

Estimates of shape derivatives around nonsmooth domains

Michel Pierre

Ecole Normale Supérieure de Rennes
and Institut de Recherche Mathématique de Rennes
Bretagne, France

Shape optimization and spectral geometry
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Introduction and notation

- ▶ Goal: find estimates on the shape derivatives $E'(\Omega_0), E''(\Omega_0)$
[Joint work with Jimmy Lamboley and Arian Novruzzi] where

$$E(\Omega) = \int_{\Omega} K(x, u_{\Omega}(x), \nabla u_{\Omega}(x)) dx, \quad \Omega \subset B(0, R) \subset \mathbf{R}^d$$

$$K(x, u, q) = \sum_{i,j=1}^d \alpha_{ij}(x) q_i q_j + \alpha_0(x) u^2 + \sum_i \beta(x) q_i + \gamma(x) u + \delta(x),$$

$$\alpha, \beta, \gamma, \delta \in W^{2,\infty}(B(0, R))$$

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$$Lu_{\Omega} = f \text{ in } \Omega, \quad u_{\Omega} \in H_0^1(\Omega),$$

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- ▶ $\Omega_0 \subset \mathbf{R}^d$ is bounded convex, or semi-convex, or Lipschitz
- ▶ **semi-convex**: Lipschitz + uniform exterior sphere condition.

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- ▶ How much can one improve these continuity property ?

A first result in this context (J. Lamboley, A. Novruzi, M.P.)

Theorem 1. Let $\Omega_0 \subset \mathbf{R}^d$, bounded and **convex**.

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$$|E'(\Omega_0)\xi| \leq C\|\xi\|_{W^{1-\frac{1}{r},r}(\partial\Omega_0)}, \quad |E'(\Omega_0)\xi| \leq C\|\xi\|_{H^s(\partial\Omega_0)}.$$

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- ▶ If moreover $E(\Omega) = \int_{\Omega} (Lu_{\Omega})u_{\Omega}$ with $L = L^*$, then the above inequalities hold with $r = 1$ and $s = 1/2$:

$$|E'(\Omega_0)\xi| \leq C\|\xi\|_{L^1(\partial\Omega_0)}, \quad |E''(\Omega_0)(\xi, \xi)| \leq C\|\xi\|_{H^{1/2}(\partial\Omega_0)}^2.$$

And these last estimates are sharp.

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- ▶ Extensions to Lipschitz domains
- ▶ Some ideas of the proof: mainly relies on the regularity of ∇u_{Ω_0} in Ω_0 + a trace theorem.

Motivations and applications

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- ▶ This shape derivative estimate is e.g. used to prove the following: let $\Omega_0 \subset \mathbf{R}^2$ be a solution of the following minimization problem where $R : \mathbf{R}^2 \rightarrow \mathbf{R}$ is smooth and $D_{a,b} = \{x \in \mathbf{R}^2; 0 < a \leq |x| \leq b < +\infty\}$:

$$(\mathbf{P}) \min\{R(E(\Omega), |\Omega|) - P(\Omega); \Omega \text{ convex}, \Omega \subset D_{a,b}\}.$$

Then, Ω_0 is polygonal inside $D_{a,b}$.

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- ▶ If $\partial\Omega_0 \cap \partial D_{a,b} = \{\text{finite number of points}\}$, then, Ω_0 is a polygon. In general, the number of extremal points of Ω_0 in the interior of $D_{a,b}$ is finite.

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- ▶ One purely geometric example:

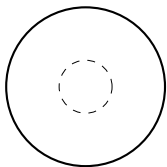
$$\min\{\lambda|\Omega| - P(\Omega), \Omega \text{ convex}, \Omega \subset D_{a,b}\}.$$

The optimal shapes according to λ for

$$\min\{\lambda|\Omega| - P(\Omega), \Omega \text{ convex}, \Omega \subset D_{a,b}\}$$

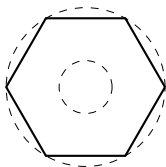
Results from a detailed analysis
by Ch. Bianchini and A. Henrot,
Case $a = 1, b = 3$

$$0 \quad \frac{1}{2b} \quad \frac{1}{a+b} \quad \frac{1}{b} \quad \frac{2b}{(b-a)(b+2a)} \quad \frac{2}{a} \quad +\infty$$



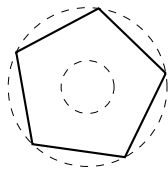
$$0 \leq \lambda < \frac{1}{6}$$

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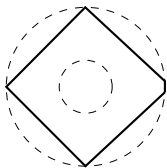
$$0.1792 < \lambda < 0.1847$$

$$0 \quad \frac{1}{2b} \quad \frac{1}{a+b} \quad \frac{1}{b} \quad \frac{2b}{(b-a)(b+2a)} \quad \frac{2}{a} \quad +\infty$$



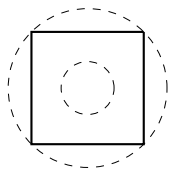
$$0.1847 < \lambda < 0.19506$$

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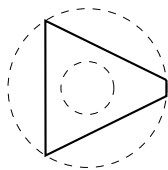
$$0.19506 < \lambda < 0.19525$$

$$0 \quad \frac{1}{2b} \quad \frac{1}{a+b} \quad \frac{1}{b} \quad \frac{2b}{(b-a)(b+2a)} \quad \frac{2}{a} \quad +\infty$$



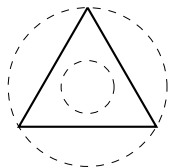
$$0.19525 < \lambda < 0.2187$$

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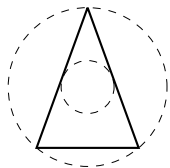
$$0.2187 < \lambda < 0.2222$$

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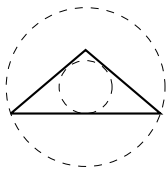
$$0.2222 < \lambda < 0.3080$$

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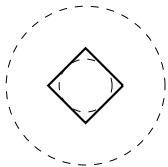
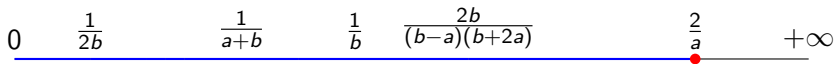


$$0.3080 < \lambda < 0.6$$

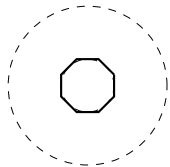
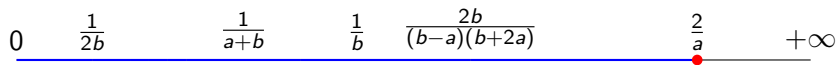
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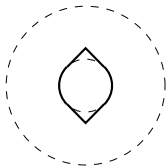
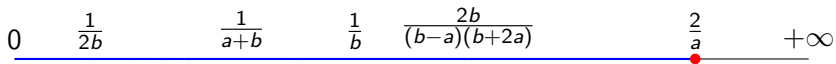
$$0.6 < \lambda < 2$$



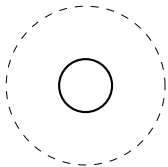
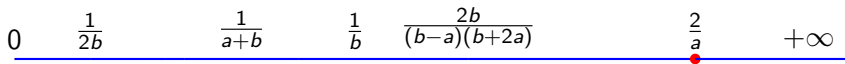
$$\lambda = 2$$



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$$2 < \lambda < +\infty$$

Motivations and applications: an analytical result

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- ▶ The "polygonal result" is a consequence of a more general result in an **analytic framework**.

Motivations and applications: an analytical result

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- ▶ The "polygonal result" is a consequence of a more general result in an **analytic framework**.
- ▶ Recall that any convex $\Omega \subset \mathbf{R}^2$ around the origin may be represented in polar coordinates as

$$\Omega = \Omega_u := \{(\rho, \theta) \in (0, \infty) \times [0, 2\pi]; \rho = 1/u(\theta), u \text{ } 2\pi\text{-periodic}\}.$$

$$[\Omega_u \text{ convex}] \Leftrightarrow [u + u'' \geq 0],$$

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- ▶ Then: $R(E(\Omega_u), |\Omega_u|) - P(\Omega_u) = j(u)$

where $j : W^{1,\infty}(\mathbb{S}^1) \rightarrow \mathbf{R}$.

Motivations and applications: an analytical result

- ▶ The geometric problem

$$(\mathbf{P}) \min\{R(E(\Omega), |\Omega|) - P(\Omega); \Omega \text{ convex}, \partial\Omega \subset D_{a,b}\},$$

may be rewritten

$$(\mathbf{j}) \min\{j(u); u \in W^{1,\infty}(\mathbb{S}^1), u + u'' \geq 0, a \leq \frac{1}{u} \leq b\},$$

where $j : W^{1,\infty}(\mathbb{S}^1) \mapsto \mathbf{R}$ is smooth. And we have the following more general analytic result:

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where $j : W^{1,\infty}(\mathbb{S}^1) \mapsto \mathbf{R}$ is smooth. And we have the following more general analytic result:

- ▶ **Theorem.** Let u_0 be a solution of Problem (j). Assume that for some $s \in [0, 1)$

$$\forall v \in W^{1,\infty}(\mathbb{S}^1), j''(u_0)(v, v) \leq -\alpha \|v\|_{H^1(\mathbb{S}^1)}^2 + \beta \|v\|_{H^s(\mathbb{S}^1)}^2.$$

Then, $u_0 + u_0''$ is a finite sum of Dirac masses inside $[a < \frac{1}{u_0} < b]$. And therefore the solution Ω_{u_0} is polygonal inside the annulus.

Motivations and applications: using the shape derivative estimates

- ▶ The functional $j(u) = R(E(\Omega_u), |\Omega_u|) - P(\Omega_u)$ does satisfy the "concavity" assumption around u_0 with $u_0 + u_0'' \geq 0$:

$$(*) \forall v \in W^{1,\infty}(\mathbb{S}^1), \quad j''(u_0)(v, v) \leq -\alpha \|v\|_{H^1(\mathbb{S}^1)}^2 + \beta \|v\|_{H^s(\mathbb{S}^1)}^2.$$

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- ▶ The reasons are:

- $u \rightarrow p(u) = P(\Omega_u)$ has a second derivative which satisfies

$$p''(u)(v, v) \geq c_1 \|v\|_{H^1(\mathbb{S}^1)}^2 - c_2 \|v\|_{L^2(\mathbb{S}^1)}^2.$$

- $u \rightarrow e(u) = E(\Omega_u)$ has a **second derivative around a convex set which is $H^{\frac{1}{2}+\epsilon}$ -continuous: this is a consequence of Theorem 1.** Whence the same for $r(u) = R(E(\Omega_u), |\Omega_u|)$.
- (*) follows with $s = \frac{1}{2} + \epsilon$.

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$$(*) \forall v \in W^{1,\infty}(\mathbb{S}^1), \quad j''(u_0)(v, v) \leq -\alpha \|v\|_{H^1(\mathbb{S}^1)}^2 + \beta \|v\|_{H^s(\mathbb{S}^1)}^2.$$

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- $u \rightarrow e(u) = E(\Omega_u)$ has a **second derivative around a convex set which is $H^{\frac{1}{2}+\epsilon}$ -continuous: this is a consequence of Theorem 1.** Whence the same for $r(u) = R(E(\Omega_u), |\Omega_u|)$.

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- ▶ **What happens in higher dimensions?**

Same problem in any dimension d

- ▶ Again the model problem ($D_{a,b} = \{x \in \mathbf{R}^d; a \leq |x| \leq b\}$)

$$(\mathbf{P}) \min\{R(E(\Omega), |\Omega|) - P(\Omega); \Omega \text{ convex}, \partial\Omega \subset D_{a,b}\},$$

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- ▶ Analytic version possible with the gauge function

$$\Omega_u = \left\{ (\rho, \theta) \in [0, \infty) \times \mathbb{S}^{d-1}, \rho < \frac{1}{u(\theta)} \right\},$$

$u : \mathbb{S}^{d-1} \rightarrow (0, \infty)$ with \bar{u} convex where $\bar{u}(x) = |x|u(x/|x|)$.

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- ▶ Then (\mathbf{P}) is equivalent to

$$\min\{j(u); u : \mathbb{S}^{d-1} \rightarrow (0, \infty), \bar{u} \text{ convex}, a \leq \frac{1}{u} \leq b, \}$$

where $j : W^{1,\infty}(\mathbb{S}^{d-1}) \rightarrow \mathbf{R}$ is C^2 and thanks to Theorem 1

$$j''(u)(v, v) \leq -\alpha \|v\|_{H^1(\mathbb{S}^{d-1})}^2 + \beta \|v\|_{H^s(\mathbb{S}^{d-1})}^2, s \in (1/2, 1).$$

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- ▶ Then the set of **admissible perturbations**

$$T_{u_0} = \left\{ v \in W^{1,\infty}(\mathbb{S}^{d-1}), \exists \epsilon > 0, \forall |t| < \epsilon, \right. \\ \left. \frac{1}{u_0 + tv} \text{ is convex}, a < \frac{1}{u_0 + tv} < b \right\},$$

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- ▶ **Can one say more???** (Could be useful for several open problems)

Extension to Lipschitz boundary-The exterior problem

- ▶ Replace the "interior Dirichlet energy" $E(\Omega)$ by the "exterior Dirichlet energy" $E_e(\Omega) = \int_{\Omega_e} |\nabla U_\Omega|^2$ where $\Omega_e = \mathbf{R}^d \setminus \Omega$ and

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- ▶ Similarly, what is the regularity of u_Ω when Ω is Lipschitz?

Regularity of u_Ω, U_Ω

$$\begin{cases} Lu_\Omega = f \text{ in } \Omega, u_\Omega = 0 \text{ on } \partial\Omega \\ -\Delta U_\Omega = f \text{ in } \Omega_e, U_\Omega = 0 \text{ on } \partial\Omega, \text{ support}(f) \subset B(0, R), R \text{ large.} \end{cases}$$

- [Jerison-Kenig '95] Assume Ω is Lipschitz and $L = -\Delta$. Then, $\exists p_1$ such that for all $p \in (p'_1, p_1)$

$$\|u_\Omega\|_{W^{1,p}(\Omega)} \leq c \|f\|_{W^{-1,p}(\Omega)},$$

$$\|U_\Omega\|_{W^{1,p}(\Omega_e \cap B(0,R))} \leq c \|f\|_{W^{-1,p}(B(0,R))},$$

$p_1 = 4 + \eta$ if $d = 2$, $p_1 = 3 + \eta$ if $d \geq 3$, $0 < \eta = \eta(\text{data})$.

The regularity $W^{1,p}$, $p < p_1$ is optimal even for f smooth.

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- ▶ If Ω is semi-convex, $W^{1,p}$ -estimate valid for all $p \in [1, \infty)$ for u_Ω . [S.J. Fromm, H. Jia, D. Li, L. Wang].

If moreover $f \in L^\infty(\Omega)$, then $u_\Omega \in W^{1,\infty}(\Omega)$.

semi-convex: Lipschitz + uniform exterior ball condition.

Regularity of the quadratic energies for Lipschitz domains

Theorem 2. Let $\Omega_0 \subset \mathbf{R}^d$, bounded and Lipschitz.

- ▶ Then, $\theta \in \Theta \rightarrow E((I + \theta)(\Omega)), E_e((I + \theta)(\Omega))$ are twice differentiable around $\theta = 0$.

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- ▶ If Ω_0 is bounded and **convex** or **only semi-convex**, then:
 - nothing better is valid for E_e
 - one may take $r_1 = 1$ (i.e. valid for all $r > 1$)
 - one may even take $r = 1$ if $E(\Omega) = \int_{\Omega} (Lu_{\Omega})u_{\Omega}$, $L = L^*$.

Some ideas of the proof of the estimates on E' , E''

- ▶ We take the model energy, with a good elliptic operator L

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Differentiability of \widehat{u}_θ

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where L_θ is the operator L transported onto Ω_0 (it would be $-\nabla \cdot (M_\theta \nabla \widehat{u}_\theta)$ in the case $L = -\Delta$).

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which is C^2 and $D_u \mathcal{F}(0, u_{\Omega_0}) : H_0^1(\Omega_0) \rightarrow H^{-1}(\Omega_0)$ is an isomorphism (if $L = -\Delta$, it is exactly $-\Delta$).

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- ▶ We do not need regularity of Ω_0 , only regularity of f and of the coefficients of L ($W^{2,\infty}$)

How to estimate $E'(\Omega_0)\xi$, $E''(\Omega)(\xi, \xi)$?

Case : $E(\Omega) = \int_{\Omega} |\nabla u_{\Omega}|^2$, $L = -\Delta$, Ω regular

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$$E''(\Omega_0)(\xi, \xi) = Q_2(\xi \cdot \nu, \xi \cdot \nu) + E'(\Omega_0)(\zeta),$$

where Q_2 is continuous quadratic form and ζ involves the tangential components of ξ

- ▶ Moreover $Q_2(\varphi, \varphi) = - \int_{\partial\Omega_0} V \partial_{\nu} V + \varphi^2 [2f \partial_{\nu} u_0 + H(\partial_{\nu} u_0)^2]$, where H is the mean curvature of Ω_0 and

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- ▶ We forget this !

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- ▶ With $u_0 := u_{\Omega_0}$ and $\xi \in \Theta$

$$E'(\Omega_0)\xi = \int_{\Omega_0} 2\nabla u_0 \cdot \nabla \hat{u}'_0 + \nabla u_0 \cdot M'_0 \cdot \nabla u_0,$$

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- ▶ With $u_0 := u_{\Omega_0}$ and $\xi \in \Theta$

$$E'(\Omega_0)\xi = \int_{\Omega_0} 2\nabla u_0 \cdot \nabla \hat{u}'_0 + \nabla u_0 \cdot M'_0 \cdot \nabla u_0,$$

where $'_0$ denotes the derivation in the ξ -direction at $\theta = 0$ and

$$M'_0 \xi = -D\xi - D\xi + \text{trace}(D\xi)I.$$

- ▶ If we know $u_0 \in W^{1,p}(\Omega)$ with $p > 2$, then

$$\left| \int_{\Omega_0} \nabla u_0 \cdot M'_0 \cdot \nabla u_0 \right| \leq c \int_{\Omega_0} |\nabla u_0|^2 |D\xi| \leq c \|u_0\|_{W^{1,p}(\Omega_0)}^2 \|\xi\|_{W^{1, \frac{p}{p-2}}(\Omega_0)}.$$

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- ▶ $Lu_{\Omega_\theta} = f \Rightarrow \int_{\Omega_\theta} \phi \circ (I + \theta)^{-1} L(u_{\Omega_\theta}) = \int_{\Omega_\theta} \phi \circ (I + \theta)^{-1} f$
and with $[L \text{ on } \Omega_\theta] \mapsto L_\theta \text{ on } \Omega_0$

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- ▶ Recalling $E'(\Omega_0)\xi = \int_{\Omega_0} 2\nabla u_0 \cdot \nabla \hat{u}'_0 + \nabla u_0 \cdot M'_0 \cdot \nabla u_0$, we have

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- ▶ $p_1 = 3 + \eta$ if Ω Lipschitz ($p_1 = 4 + \eta$ if $d = 2$).
 - Valid with $p_1 = +\infty$ if Ω semi-convex (i.e. valid for any $p \in [1, \infty)$).
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- ▶ End of the story: the fact that $E'(\Omega_0)\xi$ depends only on the trace of ξ on $\partial\Omega_0$ + a trace lemma for Ω Lipschitz:

$$\inf \left\{ \|\widehat{\xi}\|_{W^{1,q}(\Omega)}; \widehat{\xi} \in W^{1,\infty}(\Omega), \widehat{\xi} = \xi \text{ on } \partial\Omega \right\} \leq c \|\xi\|_{W^{1-\frac{1}{q},q}(\partial\Omega)},$$

for $q \in [1, \infty]$.

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- ▶ Differentiating twice $\int_{\Omega_0} L_\theta \hat{u}_\theta = \int_{\Omega_0} \phi \hat{f}_\theta$ leads to

$$\int_{\Omega_0} \phi L\hat{u}'_0 = \int_{\Omega_0} \phi \left(\hat{f}'_0 - 2L'_0 \hat{u}'_0 + L''_0 u_0 \right),$$

and we estimate \hat{u}'_0 by duality as for \hat{u}'_0 up to the change

$$W^{1, \frac{p}{p-2}} \rightarrow W^{1, \frac{2p}{p-2}}$$

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- ▶ If $d = 2$, then optimal shapes have the polygonal property.
- ▶ If $d \geq 3$, estimates of the derivatives of $E_e(\Omega_0)$ **are not sufficient to conclude.**
→ **Open problem !.**