] \}$$

where the transference plan π runs over the set of joint probability measures on $\mathbb{R}^d \times \mathbb{R}^d$ with marginals f and $g \in \mathcal{P}_1(\mathbb{R}^d)$ and (X, Y) are all possible couples of random variables with μ and ν as respective laws.

Basic Properties

- 1 **Translation:** $f \in \mathcal{P}_1(\mathbb{R}^d)$ and $a \in \mathbb{R}^d$, let f_a denotes the translated f with vector a , then $W_1(f_a, f) = |a|$.
- 2 **Convergence of measures:** $W_1(f_n, f) \rightarrow 0$ is equivalent to $f_n \rightharpoonup f$ weakly-* as measures and convergence of first moments.
- 3 **Completeness:** The space $\mathcal{P}_1(\mathbb{R}^d)$ endowed with the distance W_1 is a complete metric space.

Definition of the distance

Kantorovich-Rubinstein-Wasserstein Distance:

$$W_1(\mu, \nu) = \inf_{\pi} \left\{ \iint_{\mathbb{R}^d \times \mathbb{R}^d} |x - y| d\pi(x, y) \right\} = \inf_{(X, Y)} \{ \mathbb{E}[|X - Y|] \}$$

where the transference plan π runs over the set of joint probability measures on $\mathbb{R}^d \times \mathbb{R}^d$ with marginals f and $g \in \mathcal{P}_1(\mathbb{R}^d)$ and (X, Y) are all possible couples of random variables with μ and ν as respective laws.

Basic Properties

- 1 **Translation:** $f \in \mathcal{P}_1(\mathbb{R}^d)$ and $a \in \mathbb{R}^d$, let f_a denotes the translated f with vector a , then $W_1(f_a, f) = |a|$.
- 2 **Convergence of measures:** $W_1(f_n, f) \rightarrow 0$ is equivalent to $f_n \rightharpoonup f$ weakly-* as measures and convergence of first moments.
- 3 **Completeness:** The space $\mathcal{P}_1(\mathbb{R}^d)$ endowed with the distance W_1 is a complete metric space.

Definition of the distance

Kantorovich-Rubinstein-Wasserstein Distance:

$$W_1(\mu, \nu) = \inf_{\pi} \left\{ \iint_{\mathbb{R}^d \times \mathbb{R}^d} |x - y| d\pi(x, y) \right\} = \inf_{(X, Y)} \{ \mathbb{E}[|X - Y|] \}$$

where the transference plan π runs over the set of joint probability measures on $\mathbb{R}^d \times \mathbb{R}^d$ with marginals f and $g \in \mathcal{P}_1(\mathbb{R}^d)$ and (X, Y) are all possible couples of random variables with μ and ν as respective laws.

Basic Properties

- 1 **Translation:** $f \in \mathcal{P}_1(\mathbb{R}^d)$ and $a \in \mathbb{R}^d$, let f_a denotes the translated f with vector a , then $W_1(f_a, f) = |a|$.
- 2 **Convergence of measures:** $W_1(f_n, f) \rightarrow 0$ is equivalent to $f_n \rightharpoonup f$ weakly-* as measures and convergence of first moments.
- 3 **Completeness:** The space $\mathcal{P}_1(\mathbb{R}^d)$ endowed with the distance W_1 is a complete metric space.

Well-posedness in probability measures²

Existence, uniqueness and stability

Take a potential $U \in \mathcal{C}^2(\mathbb{R}^d)$, H locally Lipschitz, with

$$|\nabla U(x)| \leq C(1 + |x|) \quad \text{for all } x \in \mathbb{R}^d,$$

$$|H(x, v)| \leq C(1 + |x| + |v|) \quad \text{for all } x, v \in \mathbb{R}^d,$$

and f_0 a measure on $\mathbb{R}^d \times \mathbb{R}^d$ with compact support. There exists a solution $f \in \mathcal{C}([0, +\infty); \mathcal{P}_1(\mathbb{R}^d))$ in the sense of solving the equation through the characteristics: $f_t := P^t \# f_0$ with P^t the flow map associated to the equation.

Moreover, given any two solutions f and g with initial data f_0 and g_0 , there is an increasing function depending on the size of the support of the solutions and the parameters, such that

$$W_1(f_t, g_t) \leq \alpha(t) W_1(f_0, g_0)$$

Well-posedness in probability measures²

Existence, uniqueness and stability

Take a potential $U \in \mathcal{C}^2(\mathbb{R}^d)$, H locally Lipschitz, with

$$|\nabla U(x)| \leq C(1 + |x|) \quad \text{for all } x \in \mathbb{R}^d,$$

$$|H(x, v)| \leq C(1 + |x| + |v|) \quad \text{for all } x, v \in \mathbb{R}^d,$$

and f_0 a measure on $\mathbb{R}^d \times \mathbb{R}^d$ with compact support. There exists a solution $f \in \mathcal{C}([0, +\infty); \mathcal{P}_1(\mathbb{R}^d))$ in the sense of solving the equation through the characteristics: $f_t := P^t \# f_0$ with P^t the flow map associated to the equation.

Moreover, given any two solutions f and g with initial data f_0 and g_0 , there is an increasing function depending on the size of the support of the solutions and the parameters, such that

$$W_1(f_t, g_t) \leq \alpha(t) W_1(f_0, g_0)$$

Convergence of the particle method

- **Empirical measures:** if $x_i, v_i : [0, T) \rightarrow \mathbb{R}^d$, for $i = 1, \dots, N$, is a solution to the ODE system,

$$\left\{ \begin{array}{l} \frac{dx_i}{dt} = v_i, \\ \frac{dv_i}{dt} = \underbrace{(\alpha - \beta |v_i|^2)v_i}_{\text{propulsion-friction}} - \underbrace{\sum_{j \neq i} m_j \nabla U(|x_i - x_j|)}_{\text{attraction-repulsion}} + \underbrace{\sum_{j=1}^N m_j a_{ij} (v_j - v_i)}_{\text{orientation}}. \end{array} \right.$$

then the $f : [0, T) \rightarrow \mathcal{P}_1(\mathbb{R}^d)$ given by

$$f_N(t) := \sum_{i=1}^N m_i \delta_{(x_i(t), v_i(t))}$$

is the solution corresponding to initial atomic measures.

- Convergence of approximations of measures by particles due to the stability at any given time T as an alternative derivation of the kinetic models.

Convergence of the particle method

- **Empirical measures:** if $x_i, v_i : [0, T) \rightarrow \mathbb{R}^d$, for $i = 1, \dots, N$, is a solution to the ODE system,

$$\left\{ \begin{array}{l} \frac{dx_i}{dt} = v_i, \\ \frac{dv_i}{dt} = \underbrace{(\alpha - \beta |v_i|^2)v_i}_{\text{propulsion-friction}} - \underbrace{\sum_{j \neq i} m_j \nabla U(|x_i - x_j|)}_{\text{attraction-repulsion}} + \underbrace{\sum_{j=1}^N m_j a_{ij} (v_j - v_i)}_{\text{orientation}}. \end{array} \right.$$

then the $f : [0, T) \rightarrow \mathcal{P}_1(\mathbb{R}^d)$ given by

$$f_N(t) := \sum_{i=1}^N m_i \delta_{(x_i(t), v_i(t))}$$

is the solution corresponding to initial atomic measures.

- Convergence of approximations of measures by particles due to the stability at any given time T as an alternative derivation of the kinetic models.

Convergence of the particle method

- **Empirical measures:** if $x_i, v_i : [0, T) \rightarrow \mathbb{R}^d$, for $i = 1, \dots, N$, is a solution to the ODE system,

$$\left\{ \begin{array}{l} \frac{dx_i}{dt} = v_i, \\ \frac{dv_i}{dt} = \underbrace{(\alpha - \beta |v_i|^2)v_i}_{\text{propulsion-friction}} - \underbrace{\sum_{j \neq i} m_j \nabla U(|x_i - x_j|)}_{\text{attraction-repulsion}} + \underbrace{\sum_{j=1}^N m_j a_{ij} (v_j - v_i)}_{\text{orientation}}. \end{array} \right.$$

then the $f : [0, T) \rightarrow \mathcal{P}_1(\mathbb{R}^d)$ given by

$$f_N(t) := \sum_{i=1}^N m_i \delta_{(x_i(t), v_i(t))}$$

is the solution corresponding to initial atomic measures.

- Convergence of approximations of measures by particles due to the stability at any given time T as an alternative derivation of the kinetic models.

Convergence of the particle method

- **Empirical measures:** if $x_i, v_i : [0, T) \rightarrow \mathbb{R}^d$, for $i = 1, \dots, N$, is a solution to the ODE system,

$$\left\{ \begin{array}{l} \frac{dx_i}{dt} = v_i, \\ \frac{dv_i}{dt} = \underbrace{(\alpha - \beta |v_i|^2)v_i}_{\text{propulsion-friction}} - \underbrace{\sum_{j \neq i} m_j \nabla U(|x_i - x_j|)}_{\text{attraction-repulsion}} + \underbrace{\sum_{j=1}^N m_j a_{ij} (v_j - v_i)}_{\text{orientation}}. \end{array} \right.$$

then the $f : [0, T) \rightarrow \mathcal{P}_1(\mathbb{R}^d)$ given by

$$f_N(t) := \sum_{i=1}^N m_i \delta_{(x_i(t), v_i(t))}$$

is the solution corresponding to initial atomic measures.

- Convergence of approximations of measures by particles due to the stability at any given time T as an alternative derivation of the kinetic models.

Convergence of the particle method

- **Empirical measures:** if $x_i, v_i : [0, T) \rightarrow \mathbb{R}^d$, for $i = 1, \dots, N$, is a solution to the ODE system,

$$\left\{ \begin{array}{l} \frac{dx_i}{dt} = v_i, \\ \frac{dv_i}{dt} = \underbrace{(\alpha - \beta |v_i|^2)v_i}_{\text{propulsion-friction}} - \underbrace{\sum_{j \neq i} m_j \nabla U(|x_i - x_j|)}_{\text{attraction-repulsion}} + \underbrace{\sum_{j=1}^N m_j a_{ij} (v_j - v_i)}_{\text{orientation}}. \end{array} \right.$$

then the $f : [0, T) \rightarrow \mathcal{P}_1(\mathbb{R}^d)$ given by

$$f_N(t) := \sum_{i=1}^N m_i \delta_{(x_i(t), v_i(t))}$$

is the solution corresponding to initial atomic measures.

- Convergence of approximations of measures by particles due to the stability at any given time T as an alternative derivation of the kinetic models.

Outline

- 1 Some Swarming Models
 - Particle models.
 - Kinetic Models and measure solutions.
- 2 Qualitative Properties
 - Cucker-Smale Kinetic model
- 3 Stochastic Mean-Field Limit
 - Set-up & Main Result
 - Proof

Asymptotic Flocking

Let us consider the N_p -particle system:

$$\left\{ \begin{array}{l} \frac{dx_i}{dt} = v_i \\ \frac{dv_i}{dt} = \sum_{j=1}^{N_p} m_j a(|x_i - x_j|) (v_j - v_i) \end{array} \right. , \begin{array}{l} x_i(0) = x_i^0 \\ v_i(0) = v_i^0 \end{array} .$$

Due to translation invariancy, w.l.o.g. the mean velocity is zero and thus the center of mass is preserved along the evolution, i.e.,

$$\sum_{i=1}^{N_p} m_i v_i(t) = 0 \quad \text{and} \quad \sum_{i=1}^{N_p} m_i x_i(t) = x_c$$

for all $t \geq 0$ and $x_c \in \mathbb{R}^d$.

Asymptotic Flocking

Let us consider the N_p -particle system:

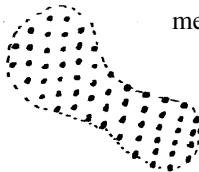
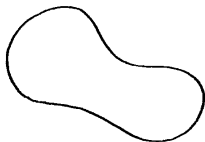
$$\left\{ \begin{array}{l} \frac{dx_i}{dt} = v_i \\ \frac{dv_i}{dt} = \sum_{j=1}^{N_p} m_j a(|x_i - x_j|) (v_j - v_i) \end{array} \right. , \quad \begin{array}{l} x_i(0) = x_i^0 \\ v_i(0) = v_i^0 \end{array} .$$

Due to translation invariancy, w.l.o.g. the mean velocity is zero and thus the center of mass is preserved along the evolution, i.e.,

$$\sum_{i=1}^{N_p} m_i v_i(t) = 0 \quad \text{and} \quad \sum_{i=1}^{N_p} m_i x_i(t) = x_c$$

for all $t \geq 0$ and $x_c \in \mathbb{R}^d$.

Asymptotic Flocking



Find a bound independent of the number of particles for the time it takes for all the particles to travel at the mean velocity.

Asymptotic Flocking

Unconditional Non-universal Flocking Result for Particles

The unique measure-valued solution for the CS kinetic model with $\gamma \leq 1/2$, with a finite number of particles given by

$$\tilde{\mu}(t) = \sum_{i=1}^{N_p} m_i \delta(x - x_i(t)) \delta(v - v_i(t)),$$

satisfies that

$$\lim_{t \rightarrow \infty} W_1(\tilde{\mu}(t), \tilde{\mu}^\infty) = 0$$

with

$$\tilde{\mu}^\infty = \sum_{i=1}^{N_p} m_i \delta(x - x_i^\infty - mt) \delta(v - m)$$

with m the initial mean velocity of the particles.

Asymptotic Flocking

Unconditional Non-universal Flocking Result for general measures

Given $\mu_0 \in \mathcal{M}(\mathbb{R}^{2d})$ compactly supported, then the unique measure-valued solution to the CS kinetic model with $\gamma \leq 1/2$, satisfies the following bounds on their supports:

$$\text{supp } \mu(t) \subset B(x_c(0) + mt, R^x(t)) \times B(m, R^v(t))$$

for all $t \geq 0$, with $R^x(t) \leq \bar{R}$ and $R^v(t) \leq R_0 e^{-\lambda t}$ with \bar{R}^x depending only on the initial support radius.

Moreover,

$$\lim_{t \rightarrow \infty} W_1(\mu_x^{mt}(t), L_\infty(\mu_0)) = 0,$$

where the measure $L_\infty(\mu_0)$ is defined as

$$\int_{\mathbb{R}^d} \zeta(x) dL_\infty(\mu_0)(x) = \int_{\mathbb{R}^{2d}} \zeta \left(x + \int_0^\infty [V(s; x, v) - m] ds \right) d\mu_0(x, v),$$

for all $\zeta \in \mathcal{C}_b^0(\mathbb{R}^d)$.

Asymptotic Flocking

Unconditional Non-universal Flocking Result for general measures

Given $\mu_0 \in \mathcal{M}(\mathbb{R}^{2d})$ compactly supported, then the unique measure-valued solution to the CS kinetic model with $\gamma \leq 1/2$, satisfies the following bounds on their supports:

$$\text{supp } \mu(t) \subset B(x_c(0) + mt, R^x(t)) \times B(m, R^v(t))$$

for all $t \geq 0$, with $R^x(t) \leq \bar{R}$ and $R^v(t) \leq R_0 e^{-\lambda t}$ with \bar{R}^x depending only on the initial support radius.

Moreover,

$$\lim_{t \rightarrow \infty} W_1(\mu_x^{mt}(t), L_\infty(\mu_0)) = 0,$$

where the measure $L_\infty(\mu_0)$ is defined as

$$\int_{\mathbb{R}^d} \zeta(x) dL_\infty(\mu_0)(x) = \int_{\mathbb{R}^{2d}} \zeta \left(x + \int_0^\infty [V(s; x, v) - m] ds \right) d\mu_0(x, v),$$

for all $\zeta \in \mathcal{C}_b^0(\mathbb{R}^d)$.

Asymptotic Flocking

Let us fix any $R_0^x > 0$ and $R_0^v > 0$, such that all the initial velocities lie inside the ball $B(0, R_0^v)$ and all positions inside $B(x_c, R_0^x)$.

Let us define the function $R^v(t)$ to be

$$R^v(t) := \max \{|v_i(t)|, i = 1, \dots, N_p\}.$$

Asymptotic Flocking

Let us fix any $R_0^x > 0$ and $R_0^v > 0$, such that all the initial velocities lie inside the ball $B(0, R_0^v)$ and all positions inside $B(x_c, R_0^x)$.

Let us define the function $R^v(t)$ to be

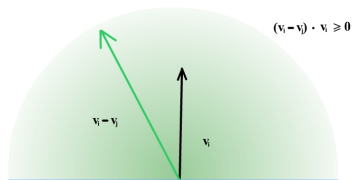
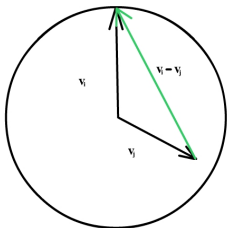
$$R^v(t) := \max \{|v_i(t)|, i = 1, \dots, N_p\}.$$

Asymptotic Flocking

Choosing the label i to be the one achieving the maximum, we get

$$\frac{d}{dt} R^v(t)^2 = \frac{d}{dt} |v_i|^2 = -2 \sum_{j \neq i} m_j [(v_i - v_j) \cdot v_i] a(|x_i - x_j|) .$$

Because of the choice of the label i , we have that $(v_i - v_j) \cdot v_i \geq 0$ for all $j \neq i$ that together with $a \geq 0$ imply $R^v(t) \leq R_0^v$ for all $t \geq 0$.

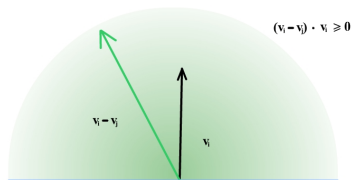
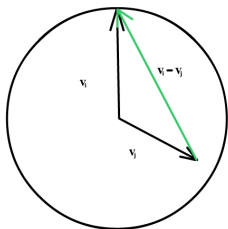


Asymptotic Flocking

Choosing the label i to be the one achieving the maximum, we get

$$\frac{d}{dt} R^v(t)^2 = \frac{d}{dt} |v_i|^2 = -2 \sum_{j \neq i} m_j [(v_i - v_j) \cdot v_i] a(|x_i - x_j|) .$$

Because of the choice of the label i , we have that $(v_i - v_j) \cdot v_i \geq 0$ for all $j \neq i$ that together with $a \geq 0$ imply $R^v(t) \leq R_0^v$ for all $t \geq 0$.



Asymptotic Flocking

Coming back to the equation for the positions,

$$|x_i(t) - x_i^0| \leq R_0^v t \quad \text{for all } t \geq 0 \text{ and all } i = 1, \dots, N_p.$$

$$a(|x_i - x_j|) \geq \frac{1}{[1 + 4R_0^2(1+t)^2]^\gamma} \quad \text{for all } t \geq 0 \text{ and all } i, j = 1, \dots, N_p,$$

with $R_0 = \min(R_0^x, R_0^v)$.

Coming back to the equation for the maximal velocity

$$\begin{aligned} \frac{d}{dt} R^v(t)^2 &= -2 \sum_{j \neq i} m_j [(v_i - v_j) \cdot v_i] a(|x_i - x_j|) \\ &\leq -\frac{2}{[1 + 4R_0^2(1+t)^2]^\gamma} \sum_{j \neq i} m_j [(v_i - v_j) \cdot v_i] \\ &= -\frac{2}{[1 + 4R_0^2(1+t)^2]^\gamma} R^v(t)^2 := -f(t) R^v(t)^2, \end{aligned}$$

Asymptotic Flocking

Coming back to the equation for the positions,

$$|x_i(t) - x_i^0| \leq R_0^v t \quad \text{for all } t \geq 0 \text{ and all } i = 1, \dots, N_p.$$

$$a(|x_i - x_j|) \geq \frac{1}{[1 + 4R_0^2(1+t)^2]^\gamma} \quad \text{for all } t \geq 0 \text{ and all } i, j = 1, \dots, N_p,$$

with $R_0 = \min(R_0^x, R_0^v)$.

Coming back to the equation for the maximal velocity

$$\begin{aligned} \frac{d}{dt} R^v(t)^2 &= -2 \sum_{j \neq i} m_j [(v_i - v_j) \cdot v_i] a(|x_i - x_j|) \\ &\leq -\frac{2}{[1 + 4R_0^2(1+t)^2]^\gamma} \sum_{j \neq i} m_j [(v_i - v_j) \cdot v_i] \\ &= -\frac{2}{[1 + 4R_0^2(1+t)^2]^\gamma} R^v(t)^2 := -f(t) R^v(t)^2, \end{aligned}$$

Asymptotic Flocking

Coming back to the equation for the positions,

$$|x_i(t) - x_i^0| \leq R_0^v t \quad \text{for all } t \geq 0 \text{ and all } i = 1, \dots, N_p.$$

$$a(|x_i - x_j|) \geq \frac{1}{[1 + 4R_0^2(1+t)^2]^\gamma} \quad \text{for all } t \geq 0 \text{ and all } i, j = 1, \dots, N_p,$$

with $R_0 = \min(R_0^x, R_0^v)$.

Coming back to the equation for the maximal velocity

$$\begin{aligned} \frac{d}{dt} R^v(t)^2 &= -2 \sum_{j \neq i} m_j [(v_i - v_j) \cdot v_i] a(|x_i - x_j|) \\ &\leq -\frac{2}{[1 + 4R_0^2(1+t)^2]^\gamma} \sum_{j \neq i} m_j [(v_i - v_j) \cdot v_i] \\ &= -\frac{2}{[1 + 4R_0^2(1+t)^2]^\gamma} R^v(t)^2 := -f(t) R^v(t)^2, \end{aligned}$$

Asymptotic Flocking

Gronwall's lemma:

$$R^v(t) \leq R_0^v \exp \left\{ -\frac{1}{2} \int_0^t f(s) ds \right\}.$$

For $\gamma \leq 1/2$, the function $f(t)$ is not integrable at ∞ and therefore

$$\lim_{t \rightarrow \infty} \int_0^t f(s) ds = +\infty$$

and $R^v(t) \rightarrow 0$ as $t \rightarrow \infty$ giving the convergence to a single point, its mean velocity, of the support for the velocity.

Again for the position variables, we get

$$\begin{cases} \int_0^t |v_i(s)| ds \leq C_1 \int_0^t (1+s)^{-1-\epsilon} ds & \gamma < 1/2 \\ \int_0^t |v_i(s)| ds \leq C \int_0^t \frac{1}{1+s} ds = C \ln(1+t) & \gamma = 1/2, \end{cases}$$

Asymptotic Flocking

Gronwall's lemma:

$$R^v(t) \leq R_0^v \exp \left\{ -\frac{1}{2} \int_0^t f(s) ds \right\}.$$

For $\gamma \leq 1/2$, the function $f(t)$ is not integrable at ∞ and therefore

$$\lim_{t \rightarrow \infty} \int_0^t f(s) ds = +\infty$$

and $R^v(t) \rightarrow 0$ as $t \rightarrow \infty$ giving the convergence to a single point, its mean velocity, of the support for the velocity.

Again for the position variables, we get

$$\begin{cases} \int_0^t |v_i(s)| ds \leq C_1 \int_0^t (1+s)^{-1-\epsilon} ds & \gamma < 1/2 \\ \int_0^t |v_i(s)| ds \leq C \int_0^t \frac{1}{1+s} ds = C \ln(1+t) & \gamma = 1/2, \end{cases}$$

Asymptotic Flocking

Gronwall's lemma:

$$R^v(t) \leq R_0^v \exp \left\{ -\frac{1}{2} \int_0^t f(s) ds \right\}.$$

For $\gamma \leq 1/2$, the function $f(t)$ is not integrable at ∞ and therefore

$$\lim_{t \rightarrow \infty} \int_0^t f(s) ds = +\infty$$

and $R^v(t) \rightarrow 0$ as $t \rightarrow \infty$ giving the convergence to a single point, its mean velocity, of the support for the velocity.

Again for the position variables, we get

$$\begin{cases} \int_0^t |v_i(s)| ds \leq C_1 \int_0^t (1+s)^{-1-\epsilon} ds & \gamma < 1/2 \\ \int_0^t |v_i(s)| ds \leq C \int_0^t \frac{1}{1+s} ds = C \ln(1+t) & \gamma = 1/2, \end{cases}.$$

Asymptotic Flocking

There exists $R_1^x > 0$ such that

$$|x_i(t) - x_i^0| \leq R_1^x$$

Now, $a(|x_i(t) - x_j(t)|) \geq a(2\bar{R}^x)$,

$$\begin{aligned} \frac{d}{dt} R^v(t)^2 &= -2 \sum_{j \neq i} m_j [(v_i - v_j) \cdot v_i] a(|x_i - x_j|) \\ &\leq -2a(2\bar{R}^x) \sum_{j \neq i} m_j [(v_i - v_j) \cdot v_i] = -2a(2\bar{R}^x) R^v(t)^2 \end{aligned}$$

from which we finally deduce the exponential decay to zero of $R^v(t)$.

Asymptotic Flocking

There exists $R_1^x > 0$ such that

$$|x_i(t) - x_i^0| \leq R_1^x$$

Now, $a(|x_i(t) - x_j(t)|) \geq a(2\bar{R}^x)$,

$$\begin{aligned} \frac{d}{dt} R^v(t)^2 &= -2 \sum_{j \neq i} m_j [(v_i - v_j) \cdot v_i] a(|x_i - x_j|) \\ &\leq -2a(2\bar{R}^x) \sum_{j \neq i} m_j [(v_i - v_j) \cdot v_i] = -2a(2\bar{R}^x) R^v(t)^2 \end{aligned}$$

from which we finally deduce the exponential decay to zero of $R^v(t)$.

Outline

- 1 Some Swarming Models
 - Particle models.
 - Kinetic Models and measure solutions.
- 2 Qualitative Properties
 - Cucker-Smale Kinetic model
- 3 **Stochastic Mean-Field Limit**
 - **Set-up & Main Result**
 - Proof

Stochastic Particle System

General Interacting Particle System with Noise:

N interacting \mathbb{R}^{2d} -valued processes $(X_t^i, V_t^i)_{t \geq 0}$ with $1 \leq i \leq N$ solution of

$$\begin{cases} dX_t^i = V_t^i dt, \\ dV_t^i = \sqrt{2} dB_t^i - F(X_t^i, V_t^i) dt - \frac{1}{N} \sum_{j=1}^N H(X_t^i - X_t^j, V_t^i - V_t^j) dt, \end{cases}$$

with independent and commonly distributed initial data (X_0^i, V_0^i) with $1 \leq i \leq N$.

Empirical Measure:

$$\hat{f}_t^N = \frac{1}{N} \sum_{i=1}^N \delta_{(X_t^i, V_t^i)}$$

Stochastic Particle System

General Interacting Particle System with Noise:

N interacting \mathbb{R}^{2d} -valued processes $(X_t^i, V_t^i)_{t \geq 0}$ with $1 \leq i \leq N$ solution of

$$\begin{cases} dX_t^i = V_t^i dt, \\ dV_t^i = \sqrt{2} dB_t^i - F(X_t^i, V_t^i) dt - \frac{1}{N} \sum_{j=1}^N H(X_t^i - X_t^j, V_t^i - V_t^j) dt, \end{cases}$$

with independent and commonly distributed initial data (X_0^i, V_0^i) with $1 \leq i \leq N$.

Empirical Measure:

$$\hat{f}_t^N = \frac{1}{N} \sum_{i=1}^N \delta_{(X_t^i, V_t^i)}$$

Stochastic Particle System

General Interacting Particle System with Noise:

N interacting \mathbb{R}^{2d} -valued processes $(X_t^i, V_t^i)_{t \geq 0}$ with $1 \leq i \leq N$ solution of

$$\begin{cases} dX_t^i = V_t^i dt, \\ dV_t^i = \sqrt{2} dB_t^i - F(X_t^i, V_t^i) dt - \frac{1}{N} \sum_{j=1}^N H(X_t^i - X_t^j, V_t^i - V_t^j) dt, \end{cases}$$

with independent and commonly distributed initial data (X_0^i, V_0^i) with $1 \leq i \leq N$.

Empirical Measure:

$$\hat{f}_t^N = \frac{1}{N} \sum_{i=1}^N \delta_{(X_t^i, V_t^i)}$$

Coupling Method 1

Stochastic Particle System Associated to PDE:

N interacting processes $(\bar{X}_t^i, \bar{V}_t^i)_{t \geq 0}$ solutions of the kinetic McKean-Vlasov type equation on \mathbb{R}^{2d} :

$$\begin{cases} d\bar{X}_t^i = \bar{V}_t^i dt \\ d\bar{V}_t^i = \sqrt{2} dB_t^i - F(\bar{X}_t^i, \bar{V}_t^i) dt - H * f_t(\bar{X}_t^i, \bar{V}_t^i) dt, \\ (\bar{X}_0^i, \bar{V}_0^i) = (X_0^i, V_0^i), \quad f_t = \text{law}(\bar{X}_t^i, \bar{V}_t^i). \end{cases}$$

The stochastic processes are independent and identically distributed according to

$$\partial_t f_t + v \cdot \nabla_x f_t = \Delta_v f_t + \nabla_v \cdot ((F + H * f_t) f_t), \quad t > 0, x, v \in \mathbb{R}^d.$$

Coupling Method 1

Stochastic Particle System Associated to PDE:

N interacting processes $(\bar{X}_t^i, \bar{V}_t^i)_{t \geq 0}$ solutions of the kinetic McKean-Vlasov type equation on \mathbb{R}^{2d} :

$$\begin{cases} d\bar{X}_t^i = \bar{V}_t^i dt \\ d\bar{V}_t^i = \sqrt{2} dB_t^i - F(\bar{X}_t^i, \bar{V}_t^i) dt - H * f_t(\bar{X}_t^i, \bar{V}_t^i) dt, \\ (\bar{X}_0^i, \bar{V}_0^i) = (X_0^i, V_0^i), \quad f_t = \text{law}(\bar{X}_t^i, \bar{V}_t^i). \end{cases}$$

The stochastic processes are independent and identically distributed according to

$$\partial_t f_t + v \cdot \nabla_x f_t = \Delta_v f_t + \nabla_v \cdot ((F + H * f_t) f_t), \quad t > 0, x, v \in \mathbb{R}^d.$$

Coupling Method 1

Stochastic Particle System Associated to PDE:

N interacting processes $(\bar{X}_t^i, \bar{V}_t^i)_{t \geq 0}$ solutions of the kinetic McKean-Vlasov type equation on \mathbb{R}^{2d} :

$$\begin{cases} d\bar{X}_t^i = \bar{V}_t^i dt \\ d\bar{V}_t^i = \sqrt{2} dB_t^i - F(\bar{X}_t^i, \bar{V}_t^i) dt - H * f_t(\bar{X}_t^i, \bar{V}_t^i) dt, \\ (\bar{X}_0^i, \bar{V}_0^i) = (X_0^i, V_0^i), \quad f_t = \text{law}(\bar{X}_t^i, \bar{V}_t^i). \end{cases}$$

The stochastic processes are independent and identically distributed according to

$$\partial_t f_t + v \cdot \nabla_x f_t = \Delta_v f_t + \nabla_v \cdot ((F + H * f_t) f_t), \quad t > 0, x, v \in \mathbb{R}^d.$$

Coupling Method 2

Conjecture: The N interacting processes $(X_t^i, V_t^i)_{t \geq 0}$ behave as $N \rightarrow \infty$ like the processes $(\bar{X}_t^i, \bar{V}_t^i)_{t \geq 0}$ associated to the PDE.

More precisely, the objective is to estimate the convergence as $N \rightarrow \infty$ of

$$\mathbb{E}[|X_t^i - \bar{X}_t^i|^2 + |V_t^i - \bar{V}_t^i|^2] \leq \varepsilon(N)$$

Consequences

1. $f_t^{(1)}$ of any of the particles X_t^i at time t converges to f_t as N goes to infinity:

$$W_2^2(f_t^{(1)}, f_t) \leq \mathbb{E}[|X_t^i - \bar{X}_t^i|^2 + |V_t^i - \bar{V}_t^i|^2] \leq \varepsilon(N).$$

Coupling Method 2

Conjecture: The N interacting processes $(X_t^i, V_t^i)_{t \geq 0}$ behave as $N \rightarrow \infty$ like the processes $(\bar{X}_t^i, \bar{V}_t^i)_{t \geq 0}$ associated to the PDE.

More precisely, the objective is to estimate the convergence as $N \rightarrow \infty$ of

$$\mathbb{E}[|X_t^i - \bar{X}_t^i|^2 + |V_t^i - \bar{V}_t^i|^2] \leq \varepsilon(N)$$

Consequences

1. $f_t^{(1)}$ of any of the particles X_t^i at time t converges to f_t as N goes to infinity:

$$W_2^2(f_t^{(1)}, f_t) \leq \mathbb{E}[|X_t^i - \bar{X}_t^i|^2 + |V_t^i - \bar{V}_t^i|^2] \leq \varepsilon(N).$$

Coupling Method 2

Conjecture: The N interacting processes $(X_t^i, V_t^i)_{t \geq 0}$ behave as $N \rightarrow \infty$ like the processes $(\bar{X}_t^i, \bar{V}_t^i)_{t \geq 0}$ associated to the PDE.

More precisely, the objective is to estimate the convergence as $N \rightarrow \infty$ of

$$\mathbb{E}[|X_t^i - \bar{X}_t^i|^2 + |V_t^i - \bar{V}_t^i|^2] \leq \varepsilon(N)$$

Consequences

1. $f_t^{(1)}$ of any of the particles X_t^i at time t converges to f_t as N goes to infinity:

$$W_2^2(f_t^{(1)}, f_t) \leq \mathbb{E}[|X_t^i - \bar{X}_t^i|^2 + |V_t^i - \bar{V}_t^i|^2] \leq \varepsilon(N).$$

Coupling Method 3

Consequences

2. **Propagation of chaos:** The law $f_t^{(k)}$ of any k particles (X_t^i, V_t^i) converges to the tensor product $f_t^{\otimes k}$ as N goes to infinity:

$$W_2^2(f_t^{(k)}, f_t^{\otimes k}) \leq k\varepsilon(N).$$

3. **Convergence of the empirical measure \hat{f}_t^N to f_t :** if φ is a Lipschitz map on \mathbb{R}^{2d} , then

$$\begin{aligned} & \mathbb{E} \left[\left| \frac{1}{N} \sum_{i=1}^N \varphi(X_t^i, V_t^i) - \int_{\mathbb{R}^{2d}} \varphi df_t \right|^2 \right] \\ & \leq 2 \mathbb{E} \left[|\varphi(X_t^i, V_t^i) - \varphi(\bar{X}_t^i, \bar{V}_t^i)|^2 + \left| \frac{1}{N} \sum_{i=1}^N \varphi(\bar{X}_t^i, \bar{V}_t^i) - \int_{\mathbb{R}^{2d}} \varphi df_t \right|^2 \right] \\ & \leq \varepsilon(N) + \frac{C}{N} \end{aligned}$$

Coupling Method 3

Consequences

2. **Propagation of chaos:** The law $f_t^{(k)}$ of any k particles (X_t^i, V_t^i) converges to the tensor product $f_t^{\otimes k}$ as N goes to infinity:

$$W_2^2(f_t^{(k)}, f_t^{\otimes k}) \leq k\varepsilon(N).$$

3. **Convergence of the empirical measure \hat{f}_t^N to f_t :** if φ is a Lipschitz map on \mathbb{R}^{2d} , then

$$\begin{aligned} & \mathbb{E} \left[\left| \frac{1}{N} \sum_{i=1}^N \varphi(X_t^i, V_t^i) - \int_{\mathbb{R}^{2d}} \varphi df_t \right|^2 \right] \\ & \leq 2 \mathbb{E} \left[|\varphi(X_t^i, V_t^i) - \varphi(\bar{X}_t^i, \bar{V}_t^i)|^2 + \left| \frac{1}{N} \sum_{i=1}^N \varphi(\bar{X}_t^i, \bar{V}_t^i) - \int_{\mathbb{R}^{2d}} \varphi df_t \right|^2 \right] \\ & \leq \varepsilon(N) + \frac{C}{N} \end{aligned}$$

Main Result

Previous Results: If the functions involved F and H are globally Lipschitz then there are classical results by Snitzman and Meleard, implying that

$$\varepsilon(N) = O\left(\frac{1}{N}\right)$$

The typical F and H in our Cucker-Smale and D'Orsogna et al model **are not globally Lipschitz.**

Hypotheses:

Assume that F and H with $H(-x, -v) = -H(x, v)$, satisfy

$$\begin{aligned} -(v-w) \cdot (F(x, v) - F(x, w)) &\leq A |v-w|^2 \\ |F(x, v) - F(y, v)| &\leq L \min\{|x-y|, 1\} (1 + |v|^p) \end{aligned}$$

for all x, y, v, w in \mathbb{R}^d , and analogously for H instead of F .

Main Result

Previous Results: If the functions involved F and H are globally Lipschitz then there are classical results by Snitzman and Meleard, implying that

$$\varepsilon(N) = O\left(\frac{1}{N}\right)$$

The typical F and H in our Cucker-Smale and D'Orsogna et al model **are not globally Lipschitz**.

Hypotheses:

Assume that F and H with $H(-x, -v) = -H(x, v)$, satisfy

$$\begin{aligned} -(v - w) \cdot (F(x, v) - F(x, w)) &\leq A |v - w|^2 \\ |F(x, v) - F(y, v)| &\leq L \min\{|x - y|, 1\} (1 + |v|^p) \end{aligned}$$

for all x, y, v, w in \mathbb{R}^d , and analogously for H instead of F .

Main Result

Previous Results: If the functions involved F and H are globally Lipschitz then there are classical results by Snitzman and Meleard, implying that

$$\varepsilon(N) = O\left(\frac{1}{N}\right)$$

The typical F and H in our Cucker-Smale and D'Orsogna et al model **are not globally Lipschitz**.

Hypotheses:

Assume that F and H with $H(-x, -v) = -H(x, v)$, satisfy

$$\begin{aligned} -(v - w) \cdot (F(x, v) - F(x, w)) &\leq A |v - w|^2 \\ |F(x, v) - F(y, v)| &\leq L \min\{|x - y|, 1\} (1 + |v|^p) \end{aligned}$$

for all x, y, v, w in \mathbb{R}^d , and analogously for H instead of F .

Main Result 2

Properties of the Stochastic Processes and PDE:

Assume that the particle system and the processes have global solutions on $[0, T]$ with initial data (X_0^i, V_0^i) such that the **uniform moment condition** holds:

$$\sup_{0 \leq t \leq T} \left\{ \int_{\mathbb{R}^{4d}} |H(x-y, v-w)|^2 df_t(x, v) df_t(y, w) + \int_{\mathbb{R}^{2d}} (|x|^2 + e^{a|v|^p}) df_t(x, v) \right\} < +\infty$$

with $f_t = \text{law}(\bar{X}_t^i, \bar{V}_t^i)$.

Main Result 3

Claim:

There exists a constant $C > 0$ such that

$$\mathbb{E}[|X_t^i - \bar{X}_t^i|^2 + |V_t^i - \bar{V}_t^i|^2] \leq \frac{C}{N^{e^{-c_t}}}$$

for all $0 \leq t \leq T$ and $N \geq 1$.

Moreover, if additionally the **uniform moment condition** holds with $p' > p$ then for all $0 < \epsilon < 1$ there exists a constant C such that

$$\mathbb{E}[|X_t^i - \bar{X}_t^i|^2 + |V_t^i - \bar{V}_t^i|^2] \leq \frac{C}{N^{1-\epsilon}}$$

for all $0 \leq t \leq T$ and $N \geq 1$.

Main Result 3

Claim:

There exists a constant $C > 0$ such that

$$\mathbb{E}[|X_t^i - \bar{X}_t^i|^2 + |V_t^i - \bar{V}_t^i|^2] \leq \frac{C}{N^{e^{-Ct}}}$$

for all $0 \leq t \leq T$ and $N \geq 1$.

Moreover, if additionally the **uniform moment condition** holds with $p' > p$ then for all $0 < \epsilon < 1$ there exists a constant C such that

$$\mathbb{E}[|X_t^i - \bar{X}_t^i|^2 + |V_t^i - \bar{V}_t^i|^2] \leq \frac{C}{N^{1-\epsilon}}$$

for all $0 \leq t \leq T$ and $N \geq 1$.

Outline

- 1 Some Swarming Models
 - Particle models.
 - Kinetic Models and measure solutions.
- 2 Qualitative Properties
 - Cucker-Smale Kinetic model
- 3 Stochastic Mean-Field Limit
 - Set-up & Main Result
 - Proof

Step 0.- Fluctuations:

Fluctuations: $x_t^i := X_t^i - \bar{X}_t^i$, $v_t^i := V_t^i - \bar{V}_t^i$, $i = 1, \dots, N$.

Coupling: the Brownian motions $(B_t^i)_{t \geq 0}$ are equal for the stochastic interacting particle system and for the processes

$$\begin{aligned} dx^i &= v^i dt, \\ dv^i &= - \left(F(X^i, V^i) - F(\bar{X}^i, \bar{V}^i) \right) dt \\ &\quad - \frac{1}{N} \sum_{j=1}^N \left(H(X^i - X^j, V^i - V^j) - (H * f_t)(\bar{X}^i, \bar{V}^i) \right) dt. \end{aligned}$$

Consider the quantity

$$\alpha(t) = \mathbb{E} [|x^i|^2 + |v^i|^2]$$

independent of the label i by symmetry.

Step 0.- Fluctuations:

Fluctuations: $x_t^i := X_t^i - \bar{X}_t^i$, $v_t^i := V_t^i - \bar{V}_t^i$, $i = 1, \dots, N$.

Coupling: the Brownian motions $(B_t^i)_{t \geq 0}$ are equal for the stochastic interacting particle system and for the processes

$$\begin{aligned} dx^i &= v^i dt, \\ dv^i &= - \left(F(X^i, V^i) - F(\bar{X}^i, \bar{V}^i) \right) dt \\ &\quad - \frac{1}{N} \sum_{j=1}^N \left(H(X^i - X^j, V^i - V^j) - (H * f_t)(\bar{X}^i, \bar{V}^i) \right) dt. \end{aligned}$$

Consider the quantity

$$\alpha(t) = \mathbb{E} [|x^i|^2 + |v^i|^2]$$

independent of the label i by symmetry.

Step 0.- Fluctuations:

Fluctuations: $x_t^i := X_t^i - \bar{X}_t^i$, $v_t^i := V_t^i - \bar{V}_t^i$, $i = 1, \dots, N$.

Coupling: the Brownian motions $(B_t^i)_{t \geq 0}$ are equal for the stochastic interacting particle system and for the processes

$$\begin{aligned} dx^i &= v^i dt, \\ dv^i &= - (F(X^i, V^i) - F(\bar{X}^i, \bar{V}^i)) dt \\ &\quad - \frac{1}{N} \sum_{j=1}^N \left(H(X^i - X^j, V^i - V^j) - (H * f_t)(\bar{X}^i, \bar{V}^i) \right) dt. \end{aligned}$$

Consider the quantity

$$\alpha(t) = \mathbb{E} [|x^i|^2 + |v^i|^2]$$

independent of the label i by symmetry.

Step 0.- Fluctuations:

$$\frac{1}{2} \frac{d}{dt} \mathbb{E} [|x^i|^2] = \mathbb{E} [x^i \cdot v^i] \leq \frac{1}{2} \alpha(t)$$

and

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \mathbb{E} [|v^i|^2] &= -\mathbb{E} \left[v^i \cdot (F(X^i, V^i) - F(\bar{X}^i, \bar{V}^i)) \right] \\ &\quad - \frac{1}{N} \mathbb{E} \left[\sum_{j=1}^N v^i \cdot (H(X^i - X^j, V^i - V^j) - H * f_t(\bar{X}^i, \bar{V}^i)) \right] =: I_1 + I_2. \end{aligned}$$

Step 1.- Localization Estimate for I_1 :

Using the hypotheses on F :

$$I_1 \leq A \mathbb{E} [|v^i|^2] + L \mathbb{E} \left[|v^i| \min\{|x^i|, 1\} (1 + |\bar{V}^i|^p) \right] := I_{11} + LI_{12}.$$

Localizing in V + Markov's inequality:

$$I_{12} \leq (1 + R^p)\alpha(t) + \frac{1}{2} \left(\mathbb{E} [|\bar{V}^i|^{4p}] \right)^{1/2} \left(e^{-aR^p} \mathbb{E} [e^{a|\bar{V}^i|^p}] \right)^{1/2}$$

Final Estimate: given $T > 0$, there exists $C > 0$ such that

$$I_1 \leq C(1 + r)\alpha(t) + Ce^{-r}$$

holds for all $r > 0$ and all $0 \leq t \leq T$.

Step 1.- Localization Estimate for I_1 :

Using the hypotheses on F :

$$I_1 \leq A \mathbb{E} [|v^i|^2] + L \mathbb{E} \left[|v^i| \min\{|x^i|, 1\} (1 + |\bar{V}^i|^p) \right] := I_{11} + LI_{12}.$$

Localizing in V + Markov's inequality:

$$I_{12} \leq (1 + R^p) \alpha(t) + \frac{1}{2} \left(\mathbb{E} [|\bar{V}^i|^{4p}] \right)^{1/2} \left(e^{-aR^p} \mathbb{E} [e^{a|\bar{V}^i|^p}] \right)^{1/2}$$

Final Estimate: given $T > 0$, there exists $C > 0$ such that

$$I_1 \leq C(1 + r) \alpha(t) + C e^{-r}$$

holds for all $r > 0$ and all $0 \leq t \leq T$.

Step 1.- Localization Estimate for I_1 :

Using the hypotheses on F :

$$I_1 \leq A \mathbb{E} [|v^i|^2] + L \mathbb{E} \left[|v^i| \min\{|x^i|, 1\} (1 + |\bar{V}^i|^p) \right] := I_{11} + LI_{12}.$$

Localizing in V + Markov's inequality:

$$I_{12} \leq (1 + R^p) \alpha(t) + \frac{1}{2} \left(\mathbb{E} [|\bar{V}^i|^{4p}] \right)^{1/2} \left(e^{-aR^p} \mathbb{E} [e^{a|\bar{V}^i|^p}] \right)^{1/2}$$

Final Estimate: given $T > 0$, there exists $C > 0$ such that

$$I_1 \leq C(1 + r) \alpha(t) + C e^{-r}$$

holds for all $r > 0$ and all $0 \leq t \leq T$.

Step 2.- Localization Estimate for I_2 :

$$\begin{aligned}
 I_2 &= -\frac{1}{N} \mathbb{E} \left[\sum_{j=1}^N v^j \cdot \left(H(X^i - X^j, v^i - v^j) - H(\bar{X}^i - \bar{X}^j, \bar{V}^i - \bar{V}^j) \right) \right] \\
 &\quad - \frac{1}{N} \mathbb{E} \left[v^i \cdot \left(H(0, 0) - (H * f_t)(\bar{X}^i, \bar{V}^i) \right) \right] \\
 &\quad - \frac{1}{N} \mathbb{E} \left[\sum_{j \neq i}^N v^j \cdot \left(H(\bar{X}^i - \bar{X}^j, \bar{V}^i - \bar{V}^j) - (H * f_t)(\bar{X}^i, \bar{V}^i) \right) \right] \\
 &=: I_{21} + I_{22} + I_{23}.
 \end{aligned}$$

Localization in I_{21} : given $T > 0$, there exists $C > 0$ such that

$$I_{21} \leq C(1+r) \alpha(t) + C e^{-r}$$

holds for all $r > 0$ and all $0 \leq t \leq T$.

Step 2.- Localization Estimate for I_2 :

$$\begin{aligned}
 I_2 &= -\frac{1}{N} \mathbb{E} \left[\sum_{j=1}^N v^i \cdot \left(H(X^i - X^j, v^i - v^j) - H(\bar{X}^i - \bar{X}^j, \bar{V}^i - \bar{V}^j) \right) \right] \\
 &\quad - \frac{1}{N} \mathbb{E} \left[v^i \cdot \left(H(0, 0) - (H * f_t)(\bar{X}^i, \bar{V}^i) \right) \right] \\
 &\quad - \frac{1}{N} \mathbb{E} \left[\sum_{j \neq i}^N v^i \cdot \left(H(\bar{X}^i - \bar{X}^j, \bar{V}^i - \bar{V}^j) - (H * f_t)(\bar{X}^i, \bar{V}^i) \right) \right] \\
 &=: I_{21} + I_{22} + I_{23}.
 \end{aligned}$$

Localization in I_{21} : given $T > 0$, there exists $C > 0$ such that

$$I_{21} \leq C(1+r)\alpha(t) + Ce^{-r}$$

holds for all $r > 0$ and all $0 \leq t \leq T$.

Step 2.- Localization Estimate for I_2 :

Moment bounds:

$$I_{22} \leq \frac{1}{N} (\mathbb{E} [|v^i|^2])^{1/2} \left(\mathbb{E} \left[|(H * f_t)(\bar{X}^i, \bar{V}^i)|^2 \right] \right)^{1/2} \leq \frac{C}{N} \sqrt{\alpha(t)}.$$

Standard Argument of Law of Large Numbers: (Snitzman)

$$I_{23} \leq \frac{1}{N} (\mathbb{E} [|v^1|^2])^{1/2} \left(\mathbb{E} \left[\left| \sum_{j=2}^N Y^j \right|^2 \right] \right)^{1/2} \leq \frac{C}{\sqrt{N}} \sqrt{\alpha(t)}$$

where $Y^j := H(\bar{X}^1 - \bar{X}^j, \bar{V}^1 - \bar{V}^j) - (H * f_t)(\bar{X}^1, \bar{V}^1)$ for $j \geq 2$.

Step 2.- Localization Estimate for I_2 :

Moment bounds:

$$I_{22} \leq \frac{1}{N} (\mathbb{E} [|v^i|^2])^{1/2} \left(\mathbb{E} \left[|(H * f_t)(\bar{X}^i, \bar{V}^i)|^2 \right] \right)^{1/2} \leq \frac{C}{N} \sqrt{\alpha(t)}.$$

Standard Argument of Law of Large Numbers: (Snitzman)

$$I_{23} \leq \frac{1}{N} (\mathbb{E} [|v^1|^2])^{1/2} \left(\mathbb{E} \left[\left| \sum_{j=2}^N Y^j \right|^2 \right] \right)^{1/2} \leq \frac{C}{\sqrt{N}} \sqrt{\alpha(t)}$$

where $Y^j := H(\bar{X}^1 - \bar{X}^j, \bar{V}^1 - \bar{V}^j) - (H * f_t)(\bar{X}^1, \bar{V}^1)$ for $j \geq 2$.

Step 3.- Conclusion:

First Result: given $T > 0$, there exists $C > 0$ such that

$$\alpha'(t) \leq C(1+r)\alpha(t) + Ce^{-r} + \frac{C}{\sqrt{N}}\sqrt{\alpha(t)} \leq C(1+r)\alpha(t) + Ce^{-r} + \frac{C}{N}$$

for all $t \in [0, T]$, all $N \geq 1$ and all $r > 0$. This implies due to changes of variables:

$$u' \leq -u \ln u + \frac{1}{N}$$

implying the first statement.

Second Result: A better localization implies that given $T > 0$, there exists $C > 0$ such that

$$\alpha'(t) \leq C(1+r)\alpha(t) + Ce^{-r^{p'/p}} + \frac{C}{N}$$

for all $t \in [0, T]$, all $N \geq 1$ and all $r > 0$.

Step 3.- Conclusion:

First Result: given $T > 0$, there exists $C > 0$ such that

$$\alpha'(t) \leq C(1+r)\alpha(t) + Ce^{-r} + \frac{C}{\sqrt{N}}\sqrt{\alpha(t)} \leq C(1+r)\alpha(t) + Ce^{-r} + \frac{C}{N}$$

for all $t \in [0, T]$, all $N \geq 1$ and all $r > 0$. This implies due to changes of variables:

$$u' \leq -u \ln u + \frac{1}{N}$$

implying the first statement.

Second Result: A better localization implies that given $T > 0$, there exists $C > 0$ such that

$$\alpha'(t) \leq C(1+r)\alpha(t) + Ce^{-r^{p'/p}} + \frac{C}{N}$$

for all $t \in [0, T]$, all $N \geq 1$ and all $r > 0$.

Step 3.- Conclusion:

First Result: given $T > 0$, there exists $C > 0$ such that

$$\alpha'(t) \leq C(1+r)\alpha(t) + Ce^{-r} + \frac{C}{\sqrt{N}}\sqrt{\alpha(t)} \leq C(1+r)\alpha(t) + Ce^{-r} + \frac{C}{N}$$

for all $t \in [0, T]$, all $N \geq 1$ and all $r > 0$. This implies due to changes of variables:

$$u' \leq -u \ln u + \frac{1}{N}$$

implying the first statement.

Second Result: A better localization implies that given $T > 0$, there exists $C > 0$ such that

$$\alpha'(t) \leq C(1+r)\alpha(t) + Ce^{-r^{p'/p}} + \frac{C}{N}$$

for all $t \in [0, T]$, all $N \geq 1$ and all $r > 0$.