Dynamical moduli spaces and multipliers of periodic points

Lukas Geyer (Montana State University) joint with Adam Epstein (University of Warwick)

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Dynamical Moduli Space

Definition

For $d \ge 2$, the *dynamical moduli spaces* of rational maps and polynomials are

$$\mathcal{M}_d = \operatorname{End}_d(\hat{\mathbb{C}}) / \operatorname{M\"ob}(\hat{\mathbb{C}}) \quad \text{ and } \quad \mathcal{M}_d^P = \operatorname{End}_d(\mathbb{C}) / \operatorname{M\"ob}(\mathbb{C})$$

Here $\operatorname{End}_d(\hat{\mathbb{C}})$ and $\operatorname{End}_d(\mathbb{C})$ are the rational maps and polynomials of degree *d*, respectively, and $\operatorname{M\ddot{o}b}(\hat{\mathbb{C}})$ and $\operatorname{M\ddot{o}b}(\mathbb{C})$ are the groups of Möbius transformations and affine transformations, respectively, acting by conjugation.

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Coordinates on Polynomial Moduli Space

Easy to see

$$\mathcal{M}_{d}^{P} \approx \{f(z) = z^{d} + a_{d-2}z^{d-2} + \ldots + a_{0}\}/C_{d-1}$$

where C_{d-1} is the group of rotations by (d-1)-th roots of unity ω , acting on coefficients by

$$(a_0,\ldots,a_{d-2})\mapsto (\omega^{-1}a_0,a_1,\omega a_2,\ldots,\omega^{d-3}a_{d-2}).$$

- Simple description as a quotient of C^{d−1} by a finite cyclic group (not acting freely), but coefficients a_k do not have an obvious dynamical significance.
- Are there better (dynamically significant) coordinates?

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Coordinates on Rational Moduli Space

Theorem (Milnor 1993)

 $\mathcal{M}_2 \approx \mathbb{C}^2$. More explicitly, quadratic rational moduli space has global coordinates given by the symmetric functions $\sigma_1 = \mu_1 + \mu_2 + \mu_3$ and $\sigma_2 = \mu_1 \mu_2 + \mu_1 \mu_3 + \mu_2 \mu_3$ of the three multipliers μ_1, μ_2, μ_3 of fixed points.

- Obviously, these coordinates σ_1 and σ_2 have dynamical significance.
- In higher dimensions things are more complicated and less explicit, see Silverman for an algebraic approach.

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Rigidity of Multipliers and Lattès Locus

Definition

A rational map *f* is a *flexible Lattès map* if there is a doubly periodic non-constant meromorphic $g : \mathbb{C} \to \hat{\mathbb{C}}$ and an integer $n \ge 2$ with f(g(z)) = g(nz) for all *z*. The *flexible Lattès locus* Λ_d is the corresponding subset of \mathcal{M}_d .

Theorem (McMullen 1987)

Outside of the flexible Lattès locus, the Möbius conjugacy class of a rational map is determined up to finitely many choices by the set of all multipliers of periodic points.

Note that deformations of the torus associated to g give rise to a complex one-dimensional family in \mathcal{M}_d with all multipliers constant.

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Rigidity of Multipliers, quantitatively

Corollary (McMullen 1987)

For every $d \ge 2$ there exist N_d and K_d such that the multipliers of periodic points up to period N_d determine at most K_d points in $\mathcal{M}_d \setminus \Lambda_d$.

Question

- Milnor: $N_2 = K_2 = 1$ is optimal.
- For all ε > 0 there exists C_ε > 0 such that K_d ≥ C_εd^{1/2-ε}. (Silverman, using non-flexible Lattès maps.)
- There are *d* independent multipliers of fixed points, and dim M_d = 2d − 2 > d for d ≥ 3, so N_d ≥ 2 for d ≥ 3.

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What are the minimal pairs (N_d, K_d) ?

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Generic rigidity definition

Definition

For $d \ge 2$, N_d , $K_d \ge 1$, we say that multipliers up to period N_d generically determine at most K_d points in dynamical moduli space \mathcal{M}_d if there exists an open dense subset $\widetilde{\mathcal{M}}_d \subset \mathcal{M}_d$ such that this holds in $\widetilde{\mathcal{M}}_d$.

Theorem (G., Epstein)

For $d \ge 3$, multipliers up to period $N_d = 2$ generically determine at most a finite number K_d of points in dynamical moduli space.

Gorbovickis 2015: Multipliers of 2*d* − 2 distinct periodic cycles, under mild additional conditions, are algebraically independent. Requires that at least one cycles has period ≥ 3, so generic rigidity with N_d = 3 follows.

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Generic rigidity, idea of proof

- End_d(Ĉ) is an irreducible affine variety, and generic rigidity follows from the fact that the rank of the derivative of the multiplier map μ₂ : End_d(Ĉ) → C^m is 2d 2 on an open dense set. (Here μ₂ maps to the multipliers of periods 1 and 2, and we have to avoid multipliers equal to 1.)
- The set of points determined by finitely many multiplier conditions is a subvariety, so it suffices to show this result locally at one point, namely in a neigborhood of f(z) = z^d.

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Generic rigidity, idea of proof, continued

- Parametrizing as f_{a,b}(z) = ^{z^d+a_{d-1}z^{d-1}+...+a₁z}/_{1+b_{d-1}z+...+b₁z^{d-1}} with a, b ∈ C^{d-1} we can calculate the partial derivatives of all the multipliers of period 1 and 2 with respect to a and b at a = b = 0.
- Interesting observation: The matrix of derivatives of fixed point multipliers with respect to *a* is up to constants the Vandermonde matrix of the (d 1)-th roots of unity.
- Computationally it helps that $1/f_{a,b}(1/z) = f_{b,a}(z)$, so that $f_{a,b}$ and $f_{b,a}$ have the same multipliers, which means that we really only need the partial derivatives with respect to *a*.

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- Parametrizing as f_{a,b}(z) = ^{z^d+a_{d-1}z^{d-1}+...+a₁z}/(1+b_{d-1}z+...+b₁z^{d-1}) with a, b ∈ C^{d-1} we can calculate the partial derivatives of all the multipliers of period 1 and 2 with respect to a and b at a = b = 0.
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Rigidity for polynomials, preliminaries

- All the same questions can be asked for the polynomial moduli space M^P_d, where the situation is considerably nicer.
- Multipliers of fixed points determine a unique point in M^P_d only for d = 2 and d = 3. For d ≥ 4, pick integers a, b ≥ 2 with a + b = d and let f_λ(z) = z + (z aλ)^b(z + bλ)^a. Then f_λ is a one-dimensional non-constant family of monic centered polynomials of degree d with all fixed point multipliers equal to 1.

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Holomorphic index of a fixed point

Definition

The holomorphic index of f at a fixed point z_0 is the residue

$$\iota(f, z_0) = \frac{1}{2\pi i} \int_{|z-z_0|=r} \frac{dz}{f(z)-z}$$

for sufficiently small r > 0.

- For a simple fixed point with $\lambda = f'(z_0) \neq 1$, we have $\iota(f, z_0) = \frac{1}{\lambda 1}$ by simple complex analysis.
- The holomorphic index is invariant under analytic conjugation.

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Fixed point data rigidity for polynomials

Definition

The *fixed point data* of a polynomial f is the collection of all multiplicities and holomorphic indices of fixed points.

Theorem (G., Epstein)

- Fujimura 2007: Generically, multipliers determine (d 2)! points in \mathcal{M}_d^P .
- Sugiyama 2017: Fiber structure of the multiplier map for polynomials without multiple fixed points.
- Gorbovickis 2016: Any collection of multipliers of *d* 1 distinct periodic points is algebraically independent.

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Fixed point data proof idea

Write

$$f_{\zeta}(z) = z + \prod_{k=1}^{l} (z - \zeta_k)^{m_k} = z + p_{\zeta}(z)$$

where ζ_k are distinct with $\sum_{k=1}^{l} m_k \zeta_k = 0$. Then f_{ζ} is monic, centered, with fixed points ζ_k of holomorphic index

$$\eta_k(\zeta) = \frac{1}{(m_k - 1)!} \left(\frac{\partial}{\partial \zeta_k}\right)^{m_k - 1} \prod_{j \neq k} \frac{1}{(\zeta_k - \zeta_j)^{m_j}}.$$

and

$$\frac{\partial \eta_k}{\partial \zeta_j}(\zeta) = m_j \operatorname{Res}_{\zeta_k} \frac{1}{(z-\zeta_j)p_{\zeta}(z)} =: a_{kj}$$

By the holomorphic fixed point formula, $\sum_{k=1}^{l} a_{kj} = 0$ for all *j*, and the vector (1, 1, ..., 1) is in the kernel of $p_{\eta_{\xi_{i}}}$, q_{i} ,

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Fixed point data proof idea, continued

If $v = (v_1 \dots, v_l)$ is in the kernel of $D\eta_{\zeta}$, then

$$\operatorname{Res}_{\zeta_k}\sum_{j=1}^l rac{m_j v_j}{(z-\zeta_j) p_\zeta(z)} = \operatorname{Res}_{\zeta_k} g(z) = 0.$$

- Then g is a rational function with all zero residues, vanishing at ∞ to order ≥ d + 1, so there exists a non-constant rational anti-derivative G with G' = g, vanishing at ∞ to order ≥ d, so deg G ≥ d.
- On the other hand, multiplicity of pole at ζ_j is $\leq m_j$, so deg $G \leq \sum_j m_j = d$.

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Fixed point data proof idea, continued

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Fixed point data proof, conclusion

So *G* is a rational function of degree *d* without finite zeros, and 1/*G* is a polynomial of degree *d* with zeros of multiplicities *m_j* at ζ_j, which implies 1/*G*(*z*) = *cp*_ζ(*z*).

• This implies

$$g(z) = G'(z) = -\frac{1}{c} \sum_{j=1}^{l} \frac{m_j}{(z-\zeta_j) p_{\zeta}(z)}$$

so $v = -\frac{1}{c}(1, 1, \dots, 1).$

 This shows that the kernel of η is spanned by (1, 1, ..., 1), so the rank of Dη_ζ is d − 1.

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Hutz-Tepper Conjecture

A natural question is whether one can trade off more multipliers (increase N_d) to reduce the ambiguity (decrease K_d).

Theorem (G., Epstein)

For $d \ge 4$, the multipliers up to period $N_d = 2$ generically determine a unique point in (polynomial) dynamical moduli space \mathcal{M}_d^P .

- Hutz and Tepper showed this for *d* ≤ 5 using explicit algebraic computations of Groebner bases and conjectured that this holds generally.
- Polynomials f
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Hutz-Tepper Conjecture proof idea

- There is exactly one point in \mathcal{M}_d^P with d-1 multipliers zero, represented by $P_0(z) = \frac{d}{d-1}z + z^d$.
- Standard construction using quasiconformal surgery shows that a neighborhood of P₀ can be analytically parametrized by the multipliers λ = (λ₁,..., λ_{d-1}) ∈ D^{d-1}.
- Similarly, any tuple of attracting multipliers $\lambda = (\lambda_1, \dots, \lambda_{d-1}) \in \mathbb{D}^{d-1}$ is obtained this way.
- Ambiguity comes from permuting the cyclic order of multipliers, which can be done in (d – 2)! ways.
- Explicitly compute the derivatives of period 2 multipliers with respect to fixed point multipliers and show non-symmetry w.r.t. (non-cyclic) permutations.

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Open questions

- What are the minimal pairs (N_d, K_d) for McMullen's original question? Some non-trivial bounds on minimal N_d ?
- Silverman showed that one always has an ambiguity K_d of at least the class number of $\mathbb{Q}[\sqrt{-d}]$ (which is the number of equivalence classes of tori admitting a multiplication by $i\sqrt{d}$). Is this bound sharp?
- Using the fact that *f* ∘ *g* and *g* ∘ *f* have the same multipliers, the ambiguity K^P_d for polynomials of degree *d* is at least the number of prime factors of *d*. Is this bound sharp?
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